



Logic: A Motivation

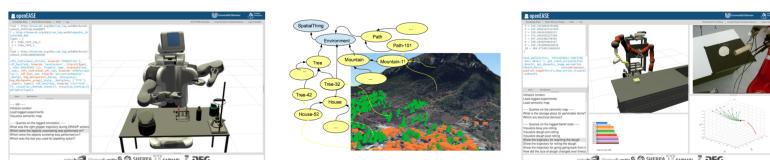
Jacek Malec

Dept. of Computer Science, Lund University, Sweden

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Knowrob: Why is knowledge so important?

- if the robot does not know about the task, the environment, or the robot, then the programmer has to hardcode **everything**



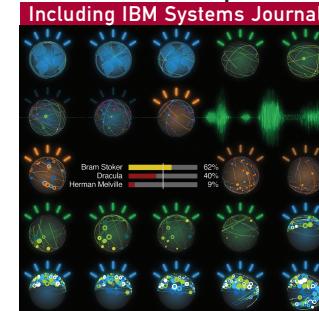
- programming/instructing at an abstract/semantic level
 - put the bolt into the nut and fasten it
 - pour water into the glass
 - ...



IBM Watson example

<https://www.youtube.com/watch?v=Dyw04zksfXw>

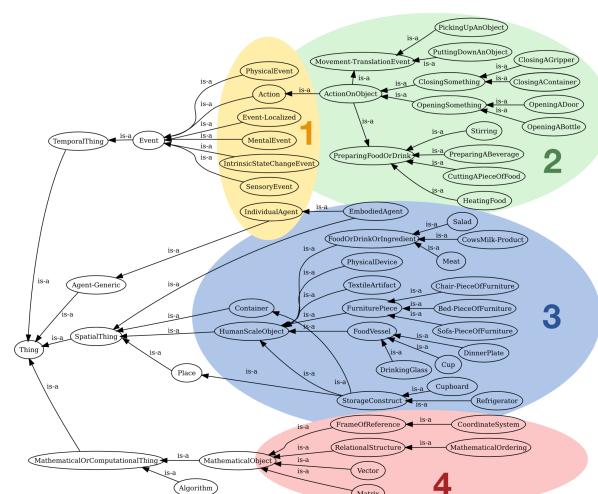
VOLUME 56, NUMBER 3/4, MAY/JUL. 2012
IBM Journal of Research and Development



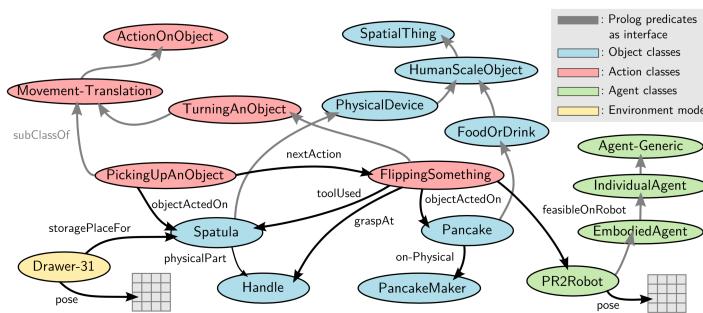
This Is Watson



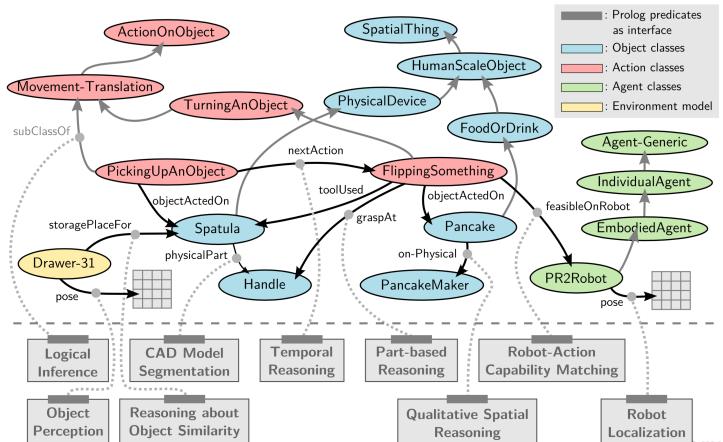
Knowrob: Ontology (knowrob.owl)



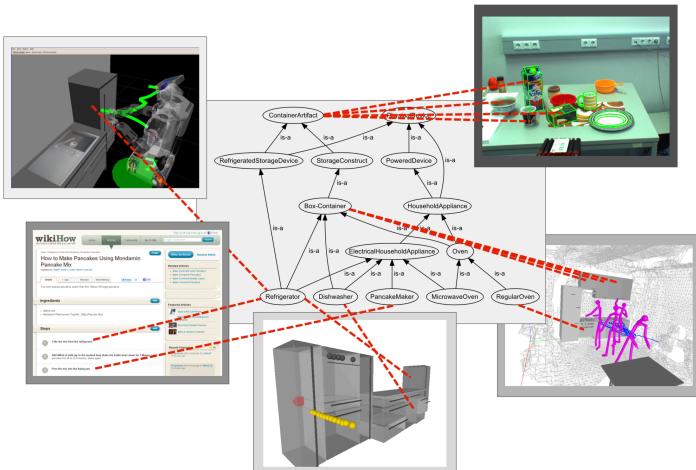
Knowrob: A task ontology



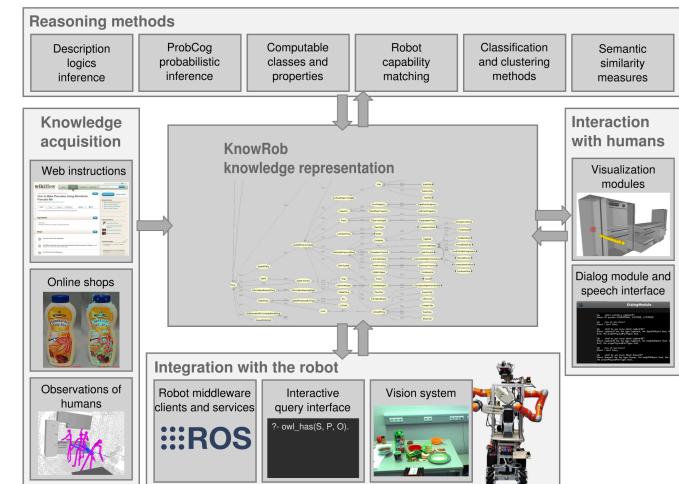
Knowrob: A task ontology



Knowrob: Knowledge types



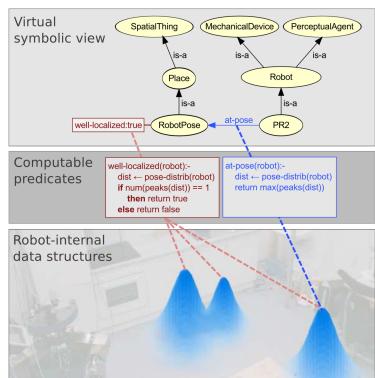
KnowRob Components



Knowrob: Procedural attachments



- Compute symbolic knowledge **on demand** from data structures that already exist on the robot by attaching procedures to semantic classes and properties
- Re-use existing information and make sure abstract knowledge is grounded



Knowrob: Summary

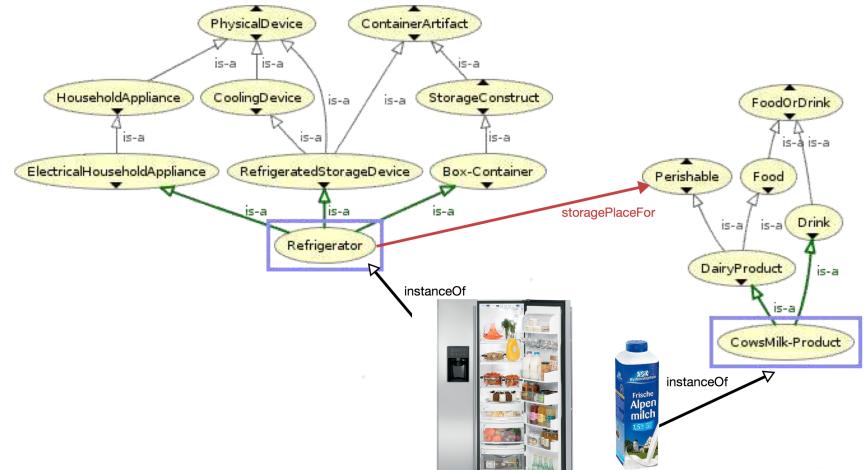


- declarative knowledge: ontologies
- procedural attachment
- logical inference
- multi-modal representation

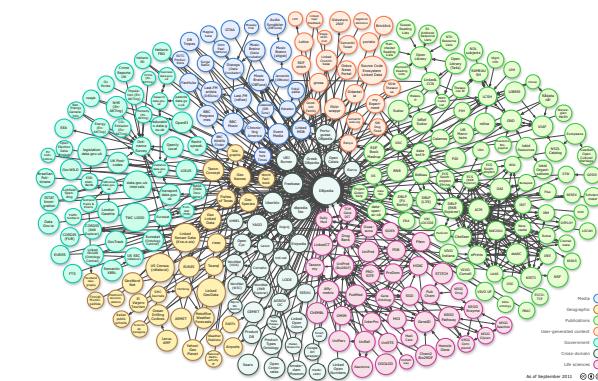
Video (13 mins):

<https://www.youtube.com/watch?v=4usoE981e7I>

Knowrob: Inferring storage location



Semantic Web



Linking Open Data cloud diagram, by Richard Cyganiak and Anja Jentzsch. <http://lod-cloud.net/>