## Exam - Computer Graphics

## 8 January 2010, 14-19

1 (a) What characterizes a rotation matrix? (0.3)
(b) What is the most important advantage of representing transforms as matrices? (0.4)
(c) How is this advantage utilized in the design of a renderer? (0.3)

2 (a) Explain how rasterization of triangle is done. (0.5)
(b) Exlplain how the shading of a rastrerized triangle is done? (0.5)

3 (a) What is the visual difference between flat shading and smooth shading. (0.3)
(b) How do their implementations differ? (0.7)
4. (a) What is a cube map and what is it used for? (0.2)
(b) How do you do lookup in a cube map? (0.8)

5 (a) Describe what is drawn on the screen after a call to the function $\operatorname{draw}()$ below. (0.8)

```
def draw():
    glColor(1, 0, 0)
    glPushMatrix()
    glScale(2, 1, 1)
    glTranslate(-2, 0, 0)
    drawSquare()
    glColor(0, 1, 0)
    glTranslate(2, 3, 0)
    glPushMatrix()
    glRotate(90, 0,0,-1)
    glPushMatrix()
    glRotate(180, 0,0,1)
    glTranslate(-2, -1, 0)
    glPopMatrix()
    glPushMatrix()
    glScale(2, 2, 1)
    drawSquare()
    glColor(0, 0, 1)
    glPopMatrix()
    glPushMatrix()
    glRotate(90, 0,0,1)
    glTranslate(-1, 0, 0)
    drawSquare()
def drawSquare():
    glBegin(GL_QUADS)
    glVertex(0,0)
    glVertex(0,1)
    glVertex (1,1)
    glVertex(1,0)
    glEnd()
```

(b) OpenGL has a concept called display list? What is it and which problem does it solve? (0.2)

6 (a) Which relationships does the rendering equation express? (0.6)
(b) Write down the equation and explain what each of its constituents means. Answer as detailed as you can (0.4)

## THE END!

