Exam – Computer Graphics

20 december 2003, 8-13

- 1 (a) What is the most important advantage of representing transforms with matrices? (0.3)
 - (b) How is this utilized in the design of a renderer? (0.4)
 - (c) How is the transformation of normals different from the transformation of vectors? (0.3)
- 2 (a) What is *Catmull-Rom-interpolation*? (0.6)
 (b) What is *back face culling*, and how is it done? (0.4)
- 3. (a) What is a *cube map* and what is it used for? (0.2)
 (b) How do you do lookup in a cube map? (0.8)
- 4 (a) What are *barycentric coordinates*? (0.3)
 (b) Explain how barycentric coordinates can be used for rasterization and shading of triangle meshes. (0.7)
- 5 (a) Describe what a call to the function draw() below will draw on the screen. (0.8)

```
def draw():
    glColor(1,0,0)
    glPushMatrix()
    glScale(3,3,3)
    glTranslate(2,0,0)
    glRotate(90, 0,0,1)
    glPushMatrix()
    glTranslate(1,0,0)
    drawSquare()
    glColor(0,1,0)
    glPopMatrix()
    glPushMatrix()
    glTranslate(4,0,0)
    glScale(0.5,0.5,0.5)
    glRotate(270, 0,0,1)
    drawSquare()
def drawSquare():
    glBegin(GL_QUADS)
    glVertex(0,0,0)
    glVertex(0,1,0)
    glVertex(1,1,0)
    glVertex(1,0,0)
    glEnd()
```

- (b) What is a *vertex array*? And what are its advantages? (0.2)
- 6 (a) A triangle surface with vertices P_0 , P_1 , P_2 bis lit by a point light source with transmittance L and positioned in P_L . There is no ambient light in the scene. Use Phong's reflection model to determine the light reflection reaching the point P_V from each of the vertices. (0.7)

Material parameters	Vertex positions	Light source	Viewer position
$k_a = 0.1$		L = 1.0	
$k_{d} = 0.5$	$P_0 = \begin{vmatrix} 0 \\ P_1 \end{vmatrix} = \begin{vmatrix} 4 \\ P_2 \end{vmatrix} = \begin{vmatrix} 0 \\ P_1 \end{vmatrix}$	5	[8]
$k_{s} = 0.2$		$P_L = 3$	$P_V = 1$
$\alpha = 3$			[8]

(b) Determine the light reflection from the point P=(2/3, 2/3, 4) by interpolation over the triangle surface. (0.3)

SLUT!