

# Contents of Lecture 3

- Translation to SSA Form
- Translation from SSA Form

# Translation to SSA Form

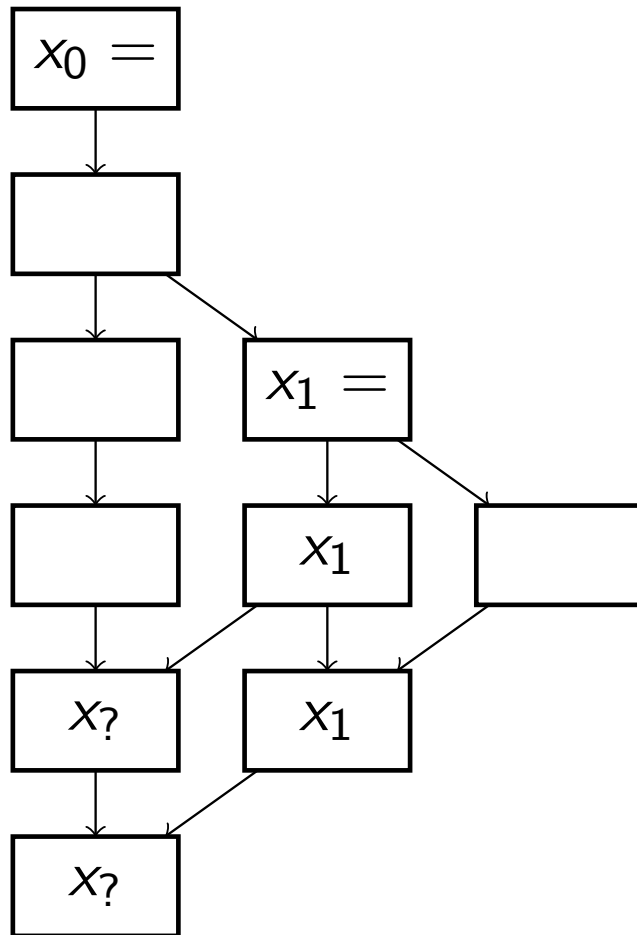
A function is translated to SSA Form in the following steps

- 1 Compute the dominator tree  $DT$  of the function.
- 2 Compute the dominance frontier of each vertex in the CFG.
- 3 Insert  $\phi$ -functions.
- 4 Rename variables while traversing the dominator tree.

# A Trick

- We want to insert a  $\phi$ -function where two paths from assignments meet.
- This formulation of the problem was difficult to use to find an efficient algorithm.
- The following is a trick which makes it easier to answer the question of where to insert  $\phi$ -functions:
- **Trick:** Every variable is given an assignment in the start vertex.
- That is, a variable  $x$  is given an assignment  $x_0$  in the start vertex.
- No assembler code is produced for the assignment though.

# Why would $x_0$ help???

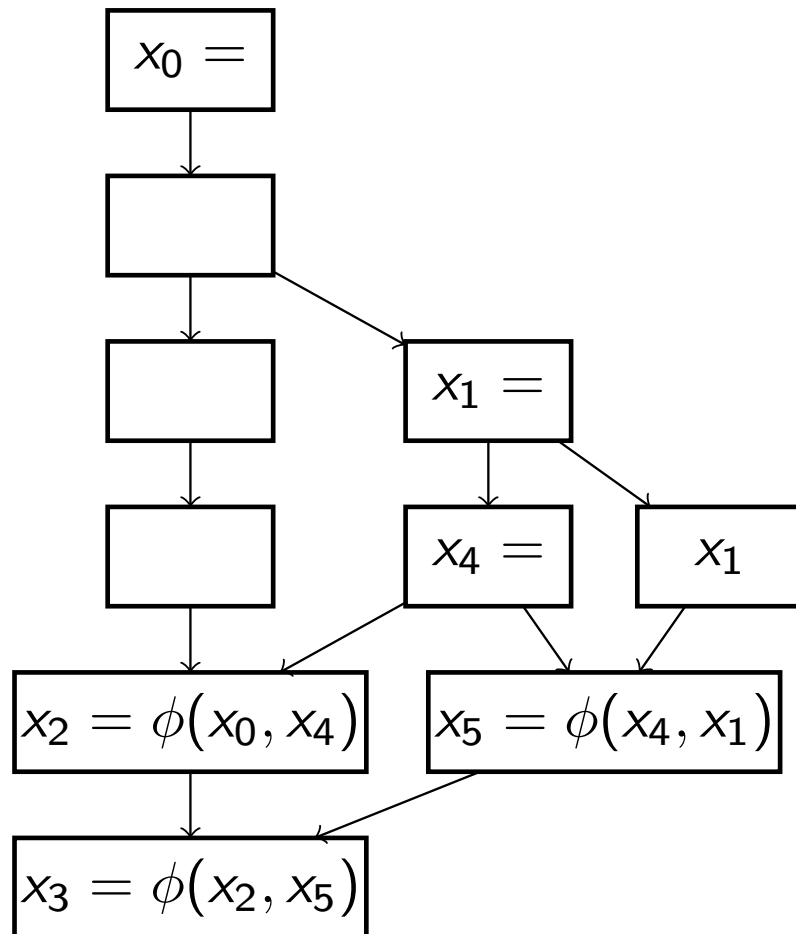


- With the assignment to  $x_0$  we can see that two paths from assignments join in the vertices with  $x_?$ .
- Therefore each of them needs a  $\phi$ -function.
- Another way to see this is that these vertices are just outside what is dominated by the vertex with  $x_1 =$ .

# Dominance frontier

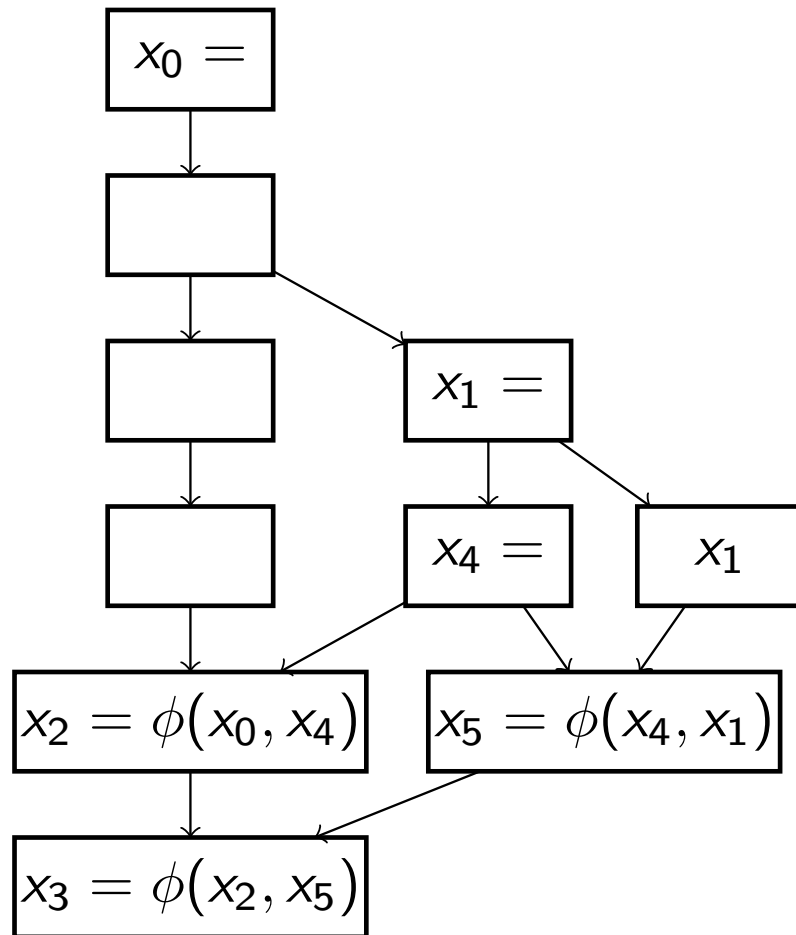
- We need to insert a  $\phi$ -function in every vertex which is just outside what is dominated by a vertex with an assignment.
- "Just outside" is called the **dominance frontier** of a vertex  $u$ .
- It is written  $DF(u)$ .
- $DF(u) = \{ v \mid \exists p \in \text{pred}(v), u \succeq p, u \not\gg v \}$ .
- In words: if  $u$  dominates a predecessor of  $v$  but does not dominate  $v$  strictly, then  $v$  is in the dominance frontier of  $u$ .
- After the dominator tree is found, the dominance frontier for each vertex is computed.
- Each local variable and compiler-generated temporary is inspected: for each vertex  $u$  with an assignment to the variable, a  $\phi$ -function is inserted in  $DF(u)$ .
- N.B. a  $\phi$ -function is an assignment — which also needs  $\phi$ -functions in the dominance frontier of its vertex. More about that below.

# Multiple assignments



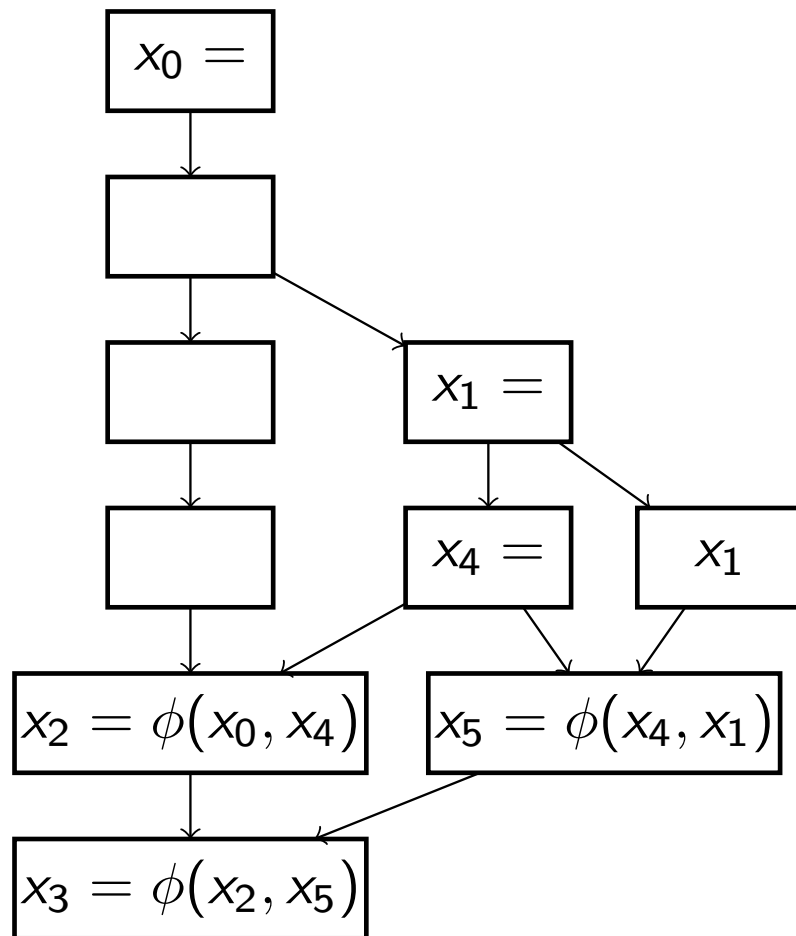
- Consider the assignment to  $x_4$ .
- We must rename variables so that after a later assignment the new version is used during the renaming.
- Obviously it is  $x_4$  that should be the  $\phi$ -operand and not  $x_1$ .
- This is achieved with a stack of variables.
- The current version of a variable is at the top of the stack.

# Using the Dominator Tree and a Stack of Variable Versions



- After  $\phi$ -functions have been inserted (more details below) the dominator tree is traversed during variable renaming.
- Each variable has its own stack of variable versions.
- At a use of a variable in a statement, the variable is replaced in the statement by the top of variable's stack.
- At an assignment a new variable version is pushed on the variable's stack, and the variable is replaced in the statement by the new version.

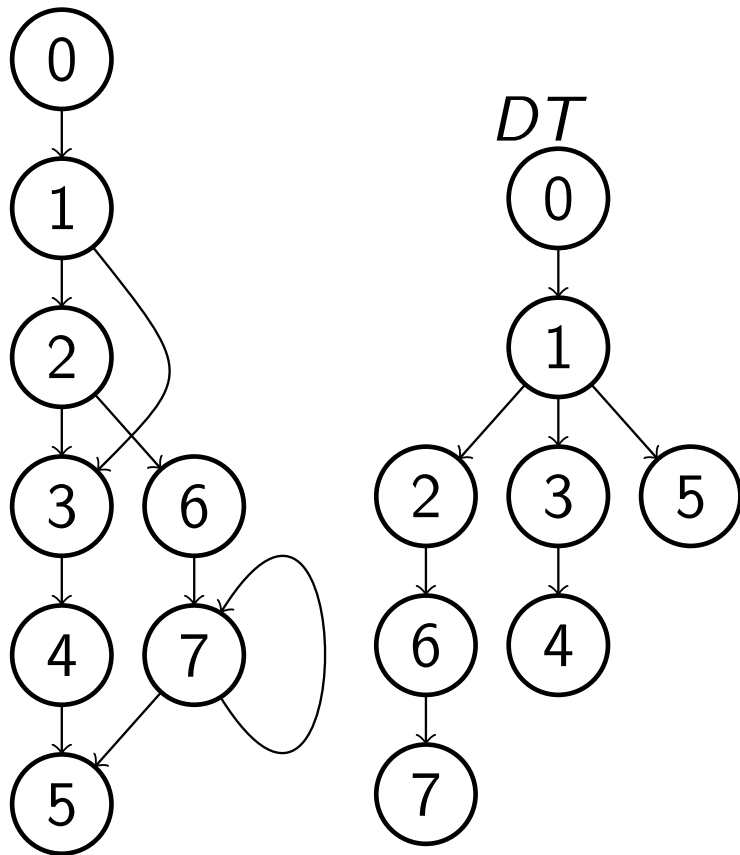
# Illustration of what happens near the assignment to $x_1$



- The new version  $x_1$  is pushed on the stack of  $x$ .
- The vertex with  $x_4$  is a child in the  $DT$  and is inspected next.
- The new version  $x_4$  is pushed on the stack of  $x$ .
- The  $\phi$ -function in the successor vertex gets one of its operands replaced to  $x_4$  from the current top of the stack.
- The vertex with  $x_4$  has no child in the  $DT$  and  $x_4$  is popped from the stack.
- $x_1$  is then at the top of the stack and is used next.

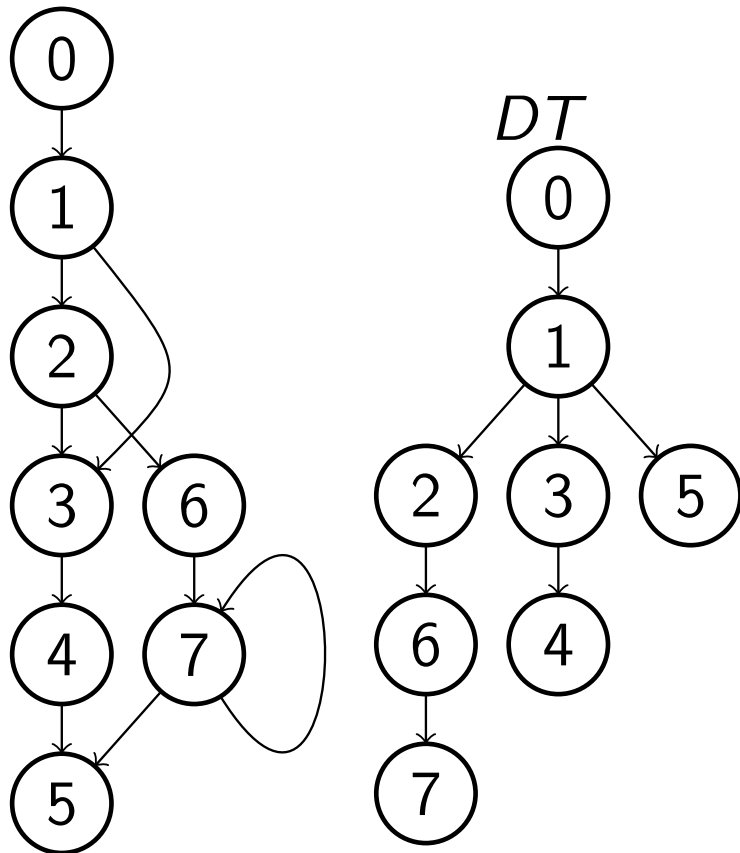


# Strict Dominance in the Definition of Dominance Frontier

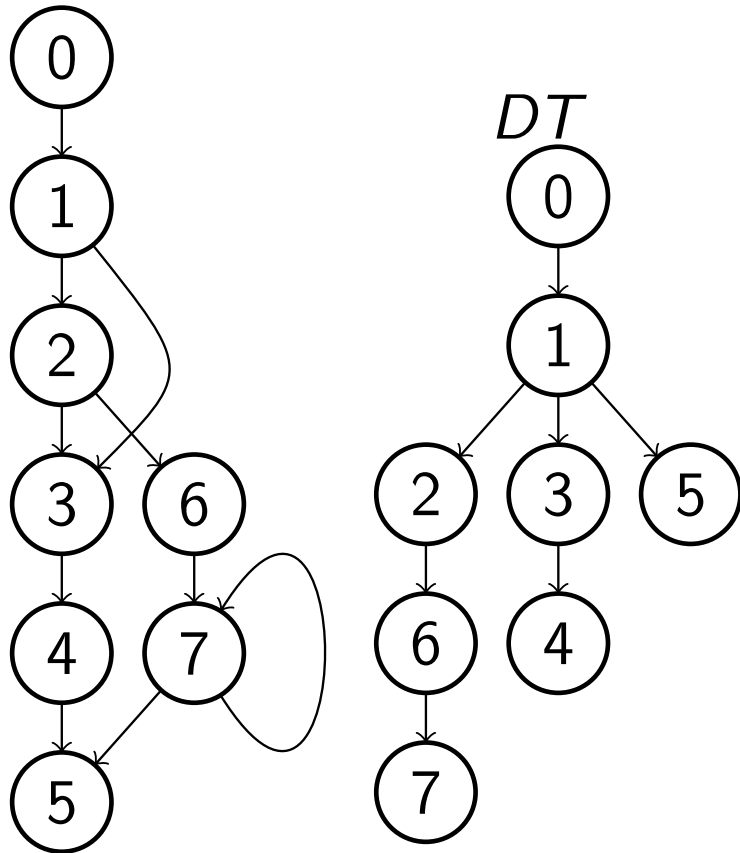


- $DF(u) = \{v | \exists p \in pred(v), u \geq p, u \not\gg v\}$ .
- Consider 7 and suppose it contains  $++i$ .
- It then needs  $i = \phi(i, i)$ .
- $DF(7) = \{5, 7\}$ .
- When 7 is added to its own DF it is both  $u$ ,  $p$ , and  $v$  in the definition.
- This situation is the reason for using not strict dominance in the definition.

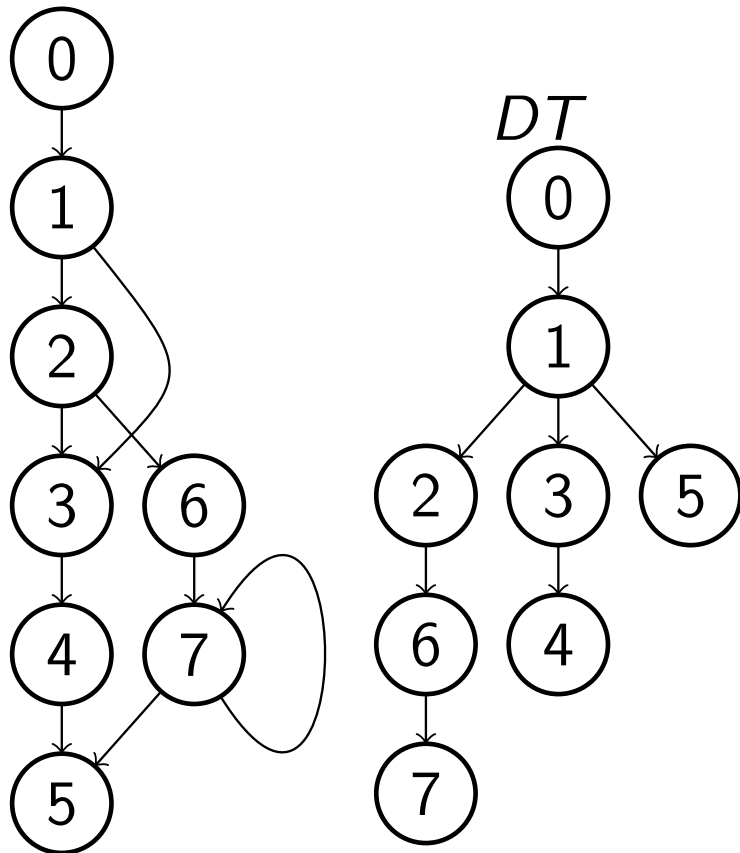
# Computing the Dominance Frontiers of a CFG



- $DF(u) = \{v \mid \exists p \in \text{pred}(v), u \geq p, u \not\geq v\}$ .
- Below  $\text{children}(u)$  is the set of children of  $u$  in the dominator tree.
- The dominance frontier is computed bottom up in the dominator tree using:
- $$DF(u) = DF_{\text{local}}(u) \cup \bigcup_{c \in \text{children}(u)} DF_{\text{up}}(c)$$
- $DF_{\text{local}}(u) \stackrel{\text{def}}{=} \{v \in \text{succ}(u) \mid u \not\geq v\}$ .
- $DF_{\text{up}}(c) \stackrel{\text{def}}{=} \{v \in DF(c) \mid \text{idom}(c) \not\geq v\}$ .
- These formulas can be simplified further as we will see, but first we will build intuition into why they are correct.

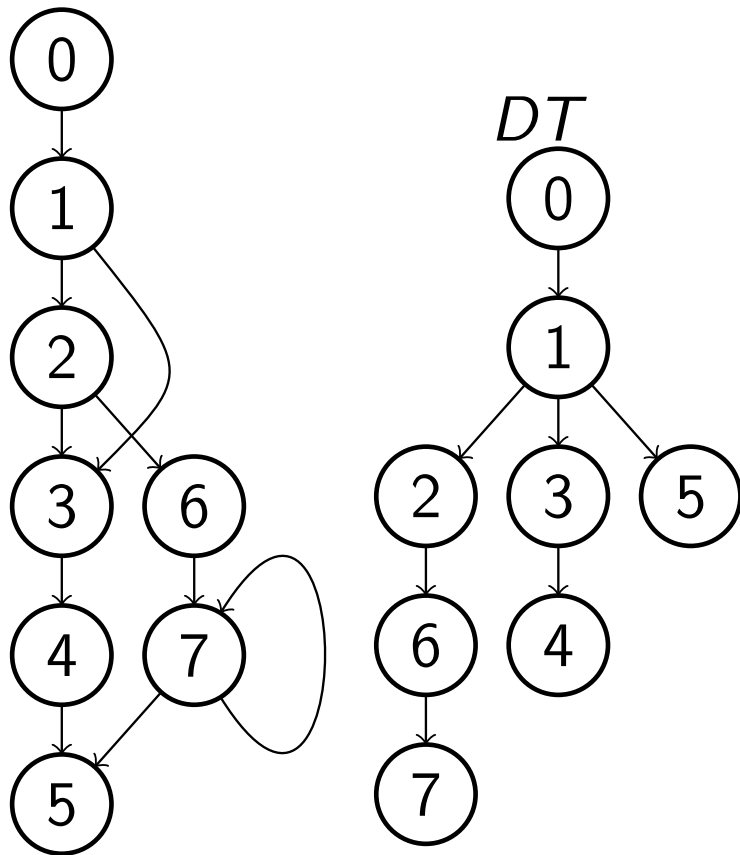


- $DF_{local}(u) \stackrel{\text{def}}{=} \{v \in succ(u) \mid u \not\gg v\}$ .
- The set  $DF_{local}(u)$  is the contribution to  $DF(u)$  which can be determined by only looking at the successors of  $u$  in the CFG.
- Since  $u$  does not dominate  $v$  strictly, but clearly it dominates a predecessor of  $v$  (namely itself),  $v \in DF(u)$ .
- For example,  $3 \in DF(2)$  and  $7 \in DF(7)$
- But e.g.  $3 \notin DF(1)$  since  $1 \gg 3$ .



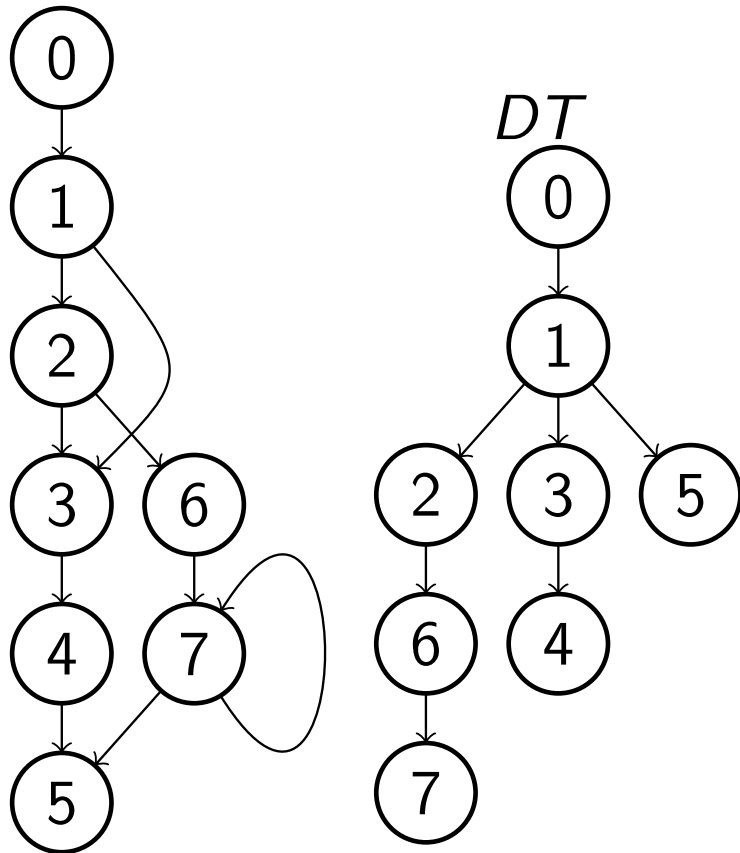
- $DF_{up}(c) \stackrel{\text{def}}{=}} \{v \in DF(c) \mid idom(c) \not\gg v\}$ .
- The set  $DF_{up}(c)$  is the contribution from a vertex  $c$  to the  $DF$  of  $idom(c)$ .
- To see that  $DF_{up}(c) \subseteq DF(idom(c))$ , consider any vertex  $v \in DF(c)$ .
- Assume  $v \in DF(c)$ . There must exist a  $p \in pred(v)$  such that  $c \gg p$ .
- Since dominance is transitive and obviously  $idom(c) \gg c$  we must have  $idom(c) \gg p$ .
- Thus the vertices in  $DF(c)$  which are not strictly dominated by  $idom(c)$  should be added to  $DF(idom(c))$  and this is what  $DF_{up}(c)$  achieves.

# More about dominance frontiers



- In the book is also shown that every vertex in  $DF(v)$  is accounted for in either  $DF_{local}(v)$  or  $DF_{up}(c)$  where  $idom(c) = v$ .
- One can also show that instead of:
- $DF_{local}(u) \stackrel{\text{def}}{=} \{v \in succ(u) \mid u \not\rightsquigarrow v\}$
- we can use:
- $DF_{local}(u) \stackrel{\text{def}}{=} \{v \in succ(u) \mid u \neq idom(v)\}$
- and:
- $DF_{up}(c) \stackrel{\text{def}}{=} \{v \in DF(c) \mid idom(c) \neq idom(v)\}$ .

# Computing the Dominance Frontiers of a CFG



procedure  $df(G, DT)$

for each  $u$  in a postorder traversal of  $DT$  do

$DF(u) \leftarrow \emptyset$

for each  $v \in succ(u)$  do

if ( $idom(v) \neq u$ )

add  $v$  to  $DF(u)$

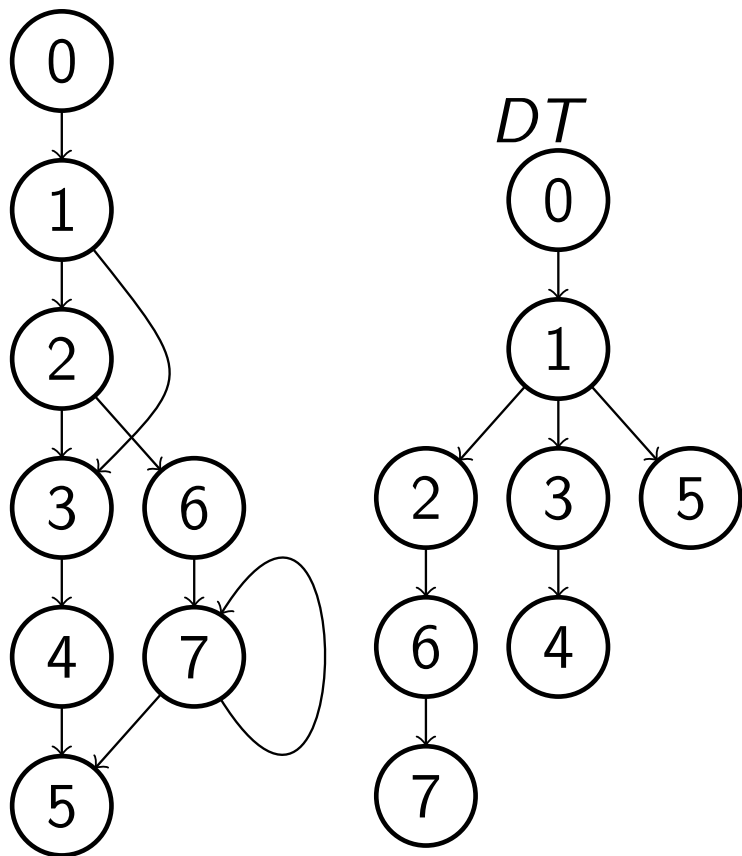
for each  $w \in children(u)$  do

for each  $v \in DF(w)$  do

if ( $idom(v) \neq u$ )

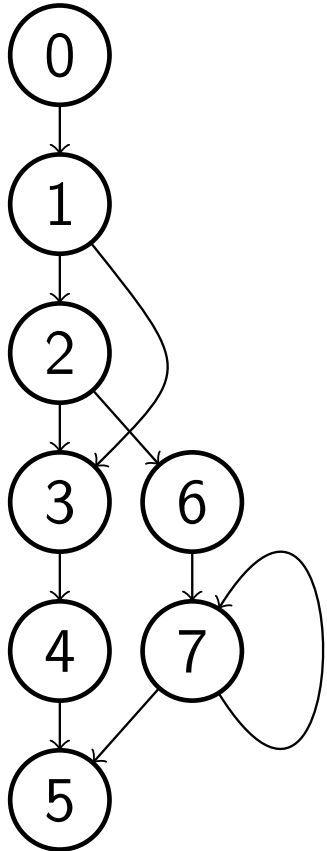
add  $v$  to  $DF(u)$

# Computing the Dominance Frontiers of a CFG



- By postorder traversal is meant that when we visit vertex  $u$ , we first compute the dominance frontier of each child  $c$  of  $u$  in  $DT$  before we compute  $DF(u)$ .
- You will implement this function in Lab 2.
- Recursively walk through the dominator tree.
- The first computed set will be  $DF_{local}(7) = \{5, 7\}$ .
- $DF_{up}(c)$  is never explicitly stored but computed by inspecting  $DF(c)$
- The first complete computed dominance frontier will be  $DF(7) = \{5, 7\}$ .
- Then the  $DF(6)$ ,  $DF(2)$ ,  $DF(4)$  etc...

# Inserting $\phi$ -functions



- $\phi$ -functions are inserted for one variable at a time.
- A counter **iteration** is incremented when the next variable is processed — i.e. gets its  $\phi$ -functions inserted into the CFG.
- Each vertex has two attributes for the  $\phi$ -function insertion which keeps track of for which iteration it was processed:
  - **has\_already** – used to determine whether a  $\phi$ -function for a certain variable has already been inserted in that vertex.
  - **work** – used to determine whether that vertex has been put in a worklist called **W**.
- These variables are all set to zero initially.



# Insert $\phi$ -functions

**procedure** *insert- $\phi$*

$W \leftarrow \emptyset$

**for** each variable  $V$  **do**

$iteration \leftarrow iteration + 1$

**for** each  $u \in vertex\_with\_assignment(V)$  **do**

$work[u] \leftarrow iteration$

add  $u$  to  $W$

**while** ( $W \neq \emptyset$ ) **do**

take  $u$  from  $W$

**for** each  $v \in DF(u)$  **do**

**if** ( $has\_already[v] < iteration$ )

place  $V \leftarrow \phi(V, \dots, V)$  at  $v$

$has\_already[v] \leftarrow iteration$

**if** ( $work[v] < iteration$ )

$work[v] \leftarrow iteration$

add  $v$  to  $W$

## Remarks on previous slide

- The use of an explicit counter and the attributes **work** and **has\_already** is how the algorithm was originally described by researchers from IBM.
- This is more efficient than using lookup-functions to determine whether a vertex has a certain  $\phi$ -function or a vertex is in the worklist.
- For optimizing compilers research the speed of the compiler at normal optimization levels, e.g. -O2 is extremely important.
- However, some optimizations which analyze the whole program is sometimes allowed to take hours.

# Rename

- Rename performs a traversal of the dominator tree.
- In a vertex  $u$  the sequence of three-address statements is examined one statement at a time:
  - First the source operands (right hand side, or RHS) are renamed by replacing the operand with the version of the variable on the top of the variable's rename stack.
  - Then the destination operand (left hand side, or LHS) is renamed by creating a new variable version, pushing it on the rename stack, and replacing the operand with the new version of the variable.
- Then the  $\phi$ -functions of each successor vertex  $v$  in the CFG is inspected and the operand corresponding to the edge  $(u, v)$  is renamed.
- Then each child  $c$  in the DT is processed.
- Finally every new version created and pushed on a rename stack in  $u$  is popped from its rename stack.

# Rename Algorithm

```
procedure rename(u)  
  for each statement t in u do  
    for each variable  $V \in RHS(t)$   
      replace use of  $V$  by use of  $V_i$  where  $i = top(S(V))$   
    for each variable  $V \in LHS(t)$  do  
       $i \leftarrow C(V)$   
      replace  $V$  by  $V_i$   
      push  $i$  onto  $S(V)$   
       $C(V) \leftarrow C(V) + 1$   
  for each  $v \in succ(u)$  do  
     $j \leftarrow which\_pred(u, v)$   
    for each  $\phi$ -function in  $v$  do  
      replace the  $j$ -th operand in  $RHS(\phi)$  by  $V_i$  where  $i = top(S(V))$   
  for each  $v \in children(u)$  do  
    rename( $v$ )  
  pop every variable version pushed in u
```

# Unnecessary $\phi$ -functions

- It's unnecessary to insert a  $\phi$ -function if its value is never used:

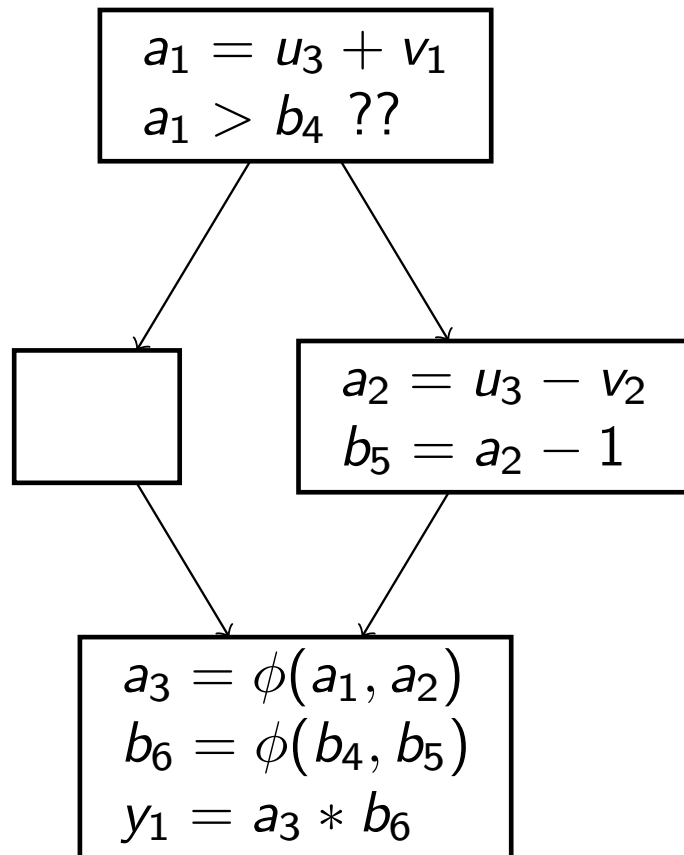
```
if (a > 0) {  
    a = a + 1;  
    f(a);  
}  
return b;
```

- Before the return, there will be a  $\phi$ -function due to the assignment to  $a$ .
- In general the cost to determine whether the value will be used is not worth the effort.
- It's not uncommon that a  $\phi$ -function is inserted in a vertex where the value is overwritten before being used. This special case can be easy to determine and may be worth the effort of avoiding inserting an unnecessary  $\phi$ -function.

# Variable versions are almost only for illustration

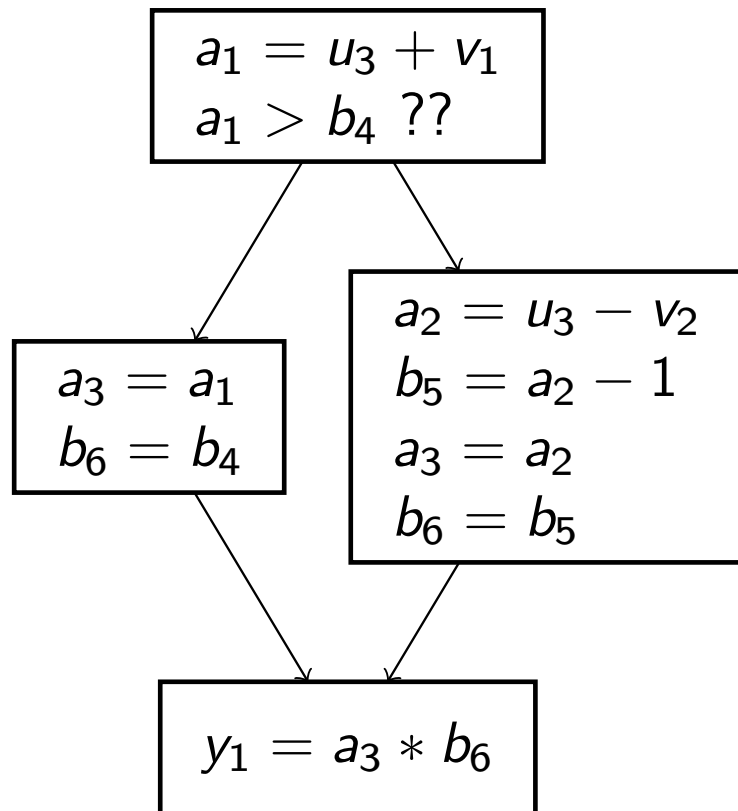
- Most optimization algorithms ignore the variable version number and treat for instance  $a_i$  and  $a_j$  as completely different variables which have no more in common than  $a_i$  and  $b_k$  have.
- Therefore no counter is usually needed: it's sufficient to simply create a new temporary variable.
- However, Partial Redundancy Elimination, SSAPRE, needs to know from which original variable such a temporary comes.

# Translation from SSA Form



- The basic idea when translating from SSA Form is to replace the  $\phi$ -functions with copy statements in the predecessor vertices.

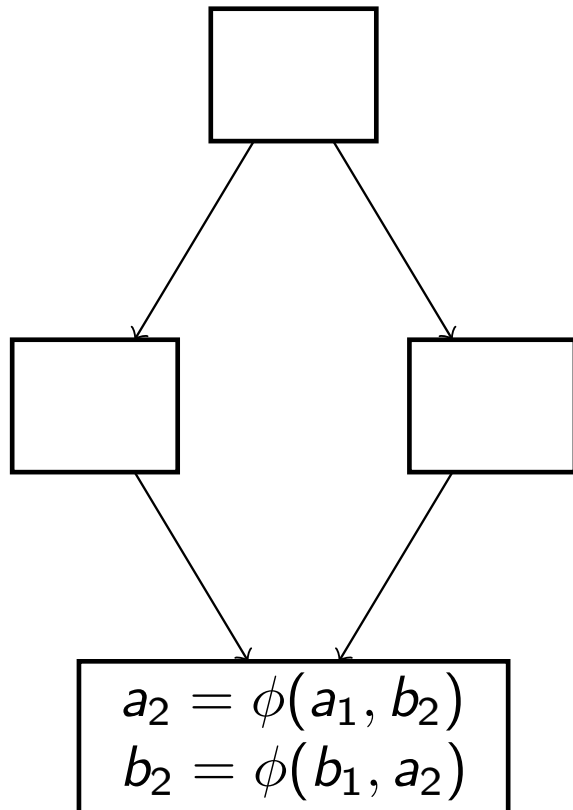
# Translation from SSA Form



- It's thus necessary to have a vertex to insert the copy statements into!
- Without the leftmost vertex, there is an edge from a vertex with multiple successors to a vertex with multiple predecessors and such an edge is called a **critical edge**.
- Critical edges are removed by inserting an extra empty vertex.
- This is done before dominance analysis.

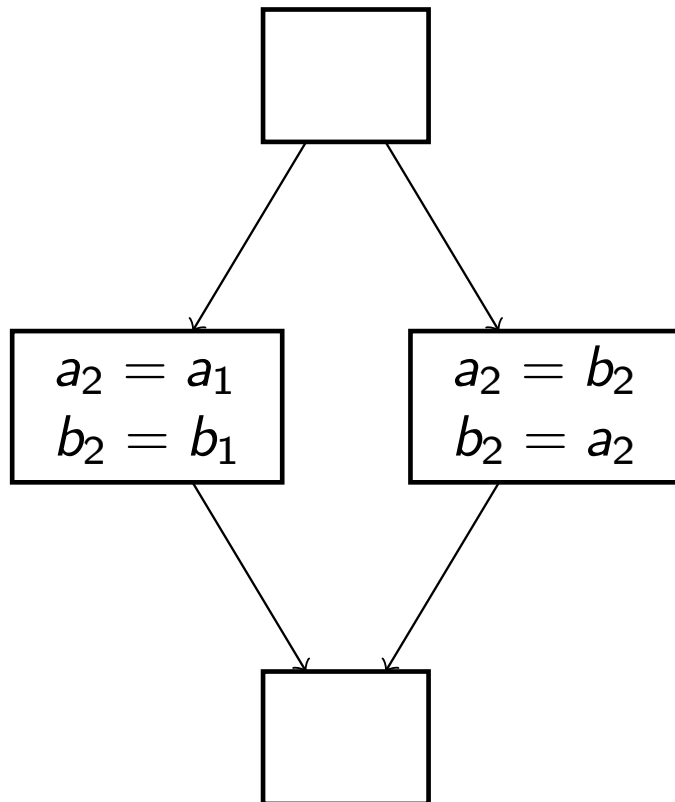


# Translation from SSA Form



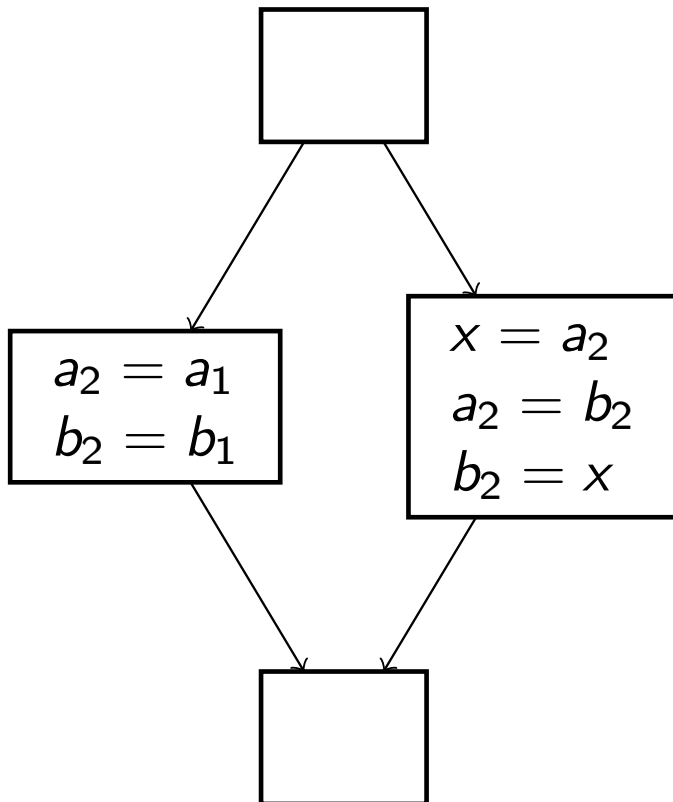
- The  $\phi$ -functions are *parallel* copy statements.
- Conceptually all  $\phi$ -functions are executed concurrently by first reading all operands and then writing all destinations.
- What will go wrong here with a "naive" translation from SSA Form?

# Translation from SSA Form



- What is wrong here?

# Translation from SSA Form



- The value of  $a_2$  must be saved before being overwritten!

# Detect Use of Uninitialized Variables

- If version zero is used and there was no explicit initializer for the variable (i.e. no `int a = 1`) it means we have discovered a buggy program with undefined behavior!

# Copy Propagation

- During Translation to SSA Form, a copy statement  $a = b$  can be optimized as follows:
- The current value of  $b$ , i.e. the version on the top of  $b$ 's rename stack is pushed on  $a$ 's rename stack and the copy statement can then be removed.
- You will do this during Lab 2.
- A copy is called MOV in vcc.
- A NOP statement does nothing.
- Easiest to remove a statement by changing it to a NOP.
- All NOP can then be removed later.