



LUND
UNIVERSITY

EDAP15: Program Analysis

POINTER ANALYSIS 1

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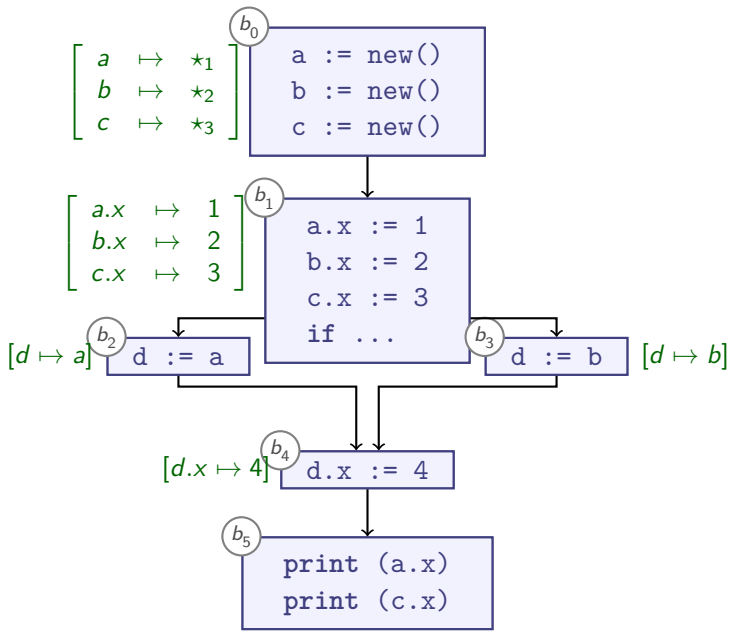
Welcome back!

- ▶ Questions?

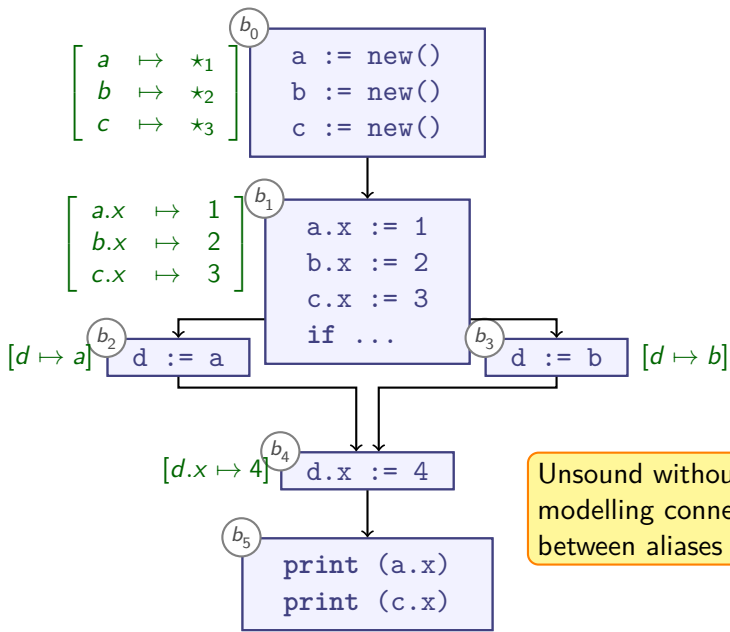
Teal-2

```
var x := new MyType();  
x.field = value;  
print(x.field);
```

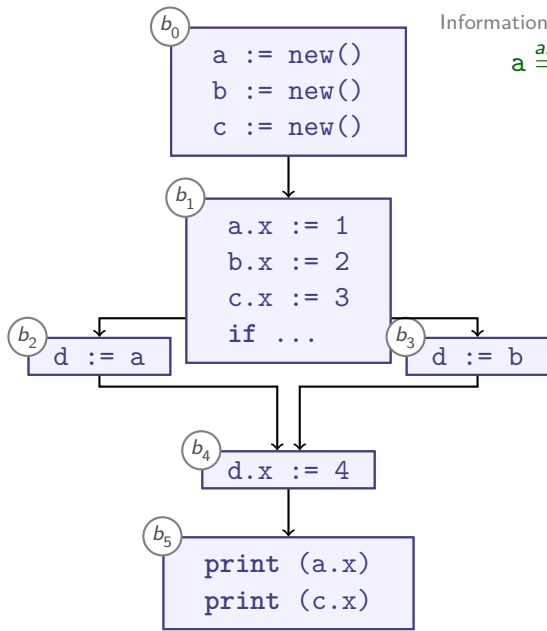
Dataflow with Alias Information



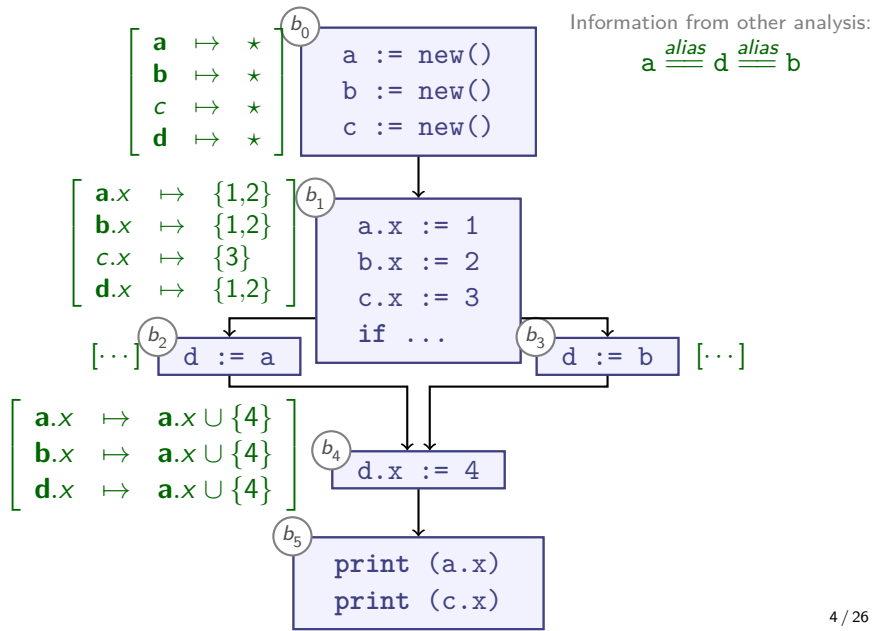
Dataflow with Alias Information



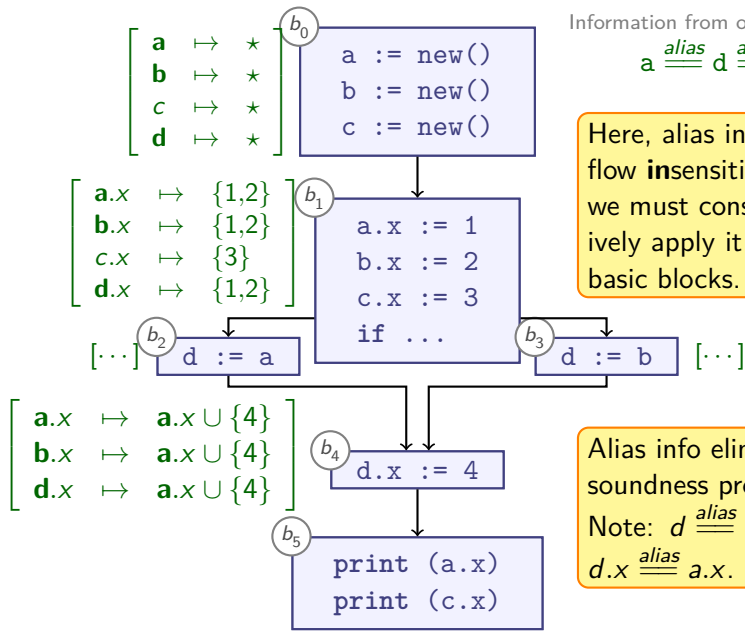
Dataflow with Alias Information



Dataflow with Alias Information



Dataflow with Alias Information



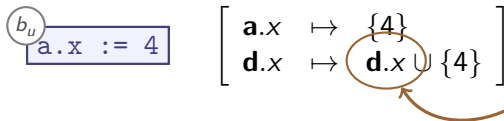
Dataflow + Aliases

- ▶ Aliasing affects shared fields:

$$a \stackrel{\text{alias}}{=} d \implies a.x \stackrel{\text{alias}}{=} d.x \text{ for all } x$$

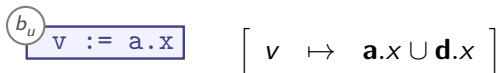
- ▶ Use aliasing knowledge in one of these ways:

- 1 Multiply *updates* for each alias:



Using MAY alias info means that we might or might not update the aliased object.

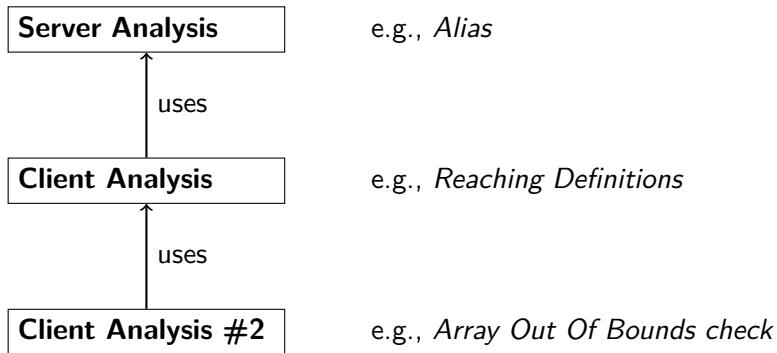
- 2 Multiply *reads* for each alias:



- 3 Replace aliased paths by single representative (e.g., **a** represents both **d** and **a**):



Collaboration in Program Analysis



Analyses often form pipeline structures

Compute Aliases during Dataflow?

- ▶ Previously: Dataflow analysis as *analysis client* of Alias analysis:
- ▶ Can use Dataflow Analysis to compute pointer analyses

- ▶ Caveat:

`y.field := z`

- ▶ Transfer function updates: $y.\text{field} \mapsto z$
- ▶ Must extract both y, z from in_b to compute update
 - ▶ y, z may have aliases
 - ▶ *Non-distributive in general*

Summary

- ▶ **Analysis client:** user of analysis, often another analysis
 - ▶ E.g., *Type analysis* is client of *name analysis*
- ▶ **Alias analysis** helps make dataflow analysis more precise
 - ▶ Fields inherit aliasing:

$$a \stackrel{\text{alias}}{=} b \quad \implies \quad a.x \stackrel{\text{alias}}{=} b.x \text{ for all } x$$

- ▶ So if $a.x \stackrel{\text{alias}}{=} b.y$, then:
 - ▶ $a.x.z \stackrel{\text{alias}}{=} b.y.z$
 - ▶ $a.x.z.z \stackrel{\text{alias}}{=} b.y.z.z$
 - ▶ $a.x.z.z.z \stackrel{\text{alias}}{=} b.y.z.z.z$ etc.
- ▶ Dataflow analysis can compute pointer analyses
 - ▶ Requires non-distributive framework

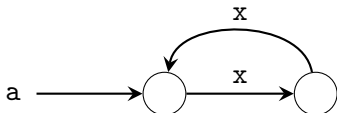
Concrete Heap Graphs (1/2)

Describe heap as a graph:

$$G_{\text{CHG}} = \langle \text{MemLoc}, \rightarrow, \overset{\blacksquare}{\rightarrow} \rangle$$

- ▶ G_{CHG} describes *actual* heap contents
- ▶ MemLoc are addressable memory locations
 - ▶ *Named* variables (a)
 - ▶ *Unnamed* variables (\bigcirc)
- ▶ Heap size typically ‘unbounded for all practical purposes’

```
a := new Obj();  
a.x := new Obj();  
a.x.x := a;
```



Concrete Heap Graphs (2/2)

- ▶ Direct points-to references:

$$(\rightarrow) : (Var \cup DynLoc) \rightarrow DynLoc$$

- ▶ Language difference:

- ▶ **Java/Teal:** *Var* is set of global / local variables and parameters

- ▶ *Disjoint* from *DynLoc*

- ▶ $HeapLoc = Var \cup DynLoc$

- ▶ **C/C++:** $Var = DynLoc = HeapLoc$

- ▶ Address-of operator (&) allows translating variable into *MemLoc*

- ▶ Points-to references via fields:

$$(\overset{\blacksquare}{\rightarrow}) : MemLoc \times Field \rightarrow MemLoc$$

- ▶ Field labels *Field*:

- ▶ E.g., *x* in 'a.x' (Java) / 'a->x' (C/C++)

- ▶ Array indices for 'a[10]' (i.e., $\mathbb{N} \subseteq Field$)

Example

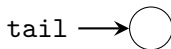
Teal-2

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fun makeList(len) {  
    var tail := new N();  
    tail.next := null;  
    var body := tail;  
    while len > 0 {  
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        body.next := t;  
        len := len - 1;  
    }  
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    return list;  
}
```

Example

Teal-2

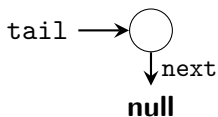
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Example

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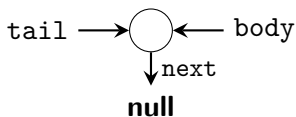
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Example

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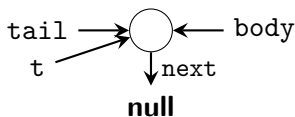
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Example

Teal-2

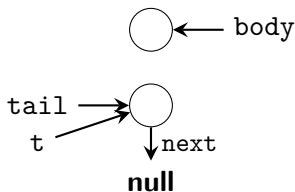
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Example

Teal-2

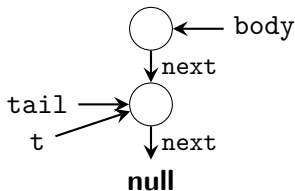
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Example

Teal-2

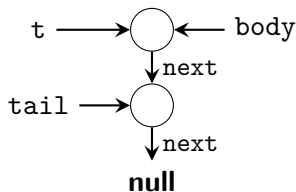
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Example

Teal-2

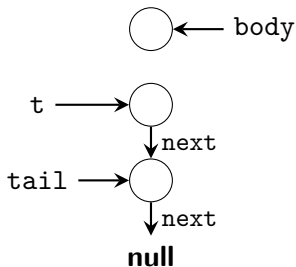
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Example

Teal-2

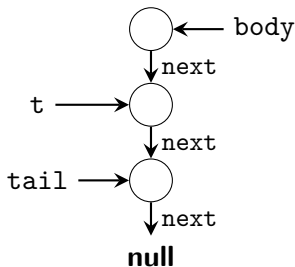
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Example

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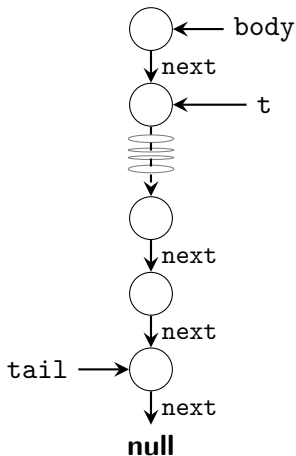
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Example

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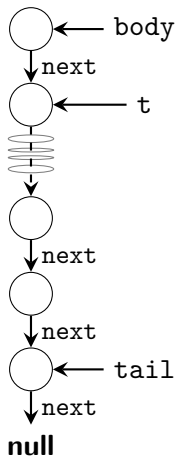
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Example

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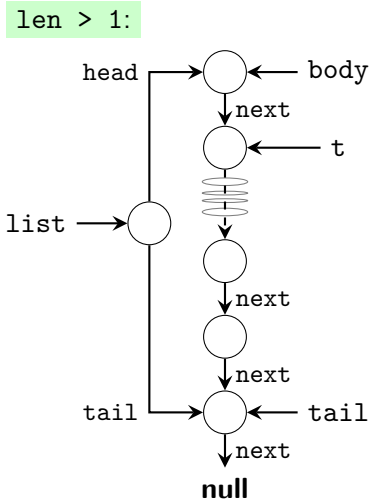
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Example

Teal-2

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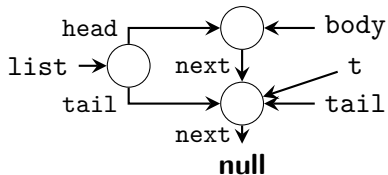


Example

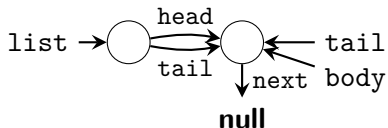
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  }  
  var list := new N();  
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  list.tail := tail;  
  return list;  
}
```

len = 1:



len = 0:

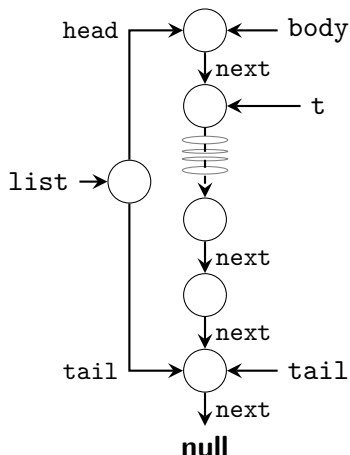


Managing Heap Graphs

- ▶ Size of Concrete Heap Graphs is unbounded
- ▶ Different parameters \implies different Concrete Heap Graphs
- ▶ **Store-less heap models:**
 - ▶ Hide heap locations
 - ▶ Model heap via *access paths*

```
list.head.next.next
```

Store-less Model



- ▶ Access path-based equivalences:

- ▶ **Must:** $\text{list.tail} \stackrel{\text{alias}}{=} \text{tail}$

- ▶ **Must:** $\text{list.head} \stackrel{\text{alias}}{=} \text{body}$

- ▶ **Must:** $\text{body.next} \stackrel{\text{alias}}{=} t$

- ▶ **May:** $\text{body.next}^* \stackrel{\text{alias}}{=} \text{tail}$

- ▶ Use *regular expressions* to denote repetition

- ▶ $\text{body.next}^* \stackrel{\text{alias}}{=} \text{tail}$ means:

$\text{body} \stackrel{\text{alias}}{=} \text{tail}$

$\text{body.next} \stackrel{\text{alias}}{=} \text{tail}$

$\text{body.next.next} \stackrel{\text{alias}}{=} \text{tail}$

...

- ▶ For **May** or **Must** information

Summary

- ▶ **Concrete Heap Graph** (CHG) describes actual heap layout during execution
- ▶ CHG is unbounded, must summarise to analyse
- ▶ **Store-less Models:**
 - ▶ Use **access paths** to describe memory locations
 - ▶ Common in alias analysis

Managing Heap Graphs

- ▶ Size of Concrete Heap Graphs is unbounded
- ▶ Different parameters \implies different Concrete Heap Graphs
- ▶ **Store-less heap models:**
 - ▶ Hide heap locations
 - ▶ Model heap via *access paths*

```
list.head.next.next
```

- ▶ **Store-based heap models:**
 - ▶ Keep heap locations explicit
 - ▶ Introduce *Summary nodes* that can describe multiple CHG nodes

Store-based Model

- ▶ Concrete Heap Graph (CHG): graph of the program's reality

$$G_{\text{CHG}} = \langle \text{MemLoc}, \rightarrow, \overset{\blacksquare}{\rightarrow} \rangle$$

- ▶ Abstract Heap Graph (AHG): approximation of the program's reality

$$G_{\text{AHG}} = \langle \mathcal{P}(\text{MemLoc}), \rightarrow, \overset{\blacksquare}{\rightarrow} \rangle$$

$$(\rightarrow) : \mathcal{P}(\text{MemLoc}) \rightarrow \mathcal{P}(\text{MemLoc})$$

$$(\overset{\blacksquare}{\rightarrow}) : \mathcal{P}(\text{MemLoc}) \times \mathcal{P}(\text{Field}) \rightarrow \mathcal{P}(\text{MemLoc})$$

- ▶ Key idea: AHG is *finite* graph that summarises CHG
- ▶ Soundness via:

$$\begin{array}{lcl} v & \rightarrow & \ell \quad \text{implies} \quad \{v\} \cup V' \quad \rightarrow \quad \{\ell\} \cup L' \\ \ell_0 & \xrightarrow{f} & \ell_1 \quad \text{implies} \quad \{\ell_0\} \cup L'_0 \quad \xrightarrow{\{f\} \cup F'} \quad \{\ell_1\} \cup L'_1 \end{array}$$

- ▶ 'Any CHG edge is represented by (at least) one AHG edge'

Summary Nodes and Edges

Notation:

- ▶ Abstract node $N \subseteq MemLoc$:

- ▶ $|N| = 1$: *precise*: \bigcirc

- ▶ $|N| > 1$: *summary*: \bigcirc (dashed)

- ▶ Consider edge $V \rightarrow L$:

- ▶ $|V| = 1$: *precise*:

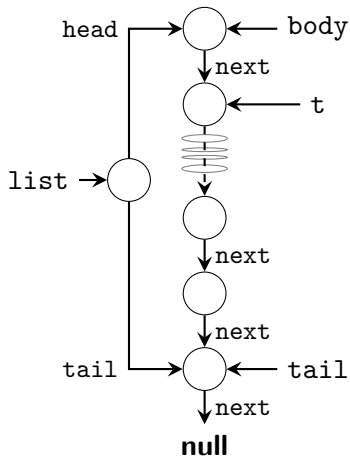
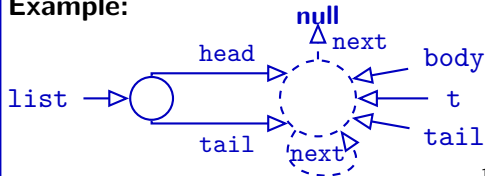
$V \rightarrow L$

- ▶ $|V| > 1$: *summary*:

$V \dashrightarrow L$

- ▶ Analogous for $(\overset{\blacksquare}{\rightarrow} f)$

Example:



Summary

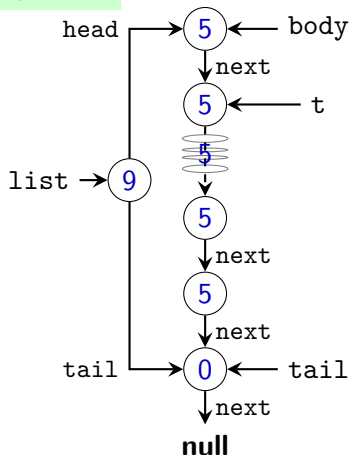
- ▶ **Store-based Models:**
 - ▶ Use **Abstract Heap Graph** to summarise *Concrete Heap Graph*
 - ▶ Common for finding memory bugs
 - ▶ Represents NFA
 - ▶ Equivalent to regular expressions

Summaries from Allocation Sites

Teal-2

```
fun makeList(len) {  
  [0] var tail := new N();  
  [1] tail.next := null;  
  [2] var body := tail;  
  [3] while len > 0 {  
  [4]   var t := body;  
  [5]   body := new N();  
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  [7]   len := len - 1;  
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  [9] var list := new N();  
  [10] list.head := body;  
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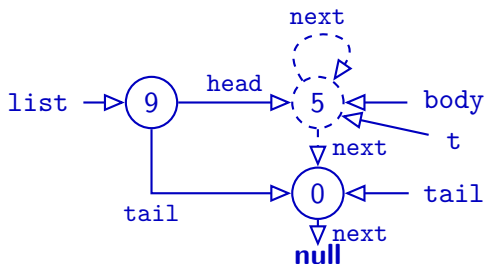
len > 1:



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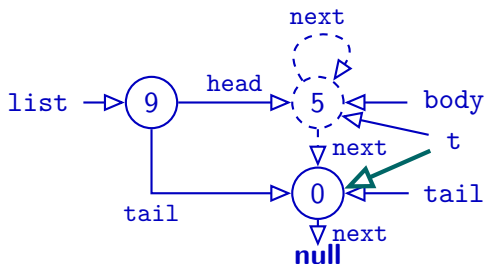


- Summarise *MemLoc* allocated at same program location

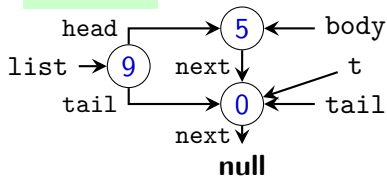
Summaries from Allocation Sites

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len = 1:

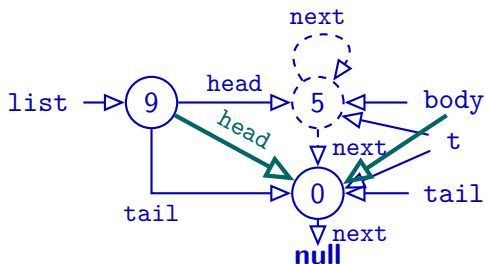


- ▶ Summarise *MemLoc* allocated at same program location
- ▶ Nodes can have multiple outgoing arrows

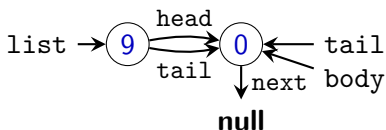
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len = 0:

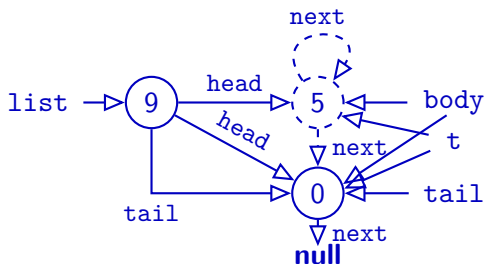


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- ▶ Summarise *MemLoc* allocated at same program location
- ▶ Nodes can have multiple outgoing arrows

Summaries via k -Limiting

- ▶ k -Limiting: bound size

- ▶ Examples: Limiting...

- ▶ Access path length

Example ($k=3$):

<code>list.head.next</code>	\Rightarrow	<code>list.head.next</code>
<code>list.head.next.next</code>	\Rightarrow	<code>list.head.next*</code>
<code>list.head.next.next.next</code>	\Rightarrow	<code>list.head.next*</code>
<code>list.head.next.next.val</code>	\Rightarrow	<code>list.head.(val next)*</code>

- ▶ # of (\rightarrow) hops after named variable
- ▶ # of nodes transitively reachable via (\rightarrow) after named variable
- ▶ # of nodes in a loop / function body

...

Other Summary Techniques

- ▶ General idea: Map $\mathcal{P}(MemLoc)$ to finite (manageable!) set
- ▶ Can combine different techniques for increased precision
- ▶ Other techniques: distinguish heap nodes by:
 - ▶ How many edges point to the node?
 - ▶ Is the node in a cycle?
 - ▶ What is the type of the node? (`ArrayList`, `StringTokenizer`, `File`, ...)
 - ...

Design Considerations

- ▶ First goal remains: make output finite
- ▶ Useful for analysis clients
- ▶ Efficient to compute / represent
- ▶ When considering flow-sensitive models:
 - ▶ Different program locations will have different AHGs
 - ▶ Exploit sharing across program locations

Summary of Heap Summaries

- ▶ *Store-less Models:*
 - ▶ Common in alias analysis
- ▶ **Store-based Models:**
 - ▶ Use **Abstract Heap Graph** to summarise *Concrete Heap Graph*
 - ▶ Common for finding memory bugs
 - ▶ NFA representation \mapsto regular expressions for Access Paths
- ▶ Summarisation techniques:
 - ▶ **Allocation-Site Based:** summarise nodes allocated at same point in program
 - ▶ **k -Limiting:** Set bound on some property P : no more than k P s allowed
 - ▶ Many combinations / extensions conceivable