



**LUND**  
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# EDAP15: Program Analysis

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STEENSGAARD'S POINTS-TO ANALYSIS

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# Pointer Operations

## Referencing

$$a \rightarrow l$$

*Create, point to location:*

## Dereferencing

$$a \rightarrow l \xrightarrow{f} l'$$

*Access location:*

## Aliasing

$$b \rightarrow l \iff a \rightarrow l$$

*Copy pointer:*

### Teal-2

```
a := new A();  
a := [...];
```

### Teal-2

```
- read -  
... := a.f;  
... := a[i];  
- write -  
a.f := ...;  
a[i] := ...;
```

### Teal-2

```
a := b;
```

# Pointer Operations Across Languages

	<b>C</b>	<b>Java</b>	<b>Teal</b>
<b>Referencing</b>	<code>a = &amp;b</code>	<code>a = new A()</code>	<code>a := new A()</code> <code>a := [..., b, ...]</code>
<b>Aliasing</b>	<code>a = b</code>	<code>a = b</code>	<code>a := b</code>
<b>Dereferencing read</b>	<code>a = *b</code>	<code>a = b.f</code> ...	<code>a := b.f</code> <code>b := a[i]</code>
<b>Dereferencing write</b>	<code>*a = b</code>	<code>a.f = b</code> ...	<code>a.f := b</code> <code>a[i] := b</code>

# Summary

- ▶ Points-to analysis: compute **Abstract Heap Graph** by *approximating*

$$v \rightarrow \ell$$

- ▶ Analysis must consider:
  - ▶ **Referencing**: taking (fresh) location
    - ▶ In languages like C/C++, code can also reference locations of stack/global variables
  - ▶ **Dereferencing**: accessing object at location
  - ▶ **Aliasing**: copying location
- ▶ Locations  $\ell$  may model different parts of memory:
  - ▶ Static variables: uniquely defined
  - ▶ Stack-dynamic variables: zero or more copies (recursion!)
  - ▶ Heap-dynamic variables: zero or more copies without variable names attached

# Steensgaard's Points-To Analysis

- ▶ Fast:  $O(n\alpha(n,n))$  over variables in program
  - ▶ Sacrifices Precision for speed
  - ▶ Developed to deal with large code bases at AT&T
- ▶ *Equality-based*
- ▶ Intuition:  
Whenever two variables *might* point to the same memory location, treat them as globally equal

B. Steensgaard. 'Points-to analysis in almost linear time.' In Proceedings of POPL '96, pages 32–41. ACM Press, 1996.

# Distinguishing Field Names?

- ▶ For simplicity, don't distinguish field names:
- ▶  $a.\square$  instead of  $a.f$  or  $a.g$
- ▶ Will discuss consequences of this simplification shortly

# Constraint Collection

- ▶ 'Points-to-set':  $pts(v)$  approximates  $\{\ell \mid v \rightarrow \ell\}$ 
  - ▶  $pts(v) = \{\ell \mid v \rightarrow \ell\}$
- ▶ For each statement in program:
  - ▶ If **Referencing** ( $a := \text{new}_{\ell_b} \dots$ ) (allocation site  $\ell_b$ ):

$$\ell_b \in pts(a)$$

- ▶ If **Aliasing** ( $a := b$ ):

$$pts(a) = pts(b)$$

- ▶ If **Dereferencing read** ( $a := b.\square$ ):

$$\text{for each } \ell \in pts(b) \implies pts(a) = pts(\ell)$$

- ▶ If **Dereferencing write** ( $a.\square := b$ ):

$$\text{for each } \ell \in pts(a) \implies pts(b) = pts(\ell)$$

# Example

$\Rightarrow x := \text{new}_{l_z}$      $l_z \in \text{pts}(x)$   
 $x := y$      $\text{pts}(x) = \text{pts}(y)$   
 $x := y.\square$     for each  $\ell \in \text{pts}(y)$   
                   $\implies \text{pts}(x) = \text{pts}(\ell)$   
 $x.\square := y$     for each  $\ell \in \text{pts}(x)$   
                   $\implies \text{pts}(y) = \text{pts}(\ell)$

## Teal

```
var a := newl1 ();  
var b := newl2 (); //  $\Leftarrow$   
a := newl3 ();  
var p := newl4 ();  
p.n := a;  
var q := newl6 ();  
q.n := b;  
p := q;  
var r := q.n;
```

### ► Actual:

a  $\longrightarrow$   $(l_1)$

p

b  $\longrightarrow$   $(l_2)$

q

r

### ► Steensgaard:

a  $\longrightarrow$   $(l_1)$

p

b  $\longrightarrow$   $(l_2)$

q

r



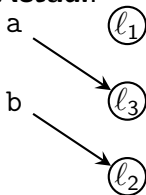
# Example

$\Rightarrow x := \text{new}_{l_z}$      $l_z \in \text{pts}(x)$   
 $x := y$      $\text{pts}(x) = \text{pts}(y)$   
 $x := y.\square$     for each  $\ell \in \text{pts}(y)$   
     $\Rightarrow \text{pts}(x) = \text{pts}(\ell)$   
 $x.\square := y$     for each  $\ell \in \text{pts}(x)$   
     $\Rightarrow \text{pts}(y) = \text{pts}(\ell)$

## Teal

```
var a := newl1 ();  
var b := newl2 ();  
a := newl3 ();    //  $\Leftarrow$   
var p := newl4 ();  
p.n := a;  
var q := newl6 ();  
q.n := b;  
p := q;  
var r := q.n;
```

## Actual:

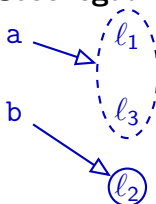


p

q

r

## Steensgaard:



p

q

r

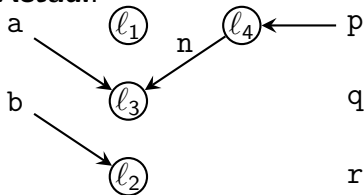
# Example

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 $x := y$          $\text{pts}(x) = \text{pts}(y)$   
 $x := y.\square$      for each  $l \in \text{pts}(y)$   
                   $\implies \text{pts}(x) = \text{pts}(l)$   
 $\implies x.\square := y$  for each  $l \in \text{pts}(x)$   
                   $\implies \text{pts}(y) = \text{pts}(l)$

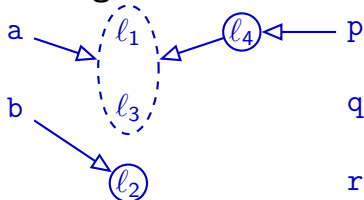
## Teal

```
var a := newl1 ();  
var b := newl2 ();  
a := newl3 ();  
var p := newl4 ();  
p.n := a; // ←  
var q := newl6 ();  
q.n := b;  
p := q;  
var r := q.n;
```

## Actual:



## Steensgaard:



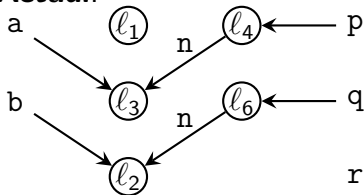
# Example

```
x := newlz   lz ∈ pts(x)
x := y         pts(x) = pts(y)
x := y.□      for each l ∈ pts(y)
               ⇒ pts(x) = pts(l)
⇒ x.□ := y    for each l ∈ pts(x)
               ⇒ pts(y) = pts(l)
```

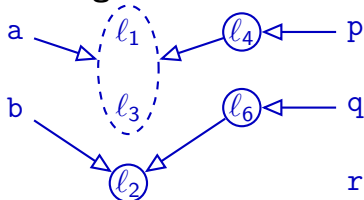
## Teal

```
var a := newl1 ();
var b := newl2 ();
a := newl3 ();
var p := newl4 ();
p.n := a;
var q := newl6 ();
q.n := b; // ←
p := q;
var r := q.n;
```

## Actual:



## Steensgaard:



# Example

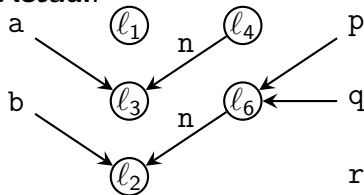
$x := \text{new}_{l_z}$      $l_z \in \text{pts}(x)$   
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                     $\Rightarrow \text{pts}(y) = \text{pts}(l)$

## Teal

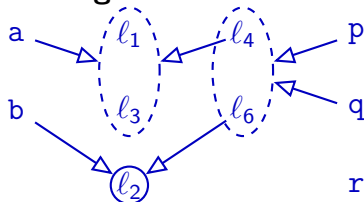
```
var a := newl1 ();  
var b := newl2 ();  
a := newl3 ();  
var p := newl4 ();  
p.n := a;  
var q := newl6 ();  
q.n := b;  
p := q;  
var r := q.n;
```

// $\Leftarrow$

## Actual:



## Steensgaard:



# Example

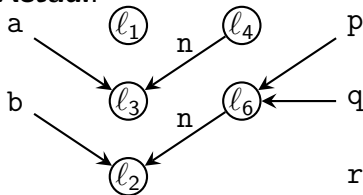
```
x := newlz   lz ∈ pts(x)
⇒ x := y       pts(x) = pts(y)
x := y.□       for each l ∈ pts(y)
                ⇒ pts(x) = pts(l)
x.□ := y       for each l ∈ pts(x)
                ⇒ pts(y) = pts(l)
```

## Teal

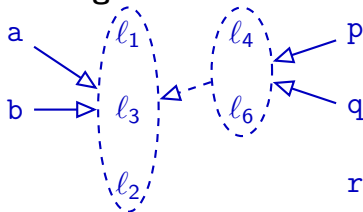
```
var a := newl1 ();
var b := newl2 ();
a := newl3 ();
var p := newl4 ();
p.n := a;
var q := newl6 ();
q.n := b;
p := q;
var r := q.n;
```

// ←

## ► Actual:



## ► Steensgaard:



When merging: 'collapse'  
children (merge recursively)

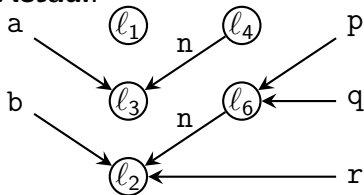
# Example

```
x := newlz   lz ∈ pts(x)
x := y         pts(x) = pts(y)
⇒ x := y.□    for each l ∈ pts(y)
               ⇒ pts(x) = pts(l)
x.□ := y      for each l ∈ pts(x)
               ⇒ pts(y) = pts(l)
```

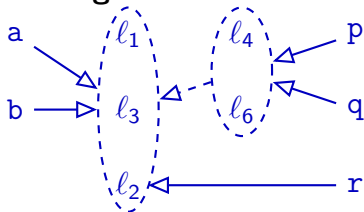
## Teal

```
var a := newl1( );
var b := newl2( );
a := newl3( );
var p := newl4( );
p.n := a;
var q := newl6( );
q.n := b;
p := q;
var r := q.n; // ←
```

## Actual:



## Steensgaard:



When merging: 'collapse'  
children (merge recursively)

# Summary

- ▶ Points-to sets  $pts(v) = \{\ell \mid v \rightarrow \ell\}$
- ▶ Steensgaard's points-to analysis:
  - ▶ special case of *type analysis*
- ▶ Steensgaard's analysis in practice:
  - ▶ Highly efficient when implemented with UNION-FIND
  - ▶ Less precise than other commonly-used analyses