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Graphs

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Rigid body
Spin and orbit
Scene graphs
Exercise 1-2

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Breakpoints
DataTips
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Hierarchical Transformation

EDAF80: Computer Graphics

Rikard Olajos



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FROM LECTURE

$$T = \begin{bmatrix} 1 & 0 & 0 & t_x \\ 0 & 1 & 0 & t_y \\ 0 & 0 & 1 & t_z \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$R_x(\theta) = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & \cos \theta & -\sin \theta & 0 \\ 0 & \sin \theta & \cos \theta & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$S = \begin{bmatrix} s_x & 0 & 0 & 0 \\ 0 & s_y & 0 & 0 \\ 0 & 0 & s_z & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Seminar Exercise 1-1: Vertex Transformations

- 1 Move the triangle to the bottom left corner using the M matrix.
- 2 Move the triangle again, this time to the top right corner.
- 3 Center the triangle and scale it to fill the viewport.
- 4 Remove the M matrix from the transformation and replace it with the rotation matrix R_z .
- 5 Rotate the triangle 90 degrees clockwise.
- 6 Animate the triangle by letting the angle a depend on the uniform variable *time*.

FOLLOW-UP QUESTIONS

- 1 What value of \mathbf{a} rotates the triangle 90 degrees counter-clockwise?
- 2 Try animating something else with *time*!
 - Cap *time* to $[0, 1]$ by using some trigonometric functions: `sin()`, `cos()`

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RIGID BODY

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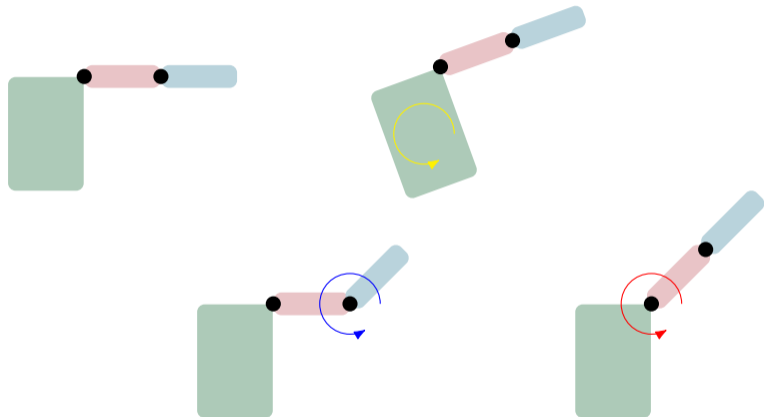
printf

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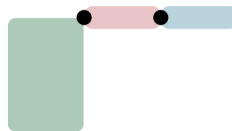
Celestial Body

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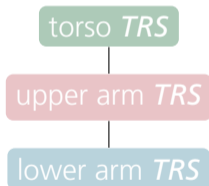
Next



RIGID BODY



Geometry

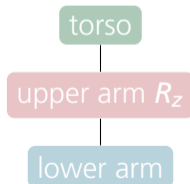
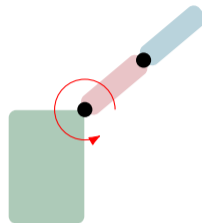
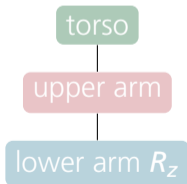
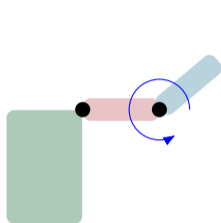


Scene graph representation



Transformations applied
during rendering

RIGID BODY



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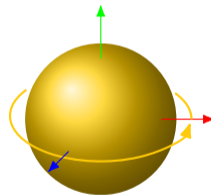
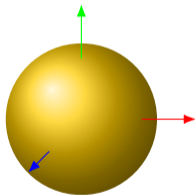
printf

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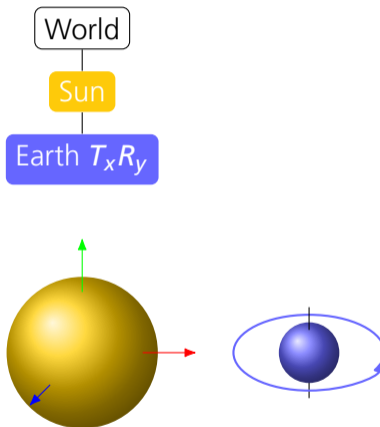
printf

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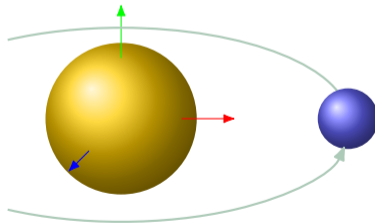
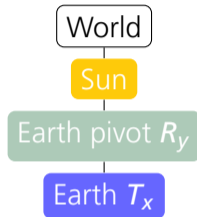
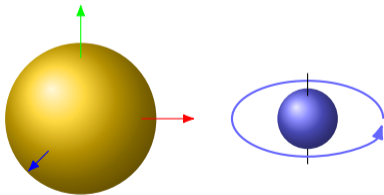
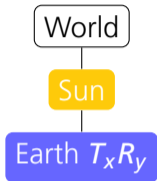
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ORBIT



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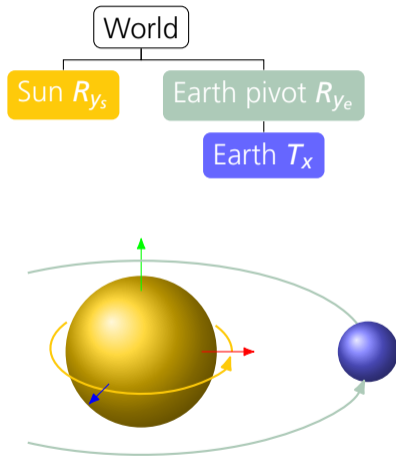
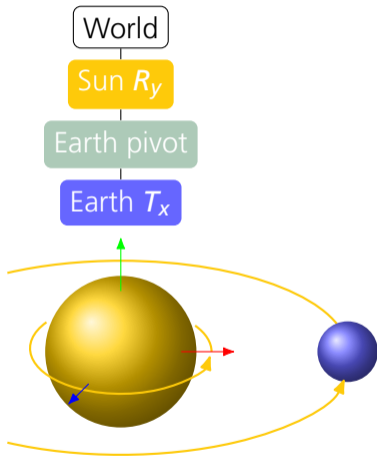
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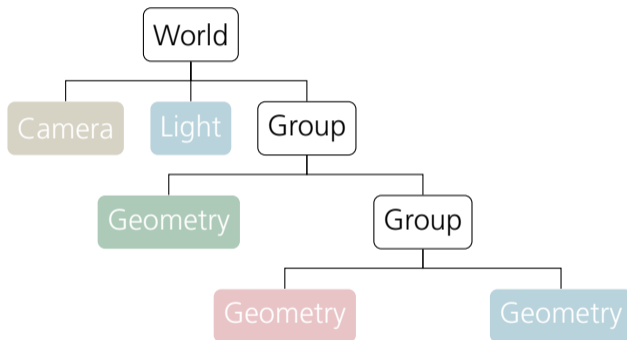
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UNCOUPLING SPIN AND ORBIT



SCENE GRAPHS



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Seminar Exercise 1-2: Hierarchical Transformations

The vertices in this program define a cube with different colors on each side. Currently, the vertices are transformed only by the view and projection matrices.

- 1 Get the cube to spin by replacing the unit matrix in M with the rotation matrix R_S .
- 2 Now, add the translation T_O , so that the cube is spinning offset from the center. The cube should not orbit!
- 3 The last rotation, R_O , will make the cube orbit as well. Add it to the correct position in the chain of transformations.

FOLLOW-UP QUESTIONS

- 1 What was the correct order of transformations?
- 2 We have seen how to use uniforms variables to move vertices around. How would you move the camera?

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C++/OpenGL Framework

C++/OPENGL FRAMEWORK: LIBRARIES

- C++/OpenGL framework: **Bonobo**
- User interface: **GLFW, imgui**
 - Window, GL context, mouse, key, log window, GUI
 - Using OpenGL 4.1
- Resource loading
 - Model/geometry loading: **assimp**
 - Image/texture loading: **stb**
- Vector algebra library: **GLM**
 - Based on OpenGL Shading Language (GLSL) specification
- Don't need to look at this code, just use them as tools

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C++/OPENGL FRAMEWORK: FUNCTIONS

- Mesh structure (`bonobo::mesh_data`)
- Node class
 - Child pointers to build a simple scene graph
 - `render(proj, trans)`
 - Member function to draw node
 - Takes two matrices: projection and transformation
- OpenGL texture setup function (`loadTexture2D()`)
- Shader setup: loading, compiling, linking (`createProgram()`)
- `while` loop to render scene graph
 - Add per frame node operations here (for example: `sun.rotate_y(0.01f)`)
 - Pushes `root_node` onto stack, then process all child nodes

CREATING A NODE

- sphere and shader are set up and can be used as is

```
Node sun = Node();  
sun.set_geometry(sphere);  
sun.set_program(shader);
```

```
GLuint sun_texture = loadTexture2D("sunmap.png");  
sun.add_texture("diffuse_texture", sun_texture, GL_TEXTURE_2D);
```

ADDING MORE NODES

- Add more nodes and start building the scene graph

```
Node world = Node();
```

```
world.add_child(&sun);
```

```
...
```

```
sun.add_child(/* Add planets */);
```

MOVING NODES

- Use translation, rotation and scaling functions
- Use a time variable to animate

```
/* Absolute transformations */  
sun.get_transform().SetScale(2.0f);  
earth.get_transform().SetTranslate(glm::vec3(3.0f, 0.0f, 0.0f));  
earth.get_transform().SetTranslate(glm::vec3(time, 0.0f, 0.0f));
```

```
/* Relative transformations */  
earth.get_transform().Scale(0.9f);  
sun.get_transform().RotateY(0.7f);
```

```
/* Useful rotation transformations */  
earth.get_transform().LookTowards(...); /* Look in a given direction */  
earth.get_transform().LookAt(...); /* Look at a fixed point */
```

INTERACTION

- FPS camera
 - Keyboard: "WASD" to move camera forward/left/backward/right
 - Keyboard: "QE" to move up/down
 - `shift` and `ctrl` to modify speed of movement
 - Mouse: Click and drag left mouse button

- User interface (imgui) with mouse



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VISUAL STUDIO DEBUGGING

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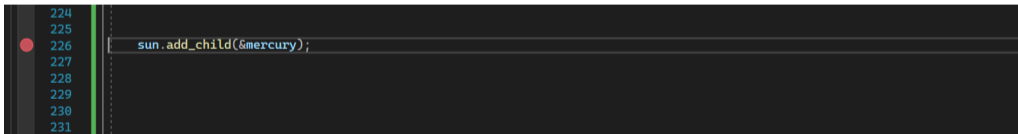
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- Breakpoints
- DataTips
- `printf`

BREAKPOINTS

- A breakpoint pauses execution
- Allows for inspection of variables, stepping of lines
- Toggle breakpoint on currently line with **F9**, or click the area to the left of the line
- Right-click a breakpoint to add conditions
- Once breakpoint is hit, step (**F10**), step into (**F11**) or continue (**F5**) execution



The screenshot shows a code editor with a dark background. On the left side, there is a vertical list of line numbers from 224 to 231. A red circle, representing a breakpoint, is positioned to the left of line 226. A vertical green line is positioned to the left of line 225. The code on line 226 is `sun.add_child(&mercury);`. The editor is otherwise empty.

- Inspect/edit variables by hovering above them with mouse pointer
- Click to expand
- Right-click and select “Watch” to pin variable to the Watch-window

```
224  
225  
226 ▶ sun.add_child(&mercury);  
227   ▶ mercury {_body={node={_vao=3 _vertices_nb=0 _indices_nb=18720 ...} orbit={radius=2.00000000 inclination=-0.0593411960 ...} ...} ...}  
228  
229  
230  
231
```

```
224  
225  
226 sun.add_child(&mercury);  
227   ◀ mercury {_body={node={_vao=3 _vertices_nb=0 _indices_nb=18720 ...} orbit={radius=2.00000000 inclination=-0.0593411960 ...} ...} ...}  
228     ▶ _body {node={_vao=3 _vertices_nb=0 _indices_nb=18720 ...} orbit={radius=2.00000000 inclination=-0.0593411960 ...} ...}  
229     ▶ _ring {node={_vao=0 _vertices_nb=0 _indices_nb=0 ...} scale={x=1.00000000 r=1.00000000 s=1.00000000 ...} is_set=...}  
230     ▶ _children {size=0}  
231
```

- Brute force debugging
- Print whatever you need to monitor to the standard output (console window)

```
printf("Monitored value: %f\n", var);
```

- Or use `std::cout`

```
std::cout << "Monitored value: " << var << "\n";
```

- Can format the output
- Can monitor output continuously as the program executes
- Messy code 😞

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Assignment 1

- **Model the solar system!**
 - Sun, planets, moons, comets, ...spaceships? It's up to you
 - Resources included in the Bonobo framework are at your disposal
 - Models, textures, shaders
 - Code for how to add shaders is included (more in assignment 3–4)
- See assignment description for details
 - Available on the [course webpage](#)
 - Source code in assignment description
- Files you have to modify
 - `src/EDAF80/assignment1.cpp`
 - `src/EDAF80/CelestialBody.cpp`

CELESTIAL BODY

```
class CelestialBody
{
public:
    CelestialBody(...);
    glm::mat4 render(...);
    void add_child(CelestialBody* child);
    ...

private:
    struct {
        Node node;
        struct { /* radius, inclination, speed, rotation_angle */ } orbit;
        struct { /* axial_tilt, speed, rotation_angle */ } spin;
    } _body;

    struct { Node node; ... } _ring;
};
```

```
glm::mat4 CelestialBody::render(
    glm::mat4 const& view_projection,
    glm::mat4 const& parent_transform,
    ...)
{
    ...

    glm::mat4 world = parent_transform;

    /* Edit world matrix here */
    glm::mat4 scale = glm::scale(glm::mat4(1.0f), glm::vec3(0.5f));
    world = world * scale;

    /* Supply full transformation matrix! */
    _body.node.render(view_projection, world);

    return parent_transform;
}
```


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- Download the code and get started
- Post questions on the discussion forum
- Use the [reference implementation](#) to compare your results