



**LUND**  
UNIVERSITY

# EDAP15: Program Analysis

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## POINTER ANALYSIS 2

**Christoph Reichenbach**



**Welcome back!**

Questions?

# Lecture Overview

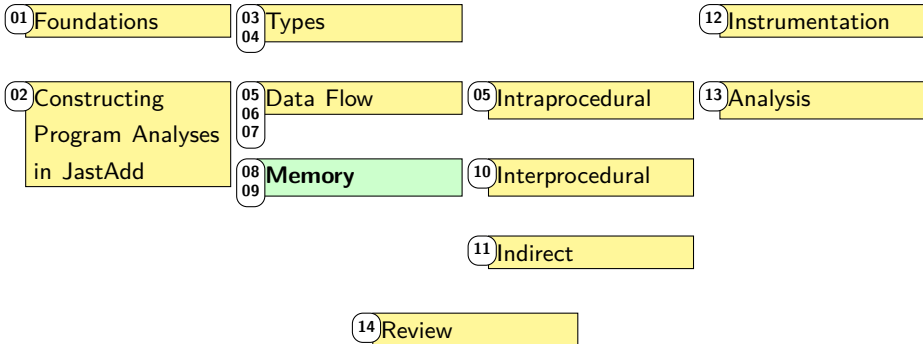
Foundations

Static Analysis

Dynamic  
Analysis

Properties

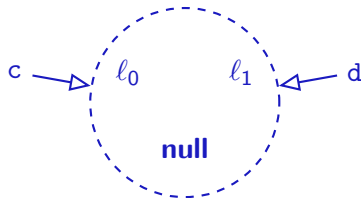
Control Flow



# Alias Analysis in Practice (1/2)

## Teal

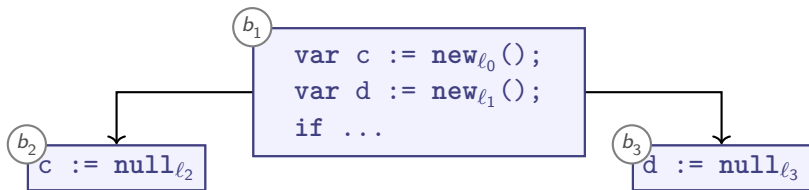
```
var c := newℓ0 ();  
var d := newℓ1 ();  
if ... {  
  c := null;  
} else {  
  d := null;  
}
```



$c \stackrel{\text{alias}}{=} d$

**null as unique memory location: Imprecision!**

# Representing Null Pointers



## 1 One unique **null**



## 2 Many **nulls** (More precise, takes up extra memory)



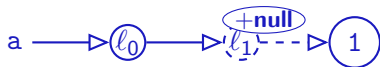
## 3 Nullness flags (Also more precise, minimal extra memory, but more complex analysis code)



# Alias Analysis in Practice (2/2)

## Teal

```
var a := newℓ0 XY();  
a.x := newℓ1 XY();  
a.x.x := 1;  
a.y := null;  
  
print(a.x.x);  
// null dereference?
```



In this example: ignore field names  
(as we did with Steensgaard)

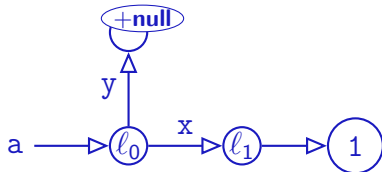
`a.x` alias `null` alias `a.□` alias `a.y`

# Field Sensitivity

- ▶ For Steensgaard, we merged all fields:

$$a.x \stackrel{\text{alias}}{=} a.\square \stackrel{\text{alias}}{=} a.y$$

- ▶ Analysis that merge field names: *field insensitive*
- ▶ A *field-sensitive* analysis would distinguish:



# Summary

- ▶ Points-to analyses often want to represent **null**
  - ▶ Single global **null** may reduce precision (in unification-based analysis)

- ▶ Some program analyses are **field insensitive**:

$$a.x \stackrel{\text{alias}}{=} a.\square \stackrel{\text{alias}}{=} a.y \quad (\text{always})$$

- ▶ **Field-sensitive** analyses improve precision by distinguishing fields along points-to edges:

$$a.x \not\stackrel{\text{alias}}{=} a.y \quad (\text{unless explicit evidence})$$

- ▶ Analogous: **index-sensitive** analyses:

$$a[0] \stackrel{\text{alias}}{=} a[1] \stackrel{\text{alias}}{=} \dots \stackrel{\text{alias}}{=} a[i]$$

# Dataflow-Based Points-To Analysis

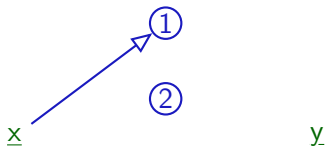
$$\begin{aligned} G_{\text{AHG}} &= \langle \bar{L}, \rightarrow \rangle \\ (\rightarrow) &\subseteq \bar{L} \times \bar{L} \end{aligned}$$

- ▶ Points-To via Dataflow:
- ▶ Lattice over set of edges between memory locations  $\bar{L}$
- ▶  $\sqcup = \cup$
- ▶  $\sqsubseteq = \subseteq$

# Example: Allocation and Update

## Teal

```
var x := new1();  
⇒ var y := new2();  
  
if ... {  
  y := new5();  
}  
  
x := new7();  
y := x;
```



## Case

x := new<sub>ℓ</sub>()

## Transfer Function

$trans_1(\rightarrow) = (\rightarrow)$

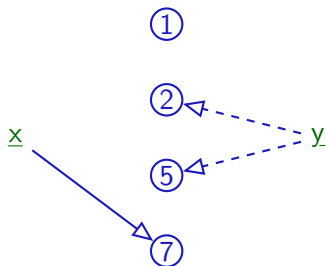
$\cup \{ \underline{x} \rightarrow \ell \}$

Slight abuse of notation: writing  $x \rightarrow \ell$  for  $\langle x, \ell \rangle$

# Example: Allocation and Update

Teal

```
var x := new1();  
var y := new2();  
  
if ... {  
  y := new5();  
}  
  
⇒ x := new7();  
   y := x;
```



Remove all  $\underline{x} \rightarrow l$  for any  $l \in \bar{L}$

Case

$\underline{x} := \text{new}_l()$

Transfer Function

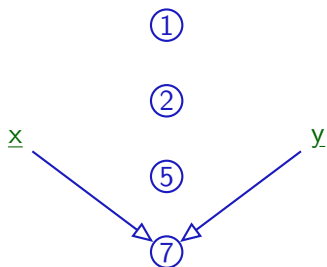
$\text{trans}_1(\rightarrow) = (\rightarrow) \setminus (\{\underline{x}\} \times \bar{L}) \cup \{\underline{x} \rightarrow l\}$

Slight abuse of notation: writing  $\underline{x} \rightarrow l$  for  $\langle \underline{x}, l \rangle$

# Example: Allocation and Update

## Teal

```
var x := new1();  
var y := new2();  
  
if ... {  
  y := new5();  
}  
  
x := new7();  
⇒ y := x;
```



## Case

x := new<sub>l</sub>()  
y := x;

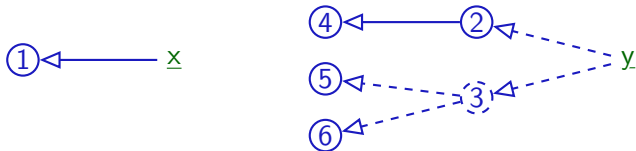
## Transfer Function

$trans_1(\rightarrow) = (\rightarrow) \setminus (\{\underline{x}\} \times \bar{L}) \cup \{\underline{x} \rightarrow l\}$   
 $trans_2(\rightarrow) = (\rightarrow) \setminus (\{\underline{y}\} \times \bar{L}) \cup \{\underline{y} \rightarrow l \mid \underline{x} \rightarrow l\}$

Slight abuse of notation: writing  $x \rightarrow l$  for  $\langle x, l \rangle$

# Dereferencing Read

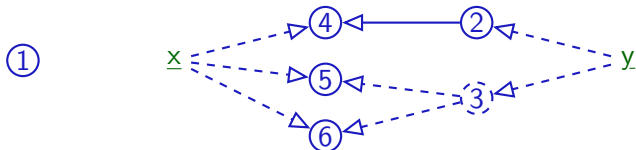
Before:



Teal

$x := y.f;$

After:



Case

$x := y.\square;$

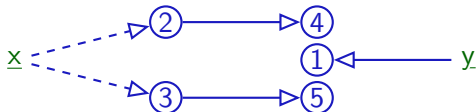
Transfer Function

$trans_3(\rightarrow) = (\rightarrow) \setminus (\{x\} \times \bar{L}) \cup \{x \rightarrow l' \mid \exists l.$

$y \rightarrow l \rightarrow l'\}$

# Dereferencing Write

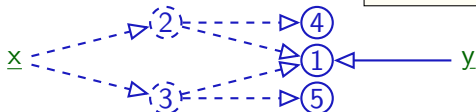
Before:



Teal

$\underline{x}.f := \underline{y};$

After:



Cannot remove edges:  
We don't know if it was 2  
or 3 that was changed!

Case

$\underline{x}.\square := \underline{y};$

Transfer Function

$trans_4(\rightarrow) = (\rightarrow) \setminus (\{\underline{x}\} \times \bar{L}) \cup \{l \rightarrow l' \mid \underline{x} \rightarrow l, \underline{y} \rightarrow l'\}$

# Weak vs Strong Update?

- ▶ **Strong update:**
  - ▶ Can remove “obsolete” information
- ▶ **Weak update:**
  - ▶ Cannot remove “obsolete” information
  - ▶ Observed with dereferencing write
- ▶ Dereferencing write *can* be strong if  $\underline{x}$  can point to only one location

## Teal

```
 $\underline{x}.f := \underline{y};$ 
```

# Dataflow-Based Points-To Analysis

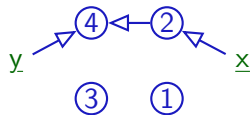
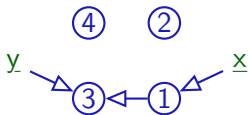
$$G_{\text{AHG}} = \langle \bar{L}, \rightarrow \rangle$$

$$(\rightarrow) \subseteq \bar{L} \times \bar{L}$$

$\underline{x} := \text{new}_\ell()$	$trans_1(\rightarrow) = (\rightarrow) \setminus (\{\underline{x}\} \times \bar{L}) \cup \{ \underline{x} \rightarrow \ell \}$
$\underline{x} := \underline{y};$	$trans_2(\rightarrow) = (\rightarrow) \setminus (\{\underline{x}\} \times \bar{L}) \cup \{ \underline{x} \rightarrow \ell \mid \underline{y} \rightarrow \ell \}$
$\underline{x} := \underline{y}. \square;$	$trans_3(\rightarrow) = (\rightarrow) \setminus (\{\underline{x}\} \times \bar{L}) \cup \{ \underline{x} \rightarrow \ell' \mid \exists \ell. \underline{y} \rightarrow \ell \rightarrow \ell' \}$
$\underline{x}. \square := \underline{y};$	$trans_{4_{\text{weak}}}(\rightarrow) = (\rightarrow) \cup \{ \ell \rightarrow \ell' \mid \underline{x} \rightarrow \ell, \underline{y} \rightarrow \ell' \}$
$\underline{x}. \square := \underline{y};$	$trans_{4_{\text{strong}}}(\rightarrow) = (\rightarrow) \setminus (\{\underline{x}\} \times \bar{L}) \cup \{ \ell \rightarrow \ell' \mid \underline{x} \rightarrow \ell, \underline{y} \rightarrow \ell' \}$

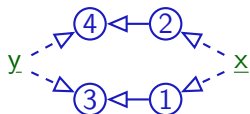


# Distributivity?



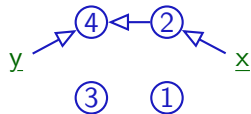
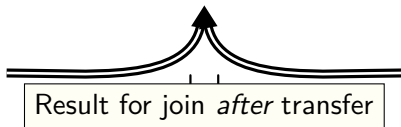
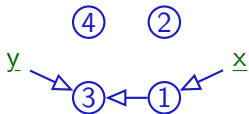
Teal

$\underline{x}.f := y;$

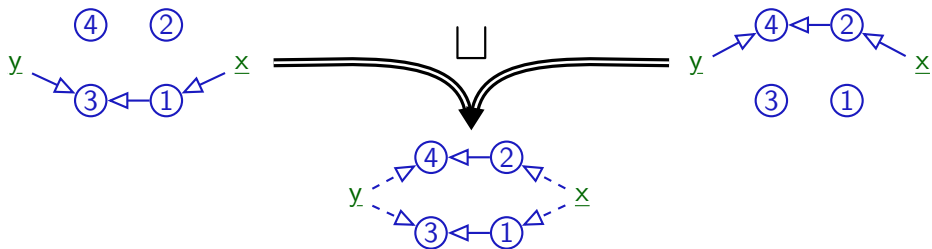


Teal

$\underline{x}.f := y;$



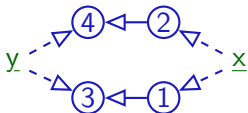
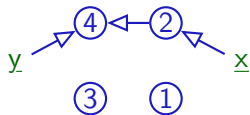
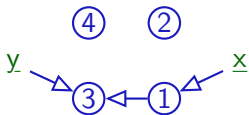
# Distributivity?



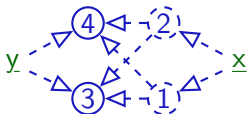
Teal

$\underline{x}.f := y;$

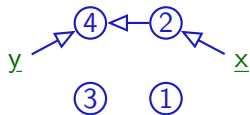
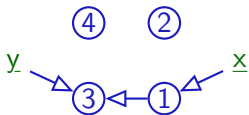
# Distributivity?



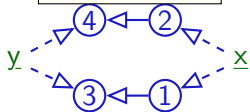
Teal  $\Downarrow$  trans  
 $x.f := y;$



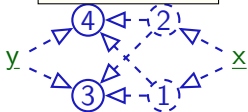
# Distributivity?



$\sqcup$ , then *trans*



*trans*, then  $\sqcup$



**Different results  $\implies$  not distributive!**

# Summary

- ▶ Flow-sensitive points-to analysis is possible but expensive
- ▶ **Weak updates** add new points-to relationship options
  - ▶ Don't remove existing options
- ▶ **Strong updates** add but also remove points-to relationship options
  - ▶ More precise than weak updates
  - ▶ Only possible if updated pointer is unambiguous
- ▶ *Not Distributive*

# Andersen's Points-To Analysis

- ▶ Asymptotic performance is  $O(n^3)$
- ▶ More precise than Steensgaard's analysis
- ▶ *Subset-based* (a.k.a. *inclusion-based*)
- ▶  $\implies$  Flow-insensitive but *directed*
- ▶ Popular as basis for current points-to analyses

L. Andersen, "Program Analysis and Specialization for the C Programming Language", PhD. thesis, DIKU report 94/19, 1994

# Collecting Constraints

- ▶ Collect constraints, resolve as needed
- ▶ For each statement in program, we record:
  - ▶ If **Referencing** ( $x := \text{new}_{\ell_i} A()$ ):

$$\ell_i \in pt(x) \quad (x \rightarrow \ell_i)$$

- ▶ If **Aliasing** ( $x := y$ ):

$$pt(x) \supseteq pt(y)$$

- ▶ If **Dereferencing read** ( $x := y.\square$ ):

$$pt(x) \supseteq pt(y.\square)$$

- ▶ If **Dereferencing write** ( $x.\square := y$ ):

$$pt(x.\square) \supseteq pt(y)$$

# Andersen's Analysis

## 1 Fact extraction:

- ▶ Initial points-to sets:  $l \in pt(x)$ , meaning  $l \leftarrow x$
- ▶ Constraints:
  - ▶  $pt(x) \supseteq pt(y)$
  - ▶  $pt(x) \supseteq pt(y.\square)$
  - ▶  $pt(x.\square) \supseteq pt(y)$

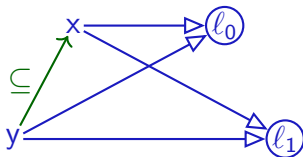
# Subset Constraints (1/2)

- ▶ Solving  $pt(x) \supseteq pt(y)$

$y := \text{new}_{l_0}();$

$x := y;$

$y := \text{new}_{l_1}();$



- ▶  $l \leftarrow y$  and  $pt(x) \supseteq pt(y)$  :

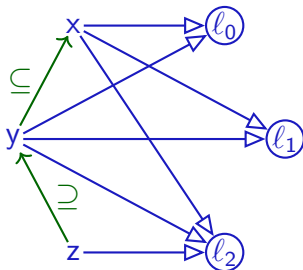
$\implies l \leftarrow x$

- ▶ *Flow insensitive*: can't distinguish before/after

# Subset Constraints (1/2)

- ▶ Solving  $pt(x) \supseteq pt(y)$

```
y := newl0 ();  
x := y;  
y := newl1 ();  
z := newl2 ();  
if ... {  
  y := z;  
}
```



- ▶  $l \leftarrow y$  and  $pt(x) \supseteq pt(y)$  :  
 $\implies l \leftarrow x$
- ▶ *Flow insensitive*: can't distinguish before/after

Solving one ( $\supseteq$ ) can depend on all ( $\leftarrow$ ) and ( $\supseteq$ ) in program

# Composite Statements

- ▶ Decompose more complex patterns:

```
y.n := newℓ1 ();
```

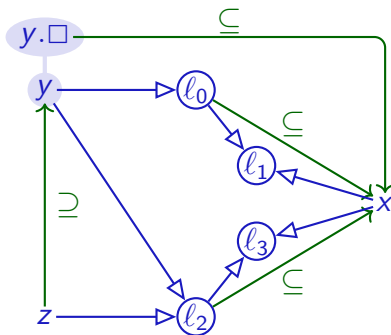
- ▶ No direct pattern for this code
- ▶ Can model as:  
var tmp := new<sub>ℓ<sub>1</sub></sub> ();  
y.n := tmp;

# Subset Constraints (2/2)

- ▶ Solving  $pt(x) \supseteq pt(y.\square)$

```
y := newl0 ();  
y.n := newl1 ();  
z := newl2 ();  
z.n := newl3 ();  
y := z;  
x := y.n;
```

Simplified presentation (omitting  $\supseteq$  constraints)



- ▶ Recall:

$l \leftarrow z$  and  $pt(y) \supseteq pt(z)$  :  
 $\implies l \leftarrow y$

- ▶  $l \leftarrow y$  and  $pt(x) \supseteq pt(y.\square)$  :  
 $\implies pt(x) \supseteq pt(l)$

# Andersen's Analysis

## 1 Fact extraction:

- ▶ Initial points-to sets:  $l \in pt(x)$ , meaning  $l \leftarrow x$
- ▶ Constraints:
  - ▶  $pt(x) \supseteq pt(y)$
  - ▶  $pt(x) \supseteq pt(y.\square)$
  - ▶  $pt(x.\square) \supseteq pt(y)$

## 2 Build directed *inclusion graph* $G_I = \langle MemLoc, E \rangle$

- ▶  $x \leftarrow y$  represents  $pt(x) \supseteq pt(y)$  (" $x := y$ ")

## 3 Expand and propagate along inclusion graph:

- ▶ Propagate points-to sets along  $E$ :
  - ▶  $l \leftarrow y$  and  $x \leftarrow y$  :  
 $\implies l \leftarrow x$
  - ▶  $l \leftarrow y$  and  $x \leftarrow y.\square$  :  
 $\implies x \leftarrow l$
  - ▶  $l \leftarrow x$  and  $x.\square \leftarrow y$  :  
 $\implies l \leftarrow y$

# Example

$\Rightarrow$   $x := \text{new}_{\ell_z}$      $x \rightarrow \ell_z$   
 $x := y$      $x \leftarrow y$   
 $x := y.\square$      $x \leftarrow y.\square$   
 $x.\square := y$      $x.\square \leftarrow y$

► **Actual:**

a  $\longrightarrow$   $(\ell_1)$

p

q

b

r

► **Andersen:**

a  $\longrightarrow$   $(\ell_1)$

p

q

b

r

## Teal

```
var a := new $\ell_1$ () ; //  $\Leftarrow$ 
var b := new $\ell_2$ () ;
a := new $\ell_3$ () ;
var p := new $\ell_4$ () ;
p.n := a ;
var q := new $\ell_6$ () ;
q.n := b ;
p := q ;
var r := q.n ;
```

# Example

$\Rightarrow$   $x := \text{new}_{l_z}$      $x \rightarrow l_z$   
 $x := y$      $x \leftarrow y$   
 $x := y.\square$      $x \leftarrow y.\square$   
 $x.\square := y$      $x.\square \leftarrow y$

► **Actual:**

$a \longrightarrow \textcircled{l_1}$

p

q

$b \longrightarrow \textcircled{l_2}$

r

► **Andersen:**

$a \longrightarrow \textcircled{l_1}$

p

q

$b \longrightarrow \textcircled{l_2}$

r

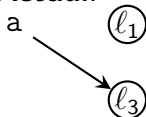
## Teal

```
var a := new $l_1$ ();  
var b := new $l_2$ () //  $\leftarrow$   
a := new $l_3$ ();  
var p := new $l_4$ ();  
p.n := a;  
var q := new $l_6$ ();  
q.n := b;  
p := q;  
var r := q.n;
```

# Example

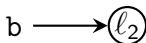
$\Rightarrow$   $x := \text{new}_{l_z}$      $x \rightarrow l_z$   
 $x := y$      $x \leftarrow y$   
 $x := y.\square$      $x \leftarrow y.\square$   
 $x.\square := y$      $x.\square \leftarrow y$

## ► Actual:



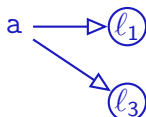
p

q



r

## ► Andersen:



p

q



r

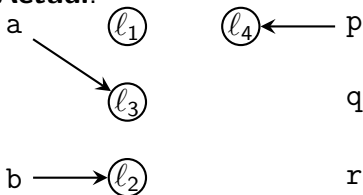
## Teal

```
var a := newl1 ();  
var b := newl2 ();  
a := newl3 ();    //←  
var p := newl4 ();  
p.n := a;  
var q := newl6 ();  
q.n := b;  
p := q;  
var r := q.n;
```

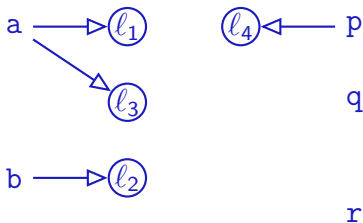
# Example

$\Rightarrow x := \text{new}_{l_z} \quad x \rightarrow l_z$   
 $x := y \quad x \leftarrow y$   
 $x := y.\square \quad x \leftarrow y.\square$   
 $x.\square := y \quad x.\square \leftarrow y$

► **Actual:**



► **Andersen:**



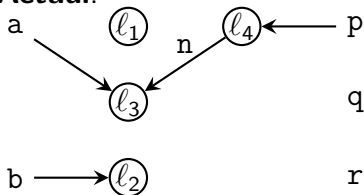
## Teal

```
var a := newl1 ();  
var b := newl2 ();  
a := newl3 ();  
var p := newl4 (); // ←  
p.n := a;  
var q := newl6 ();  
q.n := b;  
p := q;  
var r := q.n;
```

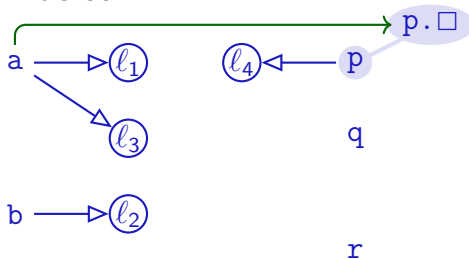
# Example

```
x := newlz   x → lz
x := y         x ← y
x := y.□      x ← y.□
⇒ x.□ := y    x.□ ← y
```

► **Actual:**



► **Andersen:**



## Teal

```
var a := newl1 ();
var b := newl2 ();
a := newl3 ();
var p := newl4 ();
p.n := a;           // ←
var q := newl6 ();
q.n := b;
p := q;
var r := q.n;
```

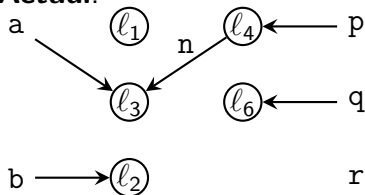
# Example

$\Rightarrow x := \text{new}_{l_z} \quad x \rightarrow l_z$   
 $x := y \quad x \leftarrow y$   
 $x := y.\square \quad x \leftarrow y.\square$   
 $x.\square := y \quad x.\square \leftarrow y$

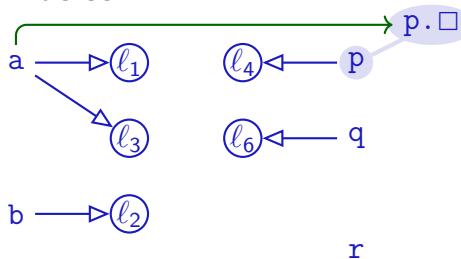
## Teal

```
var a := newl1 ();  
var b := newl2 ();  
a := newl3 ();  
var p := newl4 ();  
p.n := a;  
var q := newl6 (); // ←  
q.n := b;  
p := q;  
var r := q.n;
```

### Actual:



### Andersen:



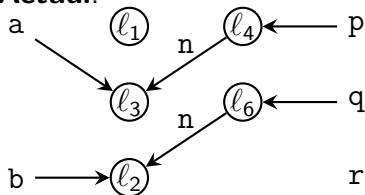
# Example

<code>x := new<sub>l<sub>z</sub></sub></code>	<code>x → l<sub>z</sub></code>
<code>x := y</code>	<code>x ← y</code>
<code>x := y.□</code>	<code>x ← y.□</code>
<code>⇒ x.□ := y</code>	<code>x.□ ← y</code>

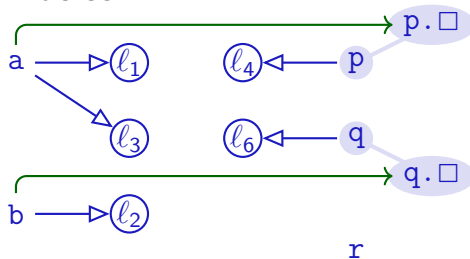
## Teal

```
var a := newl1 ();  
var b := newl2 ();  
a := newl3 ();  
var p := newl4 ();  
p.n := a;  
var q := newl6 ();  
q.n := b;           // ←  
p := q;  
var r := q.n;
```

### ► Actual:



### ► Andersen:



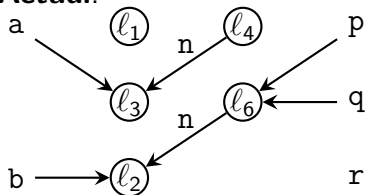
# Example

<code>x := new<sub>l<sub>z</sub></sub></code>	<code>x → l<sub>z</sub></code>
<code>⇒ x := y</code>	<code>x ← y</code>
<code>x := y.□</code>	<code>x ← y.□</code>
<code>x.□ := y</code>	<code>x.□ ← y</code>

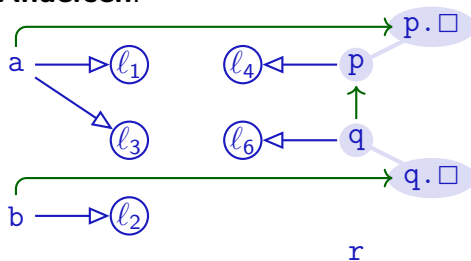
## Teal

```
var a := newl1 ();  
var b := newl2 ();  
a := newl3 ();  
var p := newl4 ();  
p.n := a;  
var q := newl6 ();  
q.n := b;  
p := q; //⇐  
var r := q.n;
```

## Actual:



## Andersen:



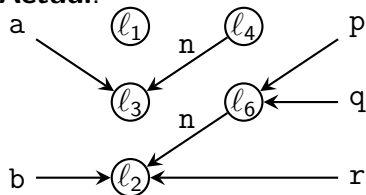
# Example

```
x := newlz    x → lz  
x := y         x ← y  
x := y.□      x ← y.□  
x.□ := y      x.□ ← y
```

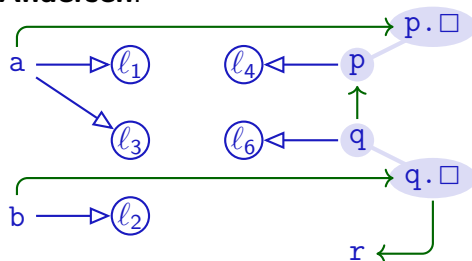
## Teal

```
var a := newl1 ();  
var b := newl2 ();  
a := newl3 ();  
var p := newl4 ();  
p.n := a;  
var q := newl6 ();  
q.n := b;  
p := q;  
var r := q.n; // ←
```

## Actual:



## Andersen:



# Example

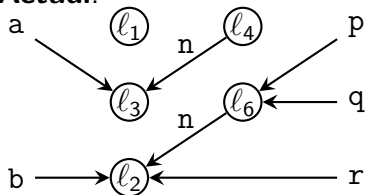
$x := \text{new}_{l_z}$      $x \rightarrow l_z$   
 $x := y$          $x \leftarrow y$   
 $x := y.\square$       $x \leftarrow y.\square$   
 $x.\square := y$       $x.\square \leftarrow y$

$l \leftarrow y$  and  $x \leftarrow y$      $\implies l \leftarrow x$   
 $l \leftarrow y$  and  $x \leftarrow y.\square$   $\implies x \leftarrow l$   
 $l \leftarrow x$  and  $x.\square \leftarrow y$   $\implies l \leftarrow y$

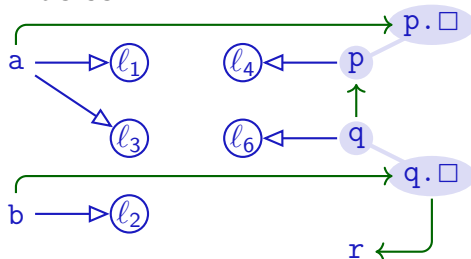
## Teal

```
var a := new $l_1$ ();  
var b := new $l_2$ ();  
a := new $l_3$ ();  
var p := new $l_4$ ();  
p.n := a;  
var q := new $l_6$ ();  
q.n := b;  
p := q;  
var r := q.n;
```

## Actual:



## Andersen:



Andersen's algorithm must propagate along **inclusion graph**

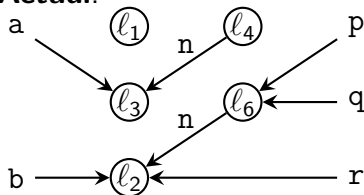
# Example

$l \leftarrow y$  and  $x \leftarrow y \implies l \leftarrow x$   
 $l \leftarrow y$  and  $x \leftarrow y.\square \implies x \leftarrow l$   
 $l \leftarrow x$  and  $x.\square \leftarrow y \implies l \leftarrow y$

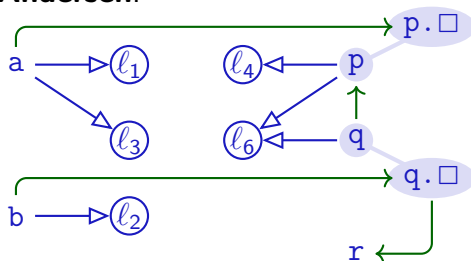
## Teal

```
var a := newl1 ();  
var b := newl2 ();  
a := newl3 ();  
var p := newl4 ();  
p.n := a;  
var q := newl6 ();  
q.n := b;  
p := q;  
var r := q.n;
```

### Actual:



### Andersen:



Andersen's algorithm must propagate along **inclusion graph**

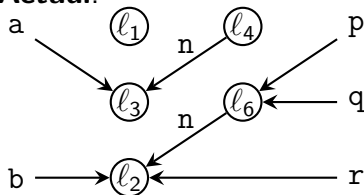
# Example

$l \leftarrow y$  and  $x \leftarrow y \implies l \leftarrow x$   
 $l \leftarrow y$  and  $x \leftarrow y.\square \implies x \leftarrow l$   
 $l \leftarrow x$  and  $x.\square \leftarrow y \implies l \leftarrow y$

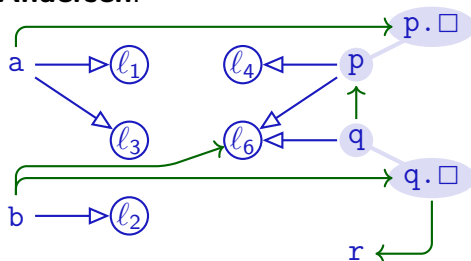
## Teal

```
var a := newl1 ();  
var b := newl2 ();  
a := newl3 ();  
var p := newl4 ();  
p.n := a;  
var q := newl6 ();  
q.n := b;  
p := q;  
var r := q.n;
```

### Actual:



### Andersen:



Andersen's algorithm must propagate along **inclusion graph**

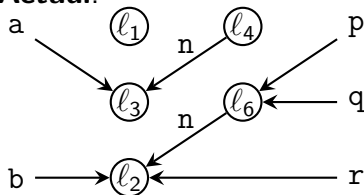
# Example

$l \leftarrow y$  and  $x \leftarrow y \implies l \leftarrow x$   
 $l \leftarrow y$  and  $x \leftarrow y.\square \implies x \leftarrow l$   
 $l \leftarrow x$  and  $x.\square \leftarrow y \implies l \leftarrow y$

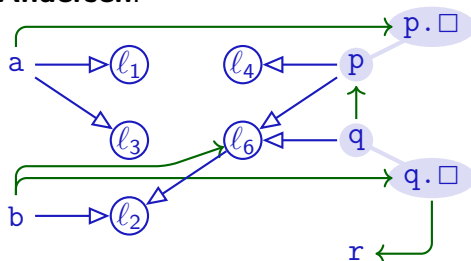
## Teal

```
var a := newl1 ();  
var b := newl2 ();  
a := newl3 ();  
var p := newl4 ();  
p.n := a;  
var q := newl6 ();  
q.n := b;  
p := q;  
var r := q.n;
```

### Actual:



### Andersen:



Andersen's algorithm must propagate along **inclusion graph**

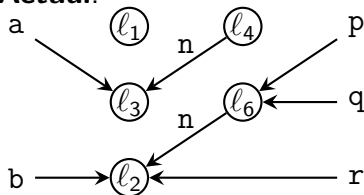
# Example

$l \leftarrow y$  and  $x \leftarrow y \implies l \leftarrow x$   
 $l \leftarrow y$  and  $x \leftarrow y.\square \implies x \leftarrow l$   
 $l \leftarrow x$  and  $x.\square \leftarrow y \implies l \leftarrow y$

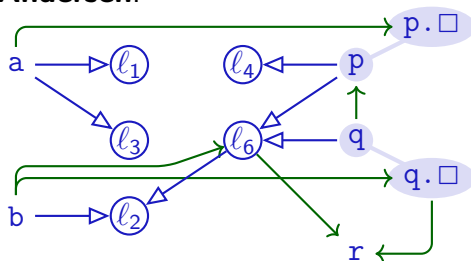
## Teal

```
var a := newl1 ();  
var b := newl2 ();  
a := newl3 ();  
var p := newl4 ();  
p.n := a;  
var q := newl6 ();  
q.n := b;  
p := q;  
var r := q.n;
```

### Actual:



### Andersen:



Andersen's algorithm must propagate along **inclusion graph**

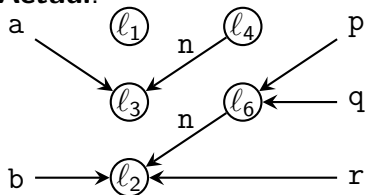
# Example

$l \leftarrow y$  and  $x \leftarrow y \implies l \leftarrow x$   
 $l \leftarrow y$  and  $x \leftarrow y.\square \implies x \leftarrow l$   
 $l \leftarrow x$  and  $x.\square \leftarrow y \implies l \leftarrow y$

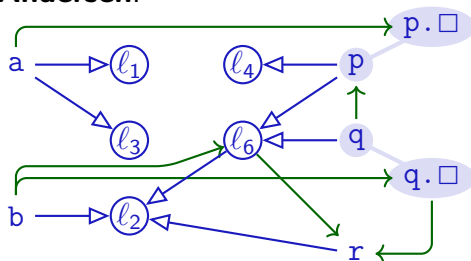
## Teal

```
var a := newl1 ();  
var b := newl2 ();  
a := newl3 ();  
var p := newl4 ();  
p.n := a;  
var q := newl6 ();  
q.n := b;  
p := q;  
var r := q.n;
```

### Actual:



### Andersen:



Andersen's algorithm must propagate along **inclusion graph**

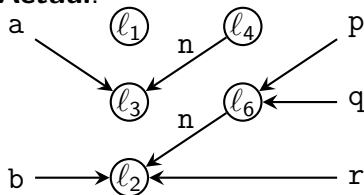
# Example

$l \leftarrow y$  and  $x \leftarrow y \implies l \leftarrow x$   
 $l \leftarrow y$  and  $x \leftarrow y.\square \implies x \leftarrow l$   
 $l \leftarrow x$  and  $x.\square \leftarrow y \implies l \leftarrow y$

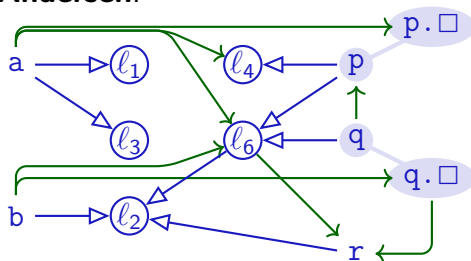
## Teal

```
var a := newl1 ();  
var b := newl2 ();  
a := newl3 ();  
var p := newl4 ();  
p.n := a;  
var q := newl6 ();  
q.n := b;  
p := q;  
var r := q.n;
```

### ► Actual:



### ► Andersen:



Andersen's algorithm must propagate along **inclusion graph**

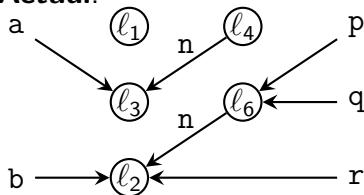
# Example

$l \leftarrow y$  and  $x \leftarrow y \implies l \leftarrow x$   
 $l \leftarrow y$  and  $x \leftarrow y.\square \implies x \leftarrow l$   
 $l \leftarrow x$  and  $x.\square \leftarrow y \implies l \leftarrow y$

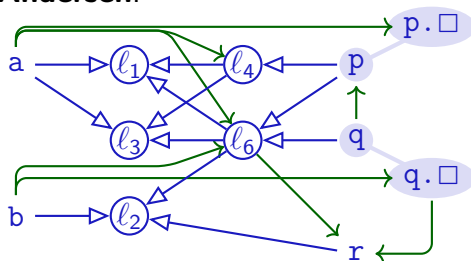
## Teal

```
var a := newl1 ();  
var b := newl2 ();  
a := newl3 ();  
var p := newl4 ();  
p.n := a;  
var q := newl6 ();  
q.n := b;  
p := q;  
var r := q.n;
```

### Actual:



### Andersen:



Andersen's algorithm must propagate along **inclusion graph**

# Implementation

- ▶ Graph structure
- ▶ Three types of edges:  $\leftarrow$ ,  $\leftarrow$ , and indirect  $\leftarrow$  (with a  $\square$ )
- ▶ Connection between  $x$  and  $x.\square$
- ▶ Worklist:
  - ▶ Track all *new* edges (at start: *all* extracted edges)
  - ▶ Process one edge at a time:
    - ▶ Remove from worklist, add to “completed edges”
    - ▶ Check our three rules: does current edge + completed edges allow producing new edge that is neither in worklist nor completed?
    - ▶ If so: add all such edges to worklist (may be several!)

$$l \leftarrow y \text{ and } x \leftarrow y \implies l \leftarrow x$$

$$v \leftarrow y \text{ and } x \leftarrow y.\square \implies x \leftarrow v$$

$$v \leftarrow x \text{ and } x.\square \leftarrow y \implies v \leftarrow y$$

# Complexity

- ▶ Complexity of graph closure:  $O(n^3)$
- ▶ Traditional assumption about Andersen's analysis
- ▶ Close to  $O(n^2)$  if:
  - 1 Few statements dereference each variable
  - 2 Control flow graphs not too complex

*Both conditions are common in practical programs*

Manu Sridharan, Stephen J. Fink, "The Complexity of Andersen's Analysis in Practice", in SAS 2009

# Summary

- ▶ Andersen's analysis:
  - ▶ Subset-based
  - ▶ Builds inclusion graph for propagating memory locations along subset constraints
  - ▶  $O(n^3)$  worst-case behaviour
  - ▶ Closer to  $O(n^2)$  in practice
  - ▶ More precise than Steensgaard's analysis
  - ▶ Less scalable than Steensgaard's analysis

