

Exam – Computer Graphics

13 January 2011, 14-19

- 1 (a) What is the most efficient way to calculate the inverse of a rotation matrix? (0.3)
 (b) What is the most important advantage of representing transforms as matrices? (0.4)
 (c) How is this advantage utilized in the design of a renderer? (0.3)

- 2 (a) Explain how *rasterization* of a triangle is done. (0.5)
 (b) Explain how *shading* of a rasterized triangle is done. (0.5)

- 3 (a) What is *perspective correct interpolation*?. (0.4)
 (b) What is *light mapping* and what is it useful for. (0.3)
 (b) What is *image based lighting*. (0.3)

- 4 (a) What is *bump mapping* and what is it used for? (0.4)
 (b) Which data must the mesh provide in order to apply it? (0.3)
 (c) Describe the algorithm for bump mapping. (0.3)

- 5 Compute $T^*(1,1,1)$ where T is defined as the matrix product

$$T = M1 * R1 * S * M2 * R2$$

where each term is the matrix for a two-dimensional transform in homogenous coordinates as given below:

M1: translation by the vector (-1,-1)
R1: rotation 45 degrees anti-clockwise
S: scaling by the factor 2
M2: translation by the vector (1,1)
R2: rotation 90 degrees clockwise

- 6 (a) State the per-pixel and per-vertex expressions for the diffuse reflection according to Phong's reflection model in a point with barycentric coordinates (b_0, b_1, b_2) . The vertices of the triangle have normals $(\mathbf{n}_0, \mathbf{n}_1, \mathbf{n}_2)$ the light comes from a directional light source such that the light vector is \mathbf{L} and the light intensity at the triangle is I . (0.8).
 (b) In Phong's reflection model there is a so called *ambient* term. What is it and what is its purpose? (0.2)

THE END!