## **Exam – Computer Graphics**

8 January 2010, 14-19

- 1 (a) What characterizes a rotation matrix? (0.3)
  - (b) What is the most important advantage of representing transforms as matrices? (0.4)
  - (c) How is this advantage utilized in the design of a renderer? (0.3)
- 2 (a) Explain how rasterization of triangle is done. (0.5)
  - (b) Exlplain how the shading of a rastrerized triangle is done? (0.5)
- 3 (a) What is the visual difference between *flat shading* and *smooth shading*. (0.3)
  - (b) How do their implementations differ? (0.7)
- 4. (a) What is a *cube map* and what is it used for? (0.2)
  - (b) How do you do lookup in a *cube map*? (0.8)
- 5 (a) Describe what is drawn on the screen after a call to the function draw() below. (0.8)

```
def draw():
   glColor(1, 0, 0)
   glPushMatrix()
   glScale(2, 1, 1)
   glTranslate(-2, 0, 0)
   drawSquare()
   glColor(0, 1, 0)
   glTranslate(2, 3, 0)
   glPushMatrix()
   qlRotate(90, 0, 0, -1)
   glPushMatrix()
   glRotate(180, 0,0,1)
   glTranslate(-2, -1, 0)
   glPopMatrix()
   glPushMatrix()
   glScale(2, 2, 1)
   drawSquare()
   glColor(0, 0, 1)
   glPopMatrix()
   glPushMatrix()
   glRotate(90, 0,0,1)
   glTranslate(-1, 0, 0)
   drawSquare()
def drawSquare():
   glBegin(GL QUADS)
   glVertex(0,0)
   glVertex(0,1)
   glVertex(1,1)
   glVertex(1,0)
   glEnd()
```

(b) OpenGL has a concept called *display list*? What is it and which problem does it solve? (0.2)

- (a) Which relationships does the *rendering equation* express? (0.6)(b) Write down the equation and explain what each of its constituents means. Answer as detailed as you can (0.4)

THE END!