



LUND
UNIVERSITY

EDAP15: Program Analysis

POINTER ANALYSIS 2

Christoph Reichenbach



Welcome back!

Questions?

Lecture Overview

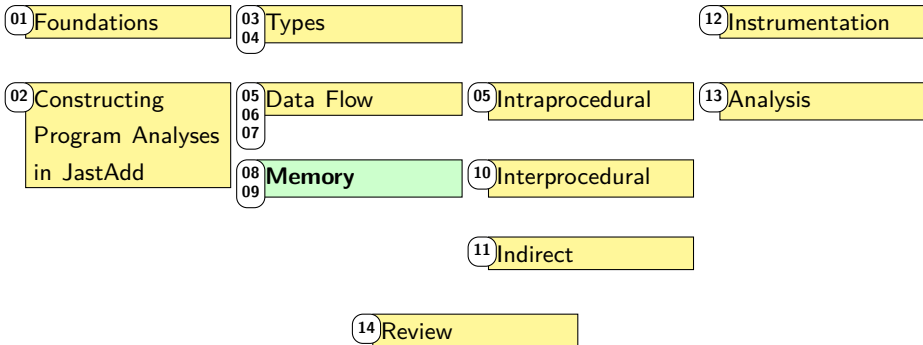
Foundations

Static Analysis

Dynamic
Analysis

Properties

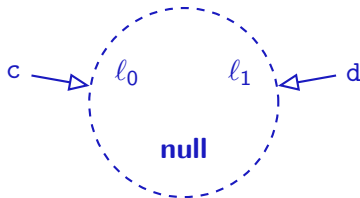
Control Flow



Alias Analysis in Practice (1/2)

Teal

```
var c := newℓ0();  
var d := newℓ1();  
if ... {  
    c := null;  
} else {  
    d := null;  
}
```



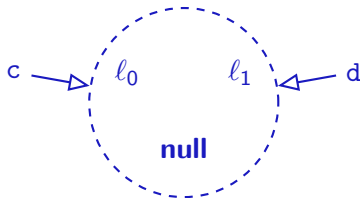
$c \stackrel{\text{alias}}{=} d$

null as unique memory location: Imprecision!

Alias Analysis in Practice (1/2)

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```



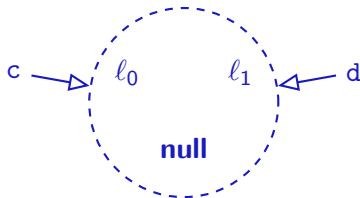
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Alias Analysis in Practice (1/2)

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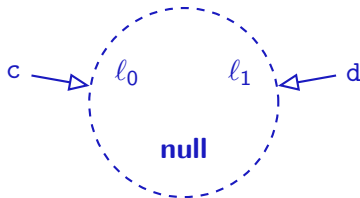
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Alias Analysis in Practice (1/2)

Teal

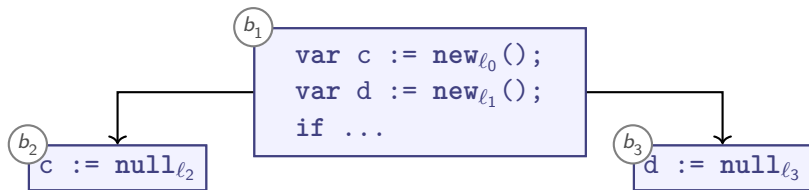
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var c := newℓ0();  
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if ... {  
    c := null;  
} else {  
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}
```



$c \stackrel{\text{alias}}{=} d$

null as unique memory location: Imprecision!

Representing Null Pointers



1 One unique **null**



2 Many **nulls** (More precise, takes up extra memory)



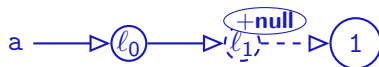
3 Nullness flags (Also more precise, minimal extra memory, but more complex analysis code)



Alias Analysis in Practice (2/2)

Teal

```
var a := newℓ0 XY();  
a.x := newℓ1 XY();  
a.x.x := 1;  
a.y := null;  
  
print(a.x.x);  
// null dereference?
```



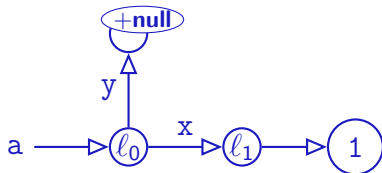
$a.x \underline{\underline{\text{alias}}} \text{null} \underline{\underline{\text{alias}}} a.y$

Field Sensitivity

- So far, we have merged all fields:

$$a.x \stackrel{\text{alias}}{=} a.\Box \stackrel{\text{alias}}{=} a.y$$

- Points-to analysis so far *field insensitive*
- Analogous for array indices
- A *field-sensitive* analysis would distinguish:



Summary

- ▶ Practical points to analysis usually wants to represent **null**
 - ▶ Single global **null** may reduce precision (unification-based analysis)
- ▶ Simple program analyses are **field insensitive**:

$$a.x \stackrel{\text{alias}}{=} a.\Box \stackrel{\text{alias}}{=} a.y$$

- ▶ **Field-sensitive** analyses improve precision by distinguishing fields along points-to edges:

$$a.x \not\stackrel{\text{alias}}{=} a.y$$

- ▶ Analogously for **Index-sensitive** analyses (for array indices)

Dataflow-Based Points-To Analysis

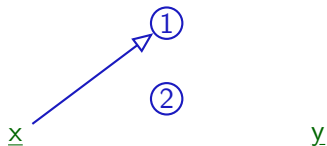
$$\begin{aligned} G_{\text{AHG}} &= \langle \bar{L}, \rightarrow \rangle \\ (\rightarrow) &\subseteq \bar{L} \times \bar{L} \end{aligned}$$

- ▶ Points-To via Dataflow:
- ▶ Lattice over set of edges between memory locations $\bar{L}$
- ▶ $\sqcup = \cup$
- ▶ $\sqsubseteq = \subseteq$

Example: Allocation and Update

Teal

```
var x := new1();  
⇒ var y := new2();  
  
if ... {  
  y := new5();  
}  
  
x := new7();  
y := x;
```



Case

x := new_ℓ()

Transfer Function

$trans_1(\rightarrow) = (\rightarrow)$

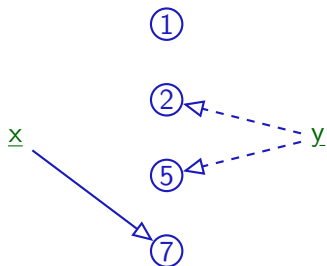
$\cup \{ \underline{x} \rightarrow \ell \}$

Slight abuse of notation: writing $x \rightarrow \ell$ for $\langle x, \ell \rangle$

Example: Allocation and Update

Teal

```
var x := new1();  
var y := new2();  
  
if ... {  
  y := new5();  
}  
  
⇒ x := new7();  
   y := x;
```



Remove all $\underline{x} \rightarrow \ell$ for any $\ell \in \bar{L}$

Case

x := new _{ℓ} ()

Transfer Function

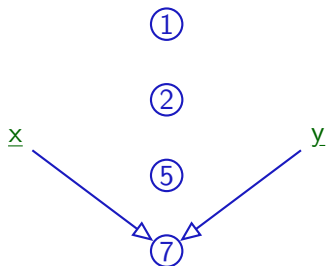
$trans_1(\rightarrow) = (\rightarrow) \setminus (\{\underline{x}\} \times \bar{L}) \cup \{ \underline{x} \rightarrow \ell \}$

Slight abuse of notation: writing $\underline{x} \rightarrow \ell$ for $\langle \underline{x}, \ell \rangle$

Example: Allocation and Update

Teal

```
var x := new1();  
var y := new2();  
  
if ... {  
  y := new5();  
}  
  
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⇒ y := x;
```



Case

x := new_ℓ()
y := x;

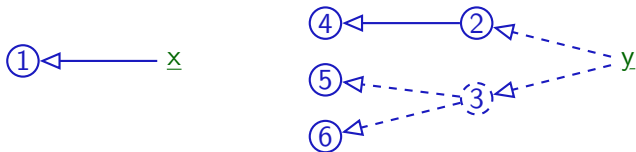
Transfer Function

$trans_1(\rightarrow) = (\rightarrow) \setminus (\{\underline{x}\} \times \overline{L}) \cup \{\underline{x} \rightarrow \ell\}$
 $trans_2(\rightarrow) = (\rightarrow) \setminus (\{\underline{y}\} \times \overline{L}) \cup \{\underline{y} \rightarrow \ell \mid \underline{x} \rightarrow \ell\}$

Slight abuse of notation: writing $\underline{x} \rightarrow \ell$ for $\langle \underline{x}, \ell \rangle$

Dereferencing Read

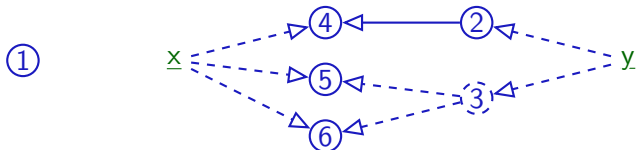
Before:



Teal

$\underline{x} := \underline{y}.f;$

After:



Case

$\underline{x} := \underline{y}.\square;$

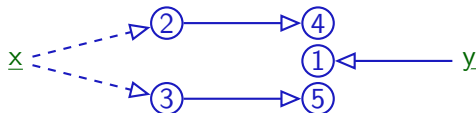
Transfer Function

$trans_3(\rightarrow) = (\rightarrow) \setminus (\{\underline{x}\} \times \overline{L}) \cup \{ \underline{x} \rightarrow \ell' \mid \exists \ell.$

$\underline{y} \rightarrow \ell \rightarrow \ell' \}$

Dereferencing Write

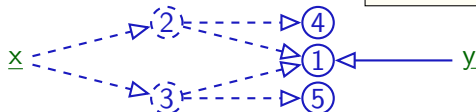
Before:



Teal

$\underline{x}.f := \underline{y};$

After:



Cannot remove edges:
We don't know if it was 2
or 3 that was changed!

Case

$\underline{x}.\square := \underline{y};$

Transfer Function

$trans_4(\rightarrow) = (\rightarrow) \setminus (\{\underline{x}\} \times \overline{L}) \cup \{ \ell \rightarrow \ell' \mid \underline{x} \rightarrow \ell, \underline{y} \rightarrow \ell' \}$

Weak vs Strong Update?

- ▶ **Strong update:**

- ▶ Can remove “obsolete” information
- ▶ So far our default

- ▶ **Weak update:**

- ▶ Cannot remove “obsolete” information
- ▶ Observed with dereferencing write

- ▶ Dereferencing write *can* be strong if x can point to only one location

Teal

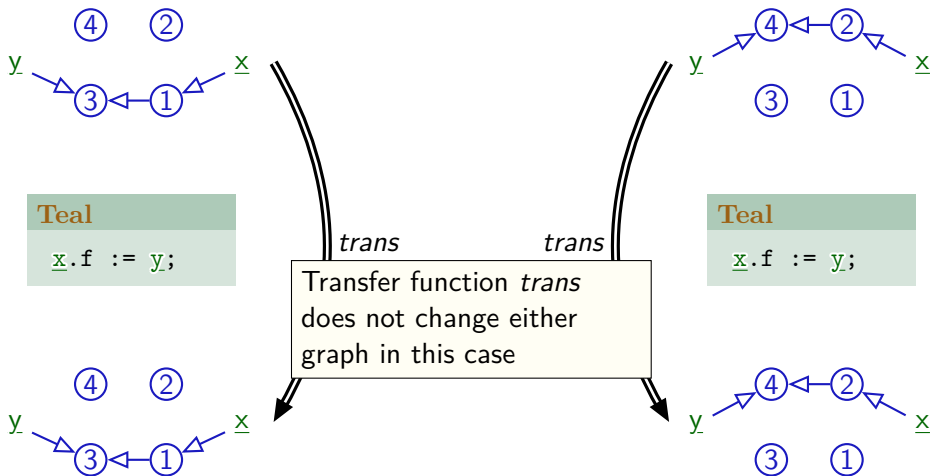
```
x.f := y;
```

Dataflow-Based Points-To Analysis

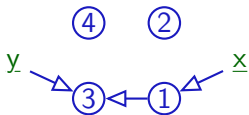
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Distributivity?

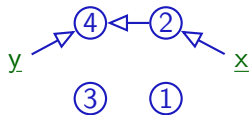
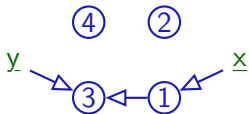


Distributivity?



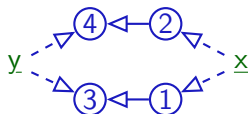
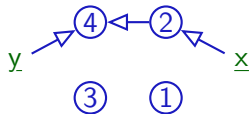
Teal

$\underline{x}.f := y;$



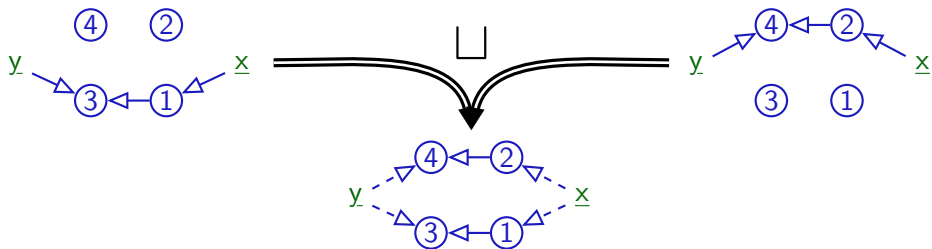
Teal

$\underline{x}.f := y;$



Result for join *after* transfer

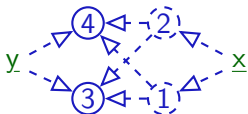
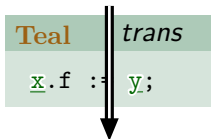
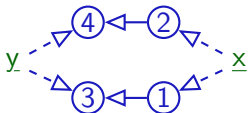
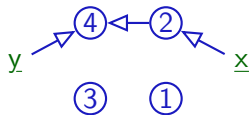
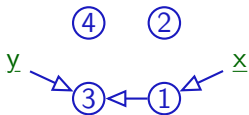
Distributivity?



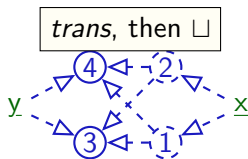
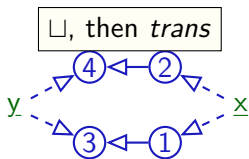
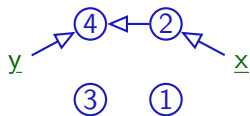
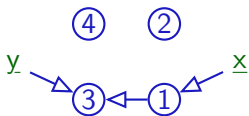
Teal

$\underline{x}.f := \underline{y};$

Distributivity?



Distributivity?



Different results $\implies$ not distributive!

Summary

- ▶ Flow-sensitive points-to analysis is possible but expensive
- ▶ **Weak updates** add new points-to relationship options
 - ▶ Don't remove existing options
- ▶ **Strong updates** add but also remove points-to relationship options
 - ▶ More precise than weak updates
 - ▶ Only possible if updated pointer is unambiguous
- ▶ *Not Distributive*

Andersen's Points-To Analysis

- ▶ Asymptotic performance is $O(n^3)$
- ▶ More precise than Steensgaard's analysis
- ▶ *Subset-based* (a.k.a. *inclusion-based*)
- ▶ $\implies$ Flow-insensitive but *directed*
- ▶ Popular as basis for current points-to analyses

L. Andersen, "Program Analysis and Specialization for the C Programming Language", PhD. thesis, DIKU report 94/19, 1994

Collecting Constraints

- ▶ Collect constraints, resolve as needed
- ▶ For each statement in program, we record:
 - ▶ If **Referencing** ($x := \text{new}_{\ell_i} A()$):

$$\ell_i \in pt(x) \quad (x \rightarrow \ell_i)$$

- ▶ If **Aliasing** ($x := y$):

$$pt(x) \supseteq pt(y)$$

- ▶ If **Dereferencing read** ($x := y.\square$):

$$pt(x) \supseteq pt(y.\square)$$

- ▶ If **Dereferencing write** ($x.\square := y$):

$$pt(x.\square) \supseteq pt(y)$$

Solving Constraints

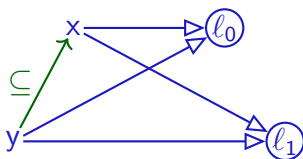
1 Fact extraction:

- ▶ Initial points-to sets: $\ell \in pt(x)$, meaning $\ell \leftarrow x$
- ▶ Constraints:
 - ▶ $pt(x) \supseteq pt(y)$
 - ▶ $pt(x) \supseteq pt(y.\Box)$
 - ▶ $pt(x.\Box) \supseteq pt(y)$

Subset Constraints (1/2)

- Solving $pt(x) \supseteq pt(y)$

```
y := newℓ₀();  
while ... {  
  x := y;  
  y := newℓ₁();
```



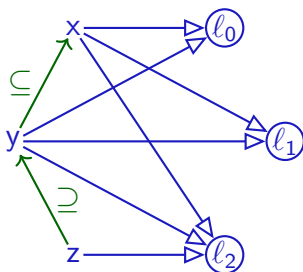
```
}
```

- $\ell \leftarrow y$ and $pt(x) \supseteq pt(y)$:
 $\implies \ell \leftarrow x$
- *Flow insensitive*: can't distinguish before/after

Subset Constraints (1/2)

- ▶ Solving $pt(x) \supseteq pt(y)$

```
y := newℓ₀();  
while ... {  
  x := y;  
  y := newℓ₁();  
  z := newℓ₂();  
  if ... {  
    y := z;  
  }  
}
```



- ▶ $\ell \leftarrow y$ and $pt(x) \supseteq pt(y)$:
 $\implies \ell \leftarrow x$
- ▶ *Flow insensitive*: can't distinguish before/after

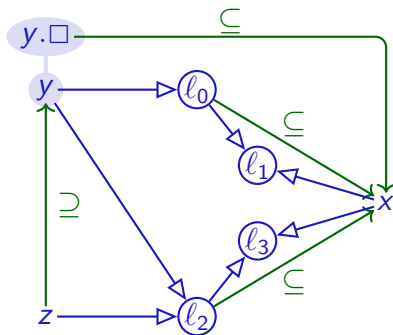
Solving one ($\supseteq$) can depend on all ($\leftarrow$) and ($\supseteq$) in program

Subset Constraints (2/2)

- Solving $pt(x) \supseteq pt(y.\square)$

```
y := newl0();  
y.n := newl1();  
z := newl2();  
z.n := newl3();  
if ... {  
  y := z;  
}  
x := y.n;
```

Simplified presentation (omitting ($\supseteq$) constraints)



- Recall:

$l \leftarrow z$ and $pt(y) \supseteq pt(z)$:

$\implies l \leftarrow y$

- $l \leftarrow y$ and $pt(x) \supseteq pt(y.\square)$:

$\implies pt(x) \supseteq pt(l)$

Fresh Assignments to Fields

- Recall:

```
y.n := newℓ1();
```

- No direct pattern for this code

- Can model as:

```
var tmp := newℓ1();  
y.n := tmp;
```


Solving Constraints

1 Fact extraction:

- ▶ Initial points-to sets: $\ell \in pt(x)$, meaning $\ell \leftarrow x$
- ▶ Constraints:
 - ▶ $pt(x) \supseteq pt(y)$
 - ▶ $pt(x) \supseteq pt(y.\Box)$
 - ▶ $pt(x.\Box) \supseteq pt(y)$

2 Build directed *inclusion graph* $G_I = \langle MemLoc, E \rangle$

- ▶ $x \leftarrow y$ represents $pt(x) \supseteq pt(y)$ (" $x := y$ ")

3 Expand and propagate along inclusion graph:

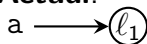
- ▶ Propagate points-to sets along E :

- ▶ $\ell \leftarrow y$ and $x \leftarrow y$:
 $\implies \ell \leftarrow x$
- ▶ $\ell \leftarrow y$ and $x \leftarrow y.\Box$:
 $\implies x \leftarrow \ell$
- ▶ $\ell \leftarrow x$ and $x.\Box \leftarrow y$:
 $\implies \ell \leftarrow y$

Example

$\Rightarrow x := \text{new}_{\ell_z} \quad x \rightarrow \ell_z$
 $x := y \quad x \leftarrow y$
 $x := y.\square \quad x \leftarrow y.\square$
 $x.\square := y \quad x.\square \leftarrow y$

► **Actual:**



p

q

b

r

► **Andersen:**



p

q

b

r

Teal

```

var a := newℓ1(); // ⇐
var b := newℓ2();
a := newℓ3();
var p := newℓ4();
p.n := a;
var q := newℓ6();
q.n := b;
p := q;
var r := q.n;
    
```

Example

$\Rightarrow$ $x := \text{new}_{\ell_z}$ $x \rightarrow \ell_z$
 $x := y$ $x \leftarrow y$
 $x := y.\square$ $x \leftarrow y.\square$
 $x.\square := y$ $x.\square \leftarrow y$

► **Actual:**

$a \longrightarrow (\ell_1)$

p

q

$b \longrightarrow (\ell_2)$

r

► **Andersen:**

$a \longrightarrow \triangleright (\ell_1)$

p

q

$b \longrightarrow \triangleright (\ell_2)$

r

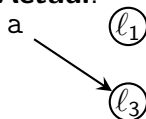
Teal

```
var a := new $\ell_1$ ();  
var b := new $\ell_2$ () ; //  $\Leftarrow$   
a := new $\ell_3$ () ;  
var p := new $\ell_4$ () ;  
p.n := a ;  
var q := new $\ell_6$ () ;  
q.n := b ;  
p := q ;  
var r := q.n ;
```

Example

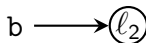
$\Rightarrow$ $x := \text{new}_{\ell_z}$ $x \rightarrow \ell_z$
 $x := y$ $x \leftarrow y$
 $x := y.\square$ $x \leftarrow y.\square$
 $x.\square := y$ $x.\square \leftarrow y$

► **Actual:**



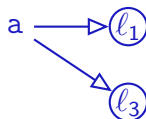
p

q



r

► **Andersen:**



p

q



r

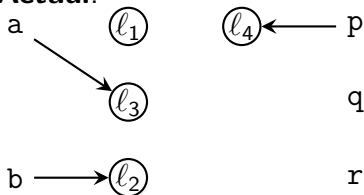
Teal

```
var a := newℓ1();  
var b := newℓ2();  
a := newℓ3();    // ←  
var p := newℓ4();  
p.n := a;  
var q := newℓ6();  
q.n := b;  
p := q;  
var r := q.n;
```

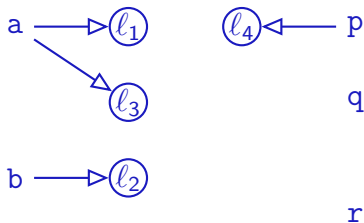
Example

$$\Rightarrow \begin{array}{ll} x := \text{new}_{\ell_z} & x \rightarrow \ell_z \\ x := y & x \leftarrow y \\ x := y.\square & x \leftarrow y.\square \\ x.\square := y & x.\square \leftarrow y \end{array}$$

► **Actual:**



► **Andersen:**



Teal

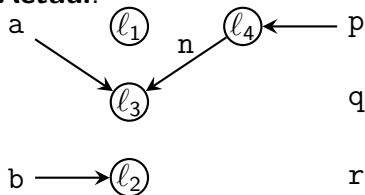
```

var a := newℓ1();
var b := newℓ2();
a := newℓ3();
var p := newℓ4(); // ←
p.n := a;
var q := newℓ6();
q.n := b;
p := q;
var r := q.n;
  
```

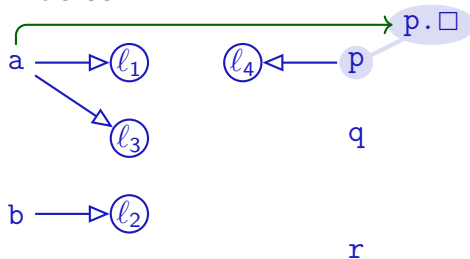
Example

$x := \text{new}_{\ell_z}$	$x \rightarrow \ell_z$
$x := y$	$x \leftarrow y$
$x := y.\square$	$x \leftarrow y.\square$
$\Rightarrow x.\square := y$	$x.\square \leftarrow y$

► Actual:



► Andersen:



Teal

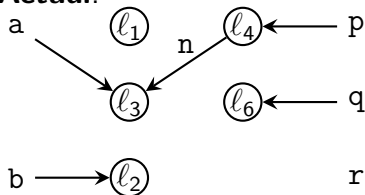
```

var a := new $\ell_1$ () ;
var b := new $\ell_2$ () ;
a := new $\ell_3$ () ;
var p := new $\ell_4$ () ;
p.n := a ;           //  $\Leftarrow$ 
var q := new $\ell_6$ () ;
q.n := b ;
p := q ;
var r := q.n ;
    
```

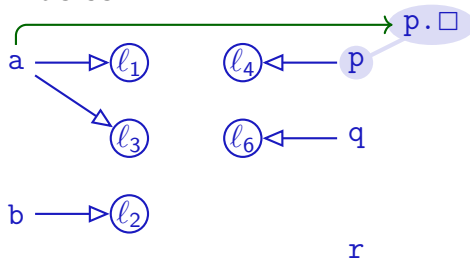
Example

$\Rightarrow x := \text{new}_{\ell_z} \quad x \rightarrow \ell_z$
 $x := y \quad x \leftarrow y$
 $x := y.\square \quad x \leftarrow y.\square$
 $x.\square := y \quad x.\square \leftarrow y$

► **Actual:**



► **Andersen:**



Teal

```

var a := new $\ell_1$ () ;
var b := new $\ell_2$ () ;
a := new $\ell_3$ () ;
var p := new $\ell_4$ () ;
p.n := a ;
var q := new $\ell_6$ () ; //  $\Leftarrow$ 
q.n := b ;
p := q ;
var r := q.n ;
    
```

Example

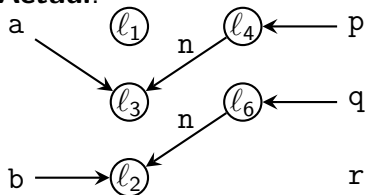
$x := \text{new}_{\ell_z}$	$x \rightarrow \ell_z$
$x := y$	$x \leftarrow y$
$x := y.\square$	$x \leftarrow y.\square$
$\Rightarrow x.\square := y$	$x.\square \leftarrow y$

Teal

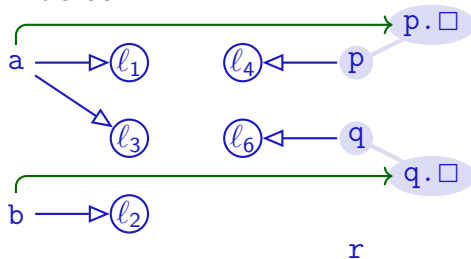
```

var a := new $\ell_1$ () ;
var b := new $\ell_2$ () ;
a := new $\ell_3$ () ;
var p := new $\ell_4$ () ;
p.n := a ;
var q := new $\ell_6$ () ;
q.n := b ;           //  $\Leftarrow$ 
p := q ;
var r := q.n ;
    
```

► Actual:



► Andersen:



Example

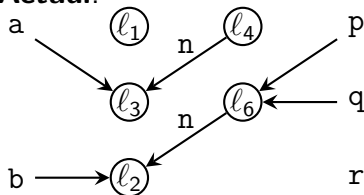
$x := \text{new}_{\ell_z}$	$x \rightarrow \ell_z$
$\Rightarrow x := y$	$x \leftarrow y$
$x := y.\square$	$x \leftarrow y.\square$
$x.\square := y$	$x.\square \leftarrow y$

Teal

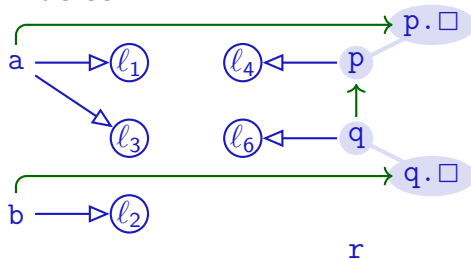
```

var a := new $\ell_1$ ();
var b := new $\ell_2$ ();
a := new $\ell_3$ ();
var p := new $\ell_4$ ();
p.n := a;
var q := new $\ell_6$ ();
q.n := b;
p := q;           //  $\Leftarrow$ 
var r := q.n;
    
```

► Actual:



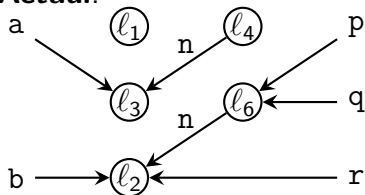
► Andersen:



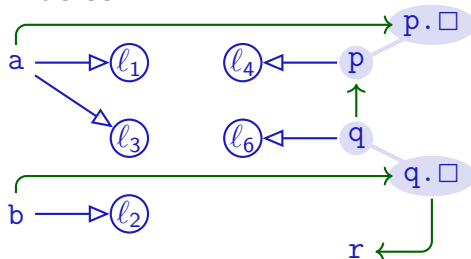
Example

$x := \text{new}_{\ell_z}$	$x \rightarrow \ell_z$
$x := y$	$x \leftarrow y$
$x := y.\square$	$x \leftarrow y.\square$
$x.\square := y$	$x.\square \leftarrow y$

► Actual:



► Andersen:



Teal

```
var a := new $\ell_1$ ();  
var b := new $\ell_2$ ();  
a := new $\ell_3$ ();  
var p := new $\ell_4$ ();  
p.n := a;  
var q := new $\ell_6$ ();  
q.n := b;  
p := q;  
var r := q.n; //  $\Leftarrow$ 
```

Example

$x := \text{new}_{\ell_z} \quad x \rightarrow \ell_z$
 $x := y \quad x \leftarrow y$
 $x := y.\square \quad x \leftarrow y.\square$
 $x.\square := y \quad x.\square \leftarrow y$

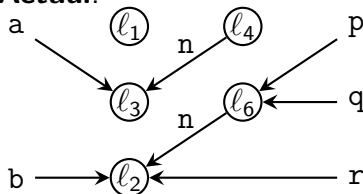
$\ell \leftarrow y \text{ and } x \leftarrow y \implies \ell \leftarrow x$
 $\ell \leftarrow y \text{ and } x \leftarrow y.\square \implies x \leftarrow \ell$
 $\ell \leftarrow x \text{ and } x.\square \leftarrow y \implies \ell \leftarrow y$

Teal

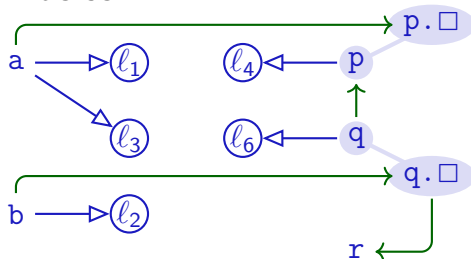
```

var a := new $\ell_1$ () ;
var b := new $\ell_2$ () ;
a := new $\ell_3$ () ;
var p := new $\ell_4$ () ;
p.n := a ;
var q := new $\ell_6$ () ;
q.n := b ;
p := q ;
var r := q.n ;
    
```

► Actual:



► Andersen:



Andersen's algorithm must propagate along **inclusion graph**

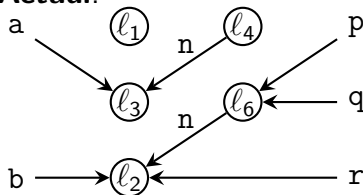
Example

$l \leftarrow y$ and $x \leftarrow y \Rightarrow l \leftarrow x$
 $l \leftarrow y$ and $x \leftarrow y.\square \Rightarrow x \leftarrow l$
 $l \leftarrow x$ and $x.\square \leftarrow y \Rightarrow l \leftarrow y$

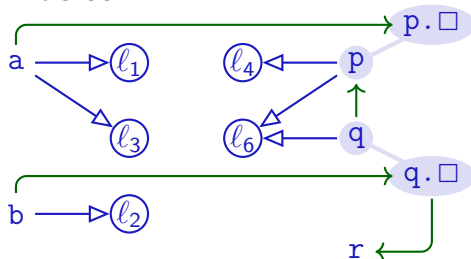
Teal

```
var a := newl1();  
var b := newl2();  
a := newl3();  
var p := newl4();  
p.n := a;  
var q := newl6();  
q.n := b;  
p := q;  
var r := q.n;
```

► Actual:



► Andersen:



Andersen's algorithm must propagate along **inclusion graph**

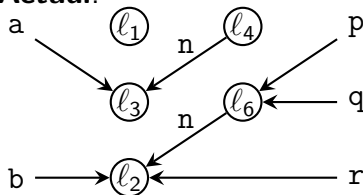
Example

$l \leftarrow y$ and $x \leftarrow y \Rightarrow l \leftarrow x$
 $l \leftarrow y$ and $x \leftarrow y.\square \Rightarrow x \leftarrow l$
 $l \leftarrow x$ and $x.\square \leftarrow y \Rightarrow l \leftarrow y$

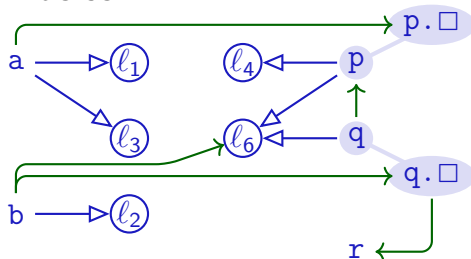
Teal

```
var a := newl1();  
var b := newl2();  
a := newl3();  
var p := newl4();  
p.n := a;  
var q := newl6();  
q.n := b;  
p := q;  
var r := q.n;
```

Actual:



Andersen:



Andersen's algorithm must propagate along **inclusion graph**

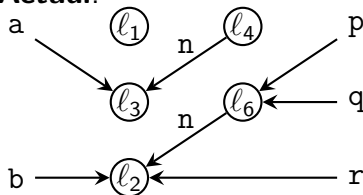
Example

$l \leftarrow y$ and $x \leftarrow y \Rightarrow l \leftarrow x$
 $l \leftarrow y$ and $x \leftarrow y.\square \Rightarrow x \leftarrow l$
 $l \leftarrow x$ and $x.\square \leftarrow y \Rightarrow l \leftarrow y$

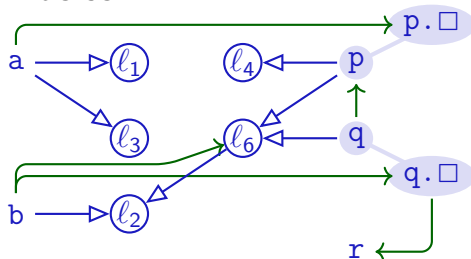
Teal

```
var a := newl1();  
var b := newl2();  
a := newl3();  
var p := newl4();  
p.n := a;  
var q := newl6();  
q.n := b;  
p := q;  
var r := q.n;
```

Actual:



Andersen:



Andersen's algorithm must propagate along **inclusion graph**

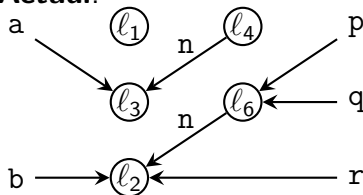
Example

$l \leftarrow y$ and $x \leftarrow y \Rightarrow l \leftarrow x$
 $l \leftarrow y$ and $x \leftarrow y.\square \Rightarrow x \leftarrow l$
 $l \leftarrow x$ and $x.\square \leftarrow y \Rightarrow l \leftarrow y$

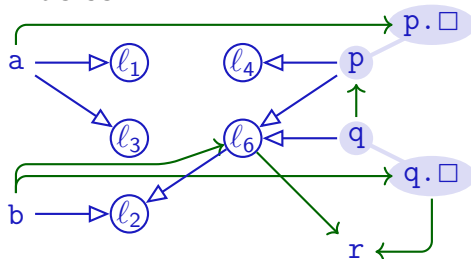
Teal

```
var a := newl1();  
var b := newl2();  
a := newl3();  
var p := newl4();  
p.n := a;  
var q := newl6();  
q.n := b;  
p := q;  
var r := q.n;
```

Actual:



Andersen:



Andersen's algorithm must propagate along **inclusion graph**

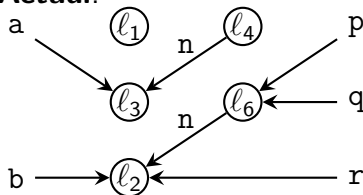
Example

$l \leftarrow y$ and $x \leftarrow y \Rightarrow l \leftarrow x$
 $l \leftarrow y$ and $x \leftarrow y.\square \Rightarrow x \leftarrow l$
 $l \leftarrow x$ and $x.\square \leftarrow y \Rightarrow l \leftarrow y$

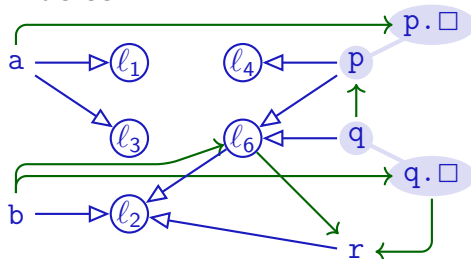
Teal

```
var a := newl1();  
var b := newl2();  
a := newl3();  
var p := newl4();  
p.n := a;  
var q := newl6();  
q.n := b;  
p := q;  
var r := q.n;
```

Actual:



Andersen:

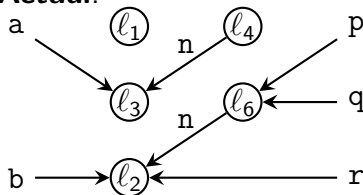


Andersen's algorithm must propagate along **inclusion graph**

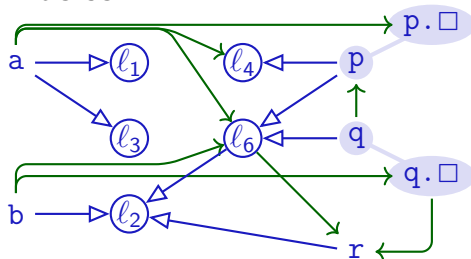
Example

$l \leftarrow y$ and $x \leftarrow y \Rightarrow l \leftarrow x$
 $l \leftarrow y$ and $x \leftarrow y.\square \Rightarrow x \leftarrow l$
 $l \leftarrow x$ and $x.\square \leftarrow y \Rightarrow l \leftarrow y$

► Actual:



► Andersen:



Teal

```
var a := newl1();  
var b := newl2();  
a := newl3();  
var p := newl4();  
p.n := a;  
var q := newl6();  
q.n := b;  
p := q;  
var r := q.n;
```

Andersen's algorithm must propagate along **inclusion graph**

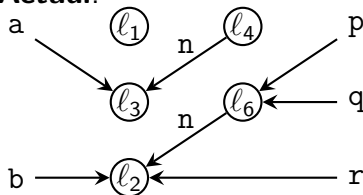
Example

$l \leftarrow y$ and $x \leftarrow y \Rightarrow l \leftarrow x$
 $l \leftarrow y$ and $x \leftarrow y.\square \Rightarrow x \leftarrow l$
 $l \leftarrow x$ and $x.\square \leftarrow y \Rightarrow l \leftarrow y$

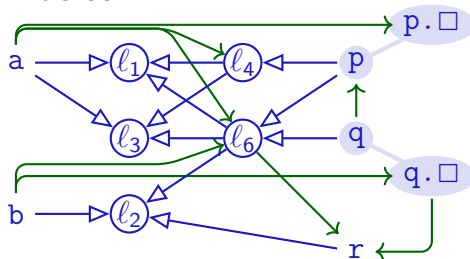
Teal

```
var a := newl1();  
var b := newl2();  
a := newl3();  
var p := newl4();  
p.n := a;  
var q := newl6();  
q.n := b;  
p := q;  
var r := q.n;
```

Actual:



Andersen:



Andersen's algorithm must propagate along **inclusion graph**

Implementation

- ▶ Graph structure
- ▶ Three types of edges: $\leftarrow$, $\leftarrow$, and indirect $\leftarrow$ (with a $\square$)
- ▶ Connection between x and $x.\square$
- ▶ Worklist:
 - ▶ Track all *new* edges (at start: *all* extracted edges)
 - ▶ Process one edge at a time:
 - ▶ Remove from worklist, add to “completed edges”
 - ▶ Check our three rules: does current edge + completed edges allow producing new edge that is neither in worklist nor completed?
 - ▶ If so: add all such edges to worklist (may be several!)

$$\ell \leftarrow y \text{ and } x \leftarrow y \implies \ell \leftarrow x$$

$$v \leftarrow y \text{ and } x \leftarrow y.\square \implies x \leftarrow v$$

$$v \leftarrow x \text{ and } x.\square \leftarrow y \implies v \leftarrow y$$

Complexity

- ▶ Complexity of graph closure: $O(n^3)$
- ▶ Traditional assumption about Andersen's analysis
- ▶ Close to $O(n^2)$ if:
 - 1 Few statements dereference each variable
 - 2 Control flow graphs not too complex

Both conditions are common in practical programs

Manu Sridharan, Stephen J. Fink, "The Complexity of Andersen's Analysis in Practice", in SAS 2009

Summary

- ▶ Andersen's analysis:
 - ▶ Subset-based
 - ▶ Builds inclusion graph for propagating memory locations along subset constraints
 - ▶ $O(n^3)$ worst-case behaviour
 - ▶ Closer to $O(n^2)$ in practice
 - ▶ More precise than Steensgaard's analysis
 - ▶ Less scalable than Steensgaard's analysis

Lecture Overview

Foundations

Static Analysis

Dynamic
Analysis

Properties

Control Flow

