

# Fundamentals and tools

Applied machine learning (EDAN95)  
Lecture 02 — Fundamentals and tools  
2019-11-06  
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Goodfellow chapter 2  
various sources

# Today's agenda

- Concept learning
- (Recap) Linear Algebra (Goodfellow chapter 2),  
example: PCA to construct a classifier for localisation
- Some tips on Python / Jupyter notebooks and Numpy,  
example: image filtering (convolution)

# Today's agenda

- **Concept learning**
- (Recap) Linear Algebra (Goodfellow chapter 2)
- Some tips on Python / Jupyter notebooks and Numpy

# Concept learning

- A central issue in learning is the acquisition of general concepts from examples, e.g., finding the descriptive features for deciding, whether something one observes is a bird or not
- Question: Given some descriptive features for the weather on a certain day, and a list of already rated weather conditions, is this particular day a good day for enjoying some sport activity?
- Assume a set of attributes (features) and possible values for them, which express the constraints for classifying a day as “good” (TRUE):  
*Sky (Sunny, Rainy, Cloudy), AirTemp (Warm, Cold), Humidity (Normal, High), Wind (Strong, Weak), Water (Warm, Cool), Forecast (Same, Change)*
- Represent hypotheses for the concept by a set of values for the attributes, where
  - ? - any value is acceptable
  - $\emptyset$  - no value is acceptable
  - <value> - a specific value is acceptable
- Find the most specific hypothesis that matches the data (examples) in a training set

# Enjoy sports - when?

Example	Sky	AirTemp	Humidity	Wind	Water	Forecast	EnjoySport?
1	Sunny	Warm	Normal	Strong	Warm	Same	Yes
2	Sunny	Warm	High	Strong	Warm	Same	Yes
3	Rainy	Cold	High	Strong	Warm	Change	No
4	Sunny	Warm	High	Strong	Cool	Change	Yes

- Most general hypothesis: EnjoySport = yes on every day is  $h = \langle ?, ?, ?, ?, ?, ? \rangle$
- Most specific hypothesis: EnjoySport = yes on no day is  $h = \langle \emptyset, \emptyset, \emptyset, \emptyset, \emptyset, \emptyset \rangle$
- A fundamental assumption (The Inductive Learning Hypothesis):  
Any hypothesis approximating the target function well over a sufficiently large training set will also approximate the target function well for unseen data
- So - let's find this hypothesis by search...

# Search space for EnjoySport

- # of hypotheses  $h$  for the task:  $3*2*2*2*2*2 = 96$  (# of values per attribute)
- or actually, including ? and  $\emptyset$ :  $5*4*4*4*4*4 = 5120$  *syntactically distinct*  $h$
- but, given that any  $\emptyset$  makes all other attributes obsolete (render the outcome as “no”, we have  $4*3*3*3*3*3 + 1 = 973$  *semantically distinct* hypotheses  $h$
- Hence, the search needs to be organised somehow (we cannot test all  $h$ , if the problem grows more complex...)

# Find-S

- Start with the most specific hypothesis

$h \leftarrow \langle \emptyset, \emptyset, \emptyset, \emptyset, \emptyset, \emptyset \rangle$  (no day is a good day for sports)

- observe first example (it is a positive one)

$h \leftarrow \langle \text{Sunny}, \text{Warm}, \text{Normal}, \text{Strong}, \text{Warm}, \text{Same} \rangle$

(a day with exactly these values in its attributes is a good day for sports, all others are not)

- observe second example (it is a positive one)

$h \leftarrow \langle \text{Sunny}, \text{Warm}, ?, \text{Strong}, \text{Warm}, \text{Same} \rangle$

(since both “Normal” and “High” for the third attribute produce “yes”, the third attribute can obviously have any value, while the others need to be fixed ...)

- ignore the third example (it is negative)

- observe the fourth example and get

$h \leftarrow \langle \text{Sunny}, \text{Warm}, ?, \text{Strong}, ?, ? \rangle$

# Find-S

- Find-S finds the most specific hypothesis that matches the training data (positive examples) and it is correct regarding the negative examples it excludes.
- But there is no guarantee that the found  $h$  is the **ONLY** one that covers the concept fully.
- Also, maybe it would be better to also look at the most general hypothesis that still fits the training data?



# Version Space and Candidate Elimination

- Candidate Elimination finds ALL hypotheses consistent with the training data, the Version Space of the hypothesis space H.
- The algorithm:  
Initialize G to the set of maximally general hypotheses in H:  $G = \{ \langle ?, ?, ?, ?, ?, ? \rangle \}$   
Initialize S to the set of maximally specific hypotheses in H:  $S = \{ \langle \emptyset, \emptyset, \emptyset, \emptyset, \emptyset, \emptyset \rangle \}$   
For each training example d, do

If d is a positive example

- Remove from G any hypothesis inconsistent with d
- For each hypothesis s in S that is not consistent with d
  - Remove s from S
  - Add to S all minimal generalisations h of s such that
    - h is consistent with d, and some g in G is more general than h
- Remove from S any hypothesis that is more general than another hypothesis in S

If d is a negative example

- Remove from S any hypothesis inconsistent with d
- For each hypothesis g in G that is not consistent with d
  - Remove g from G
  - Add to G all minimal specialisations h of g such that
    - h is consistent with d, and some s in S is more specific than h
- Remove from G any hypothesis that is less general than another hypothesis in G

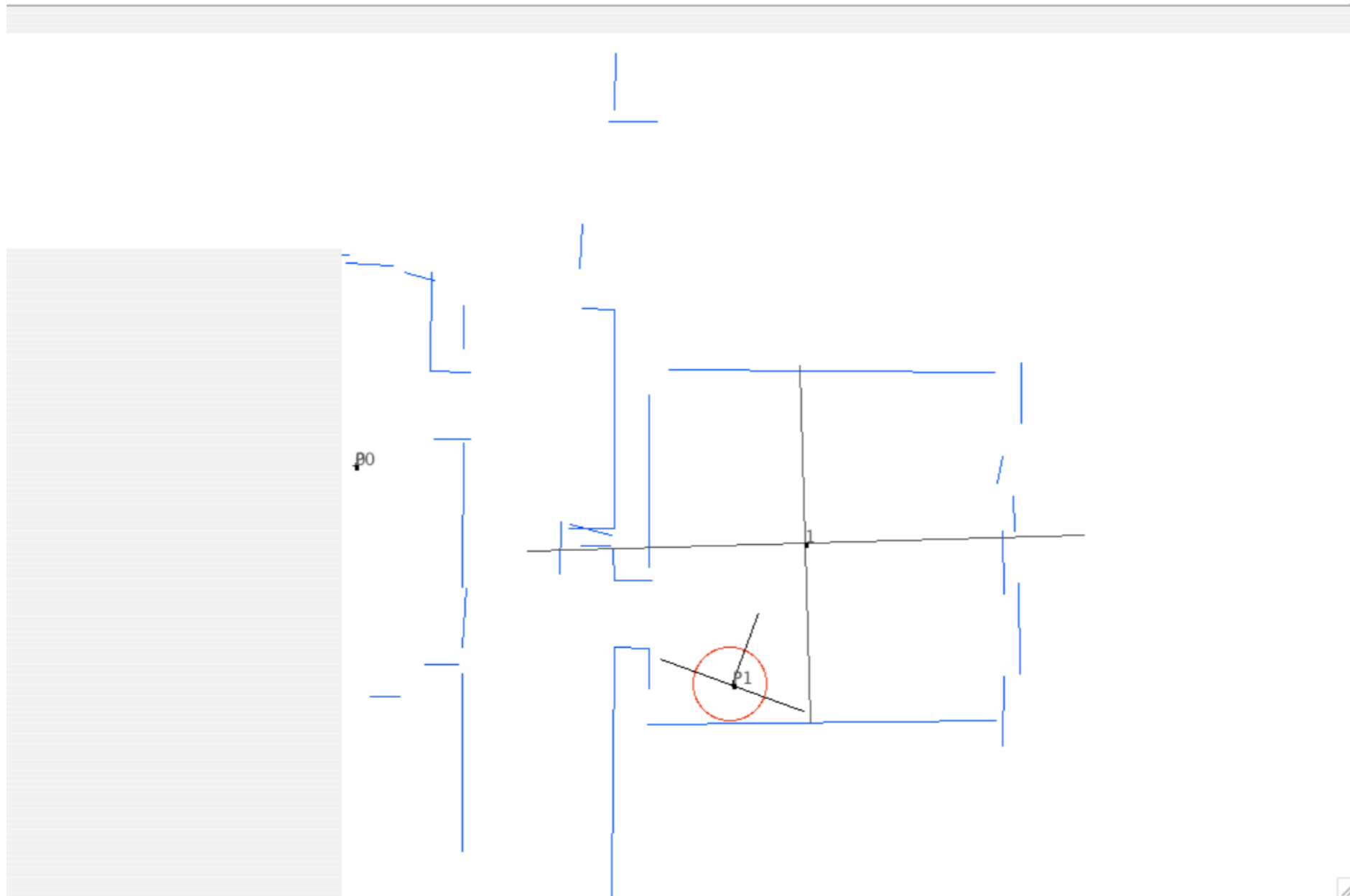
# Problem solved?

- Candidate Elimination converges if the training data are correct and there is actually a correct hypothesis in  $H$  (if it converges after sufficiently many positive AND negative examples to one single hypothesis, this is the optimal and correct one).
- Extremely sensitive to noise - one single “false negative” in the training data can eliminate the correct hypothesis, and it will never come back ...
- Not exactly practical with an image of a bird or not a bird, if attributes are not conceptual but correspond to pixels with a much larger value range than “high” vs “normal”.

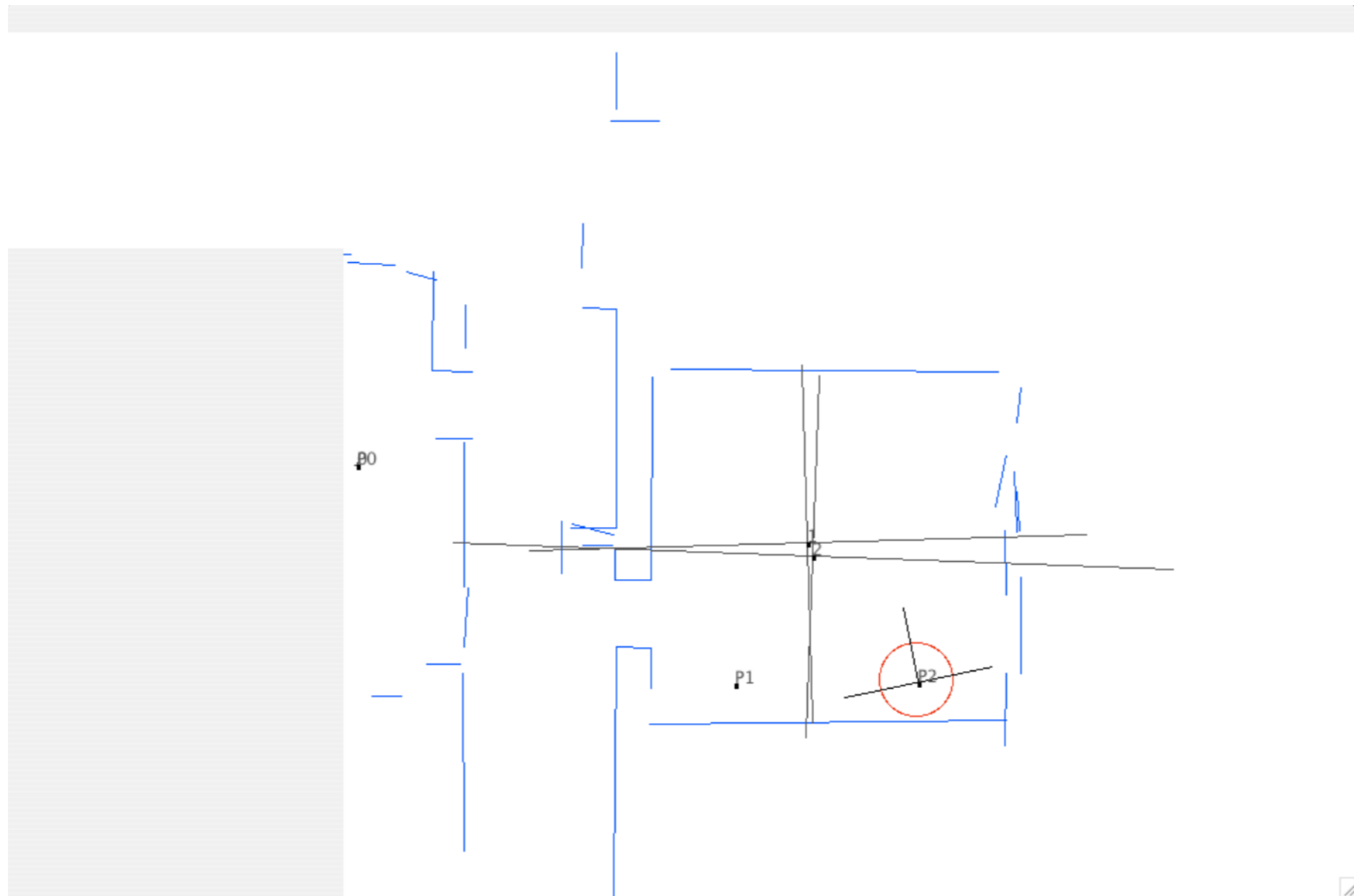
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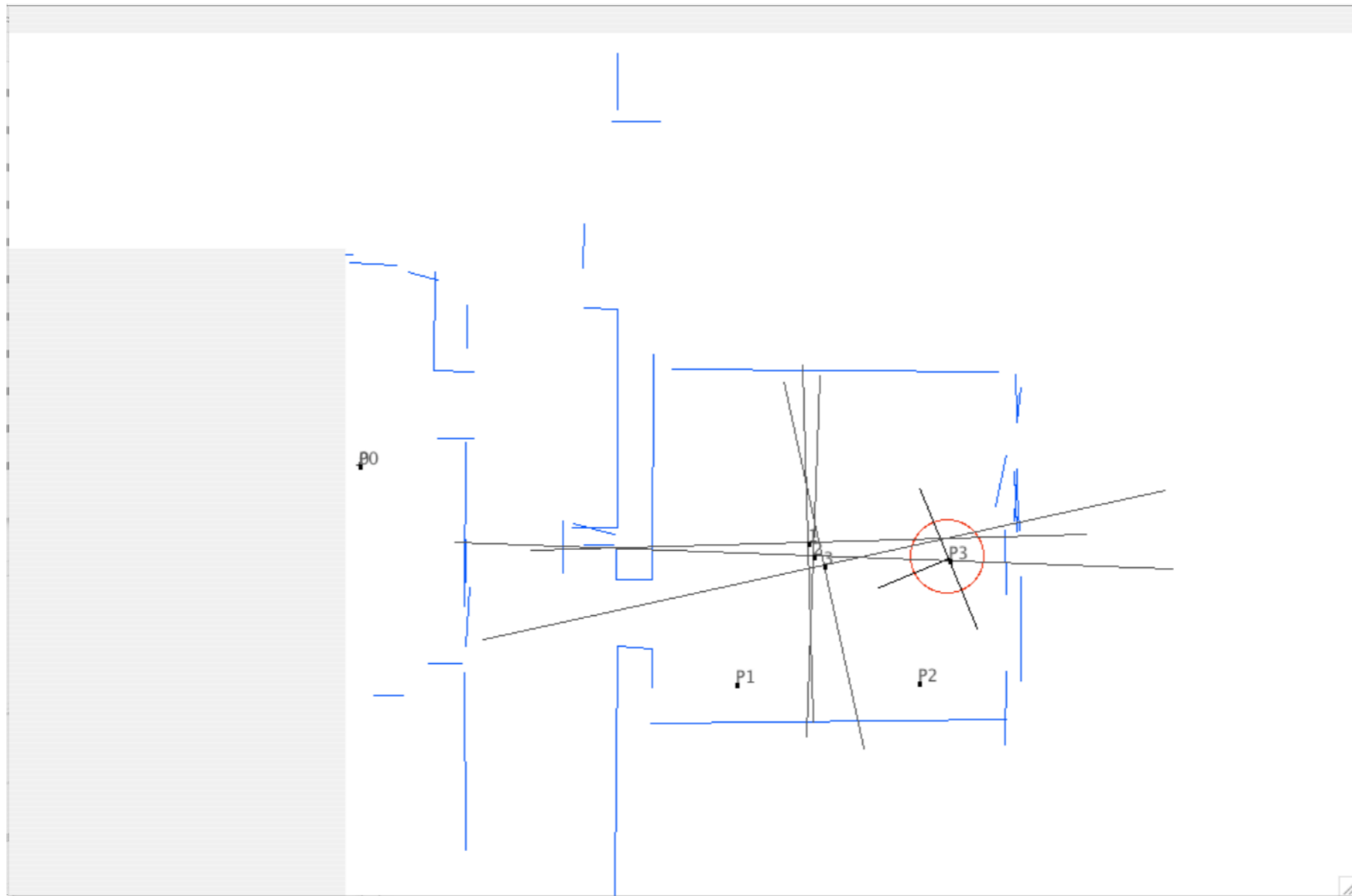
# Building up an ellipsoid from different viewpoints



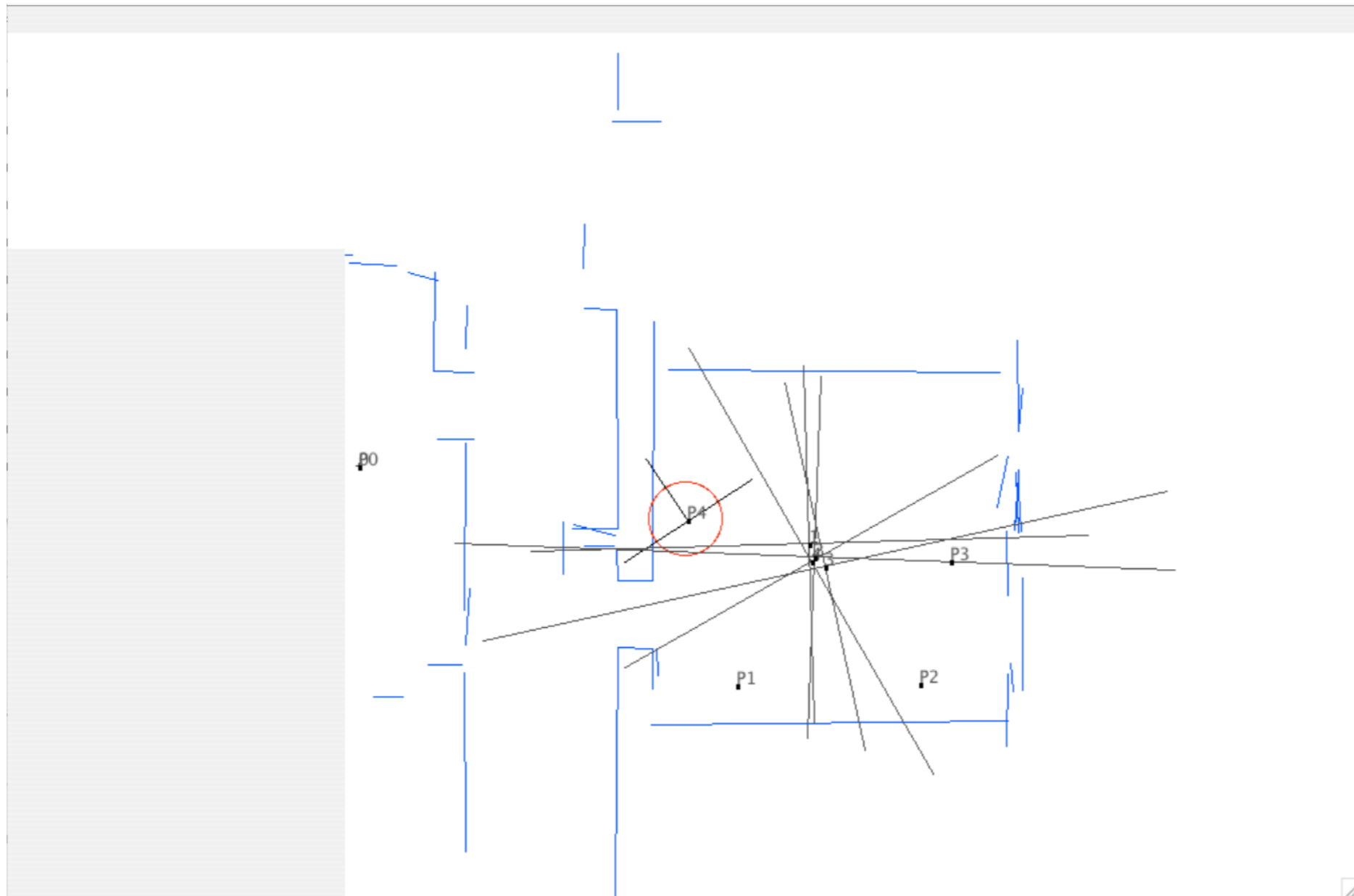
# Building up an ellipsoid from different viewpoints



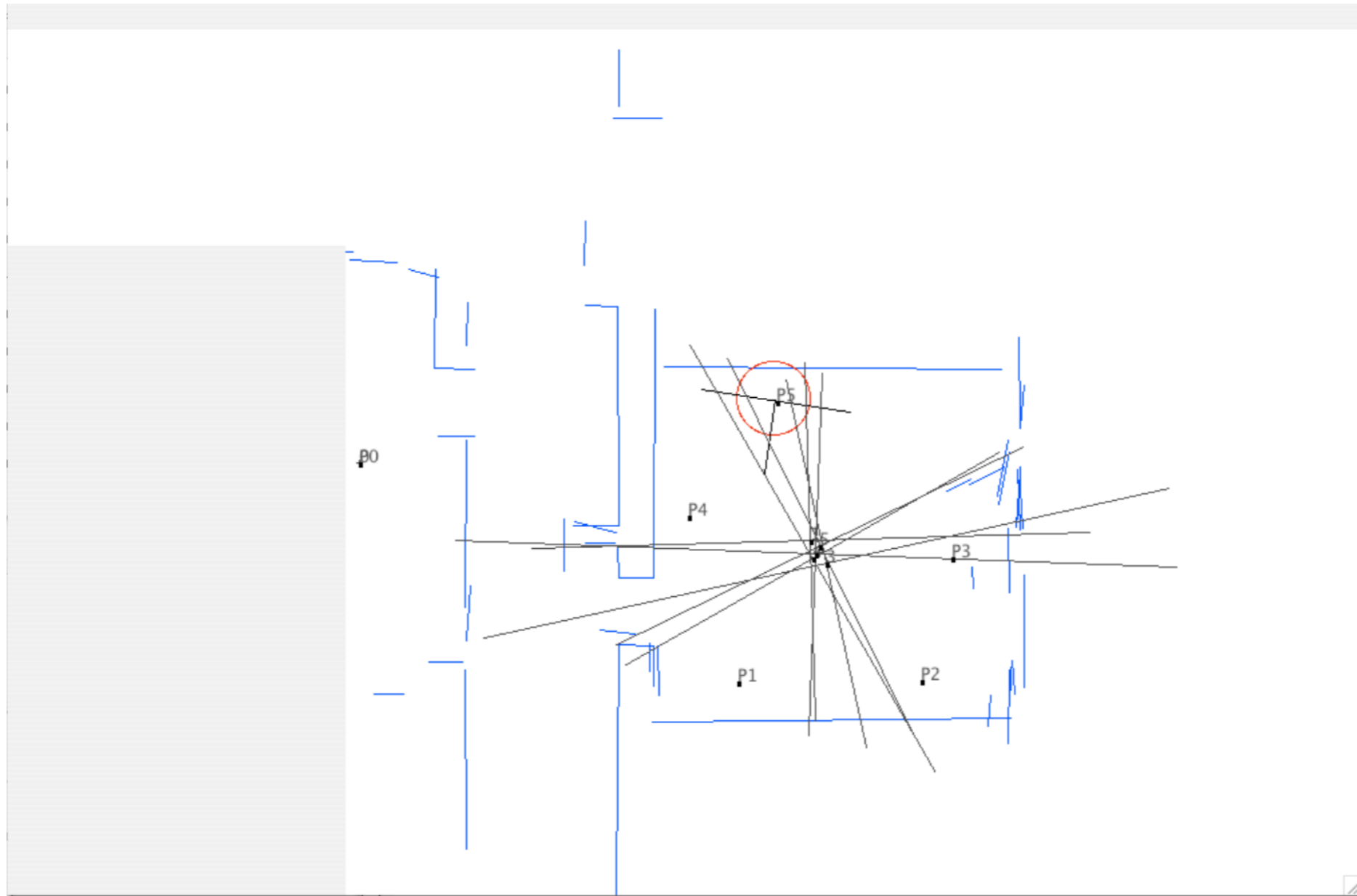
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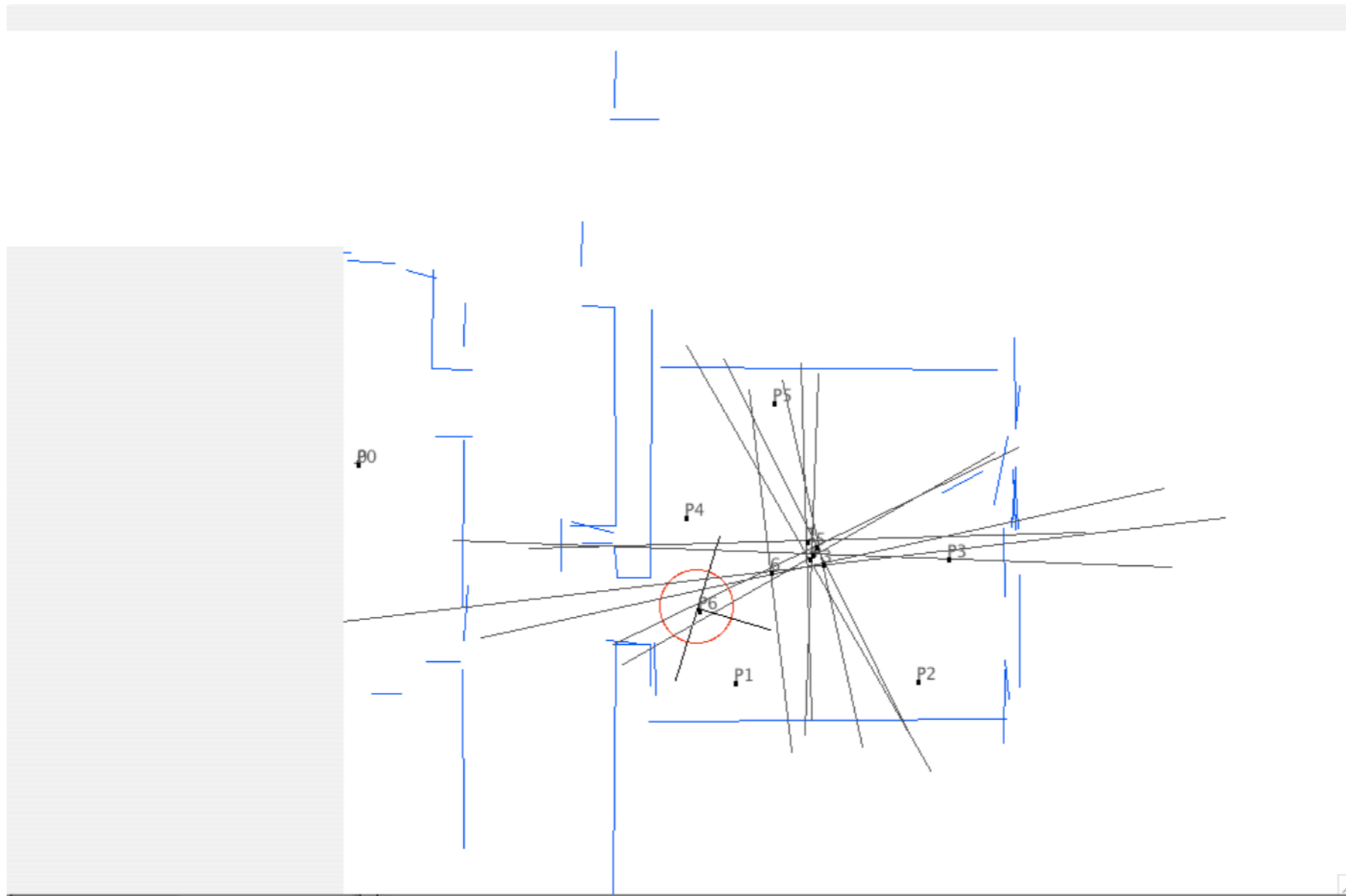


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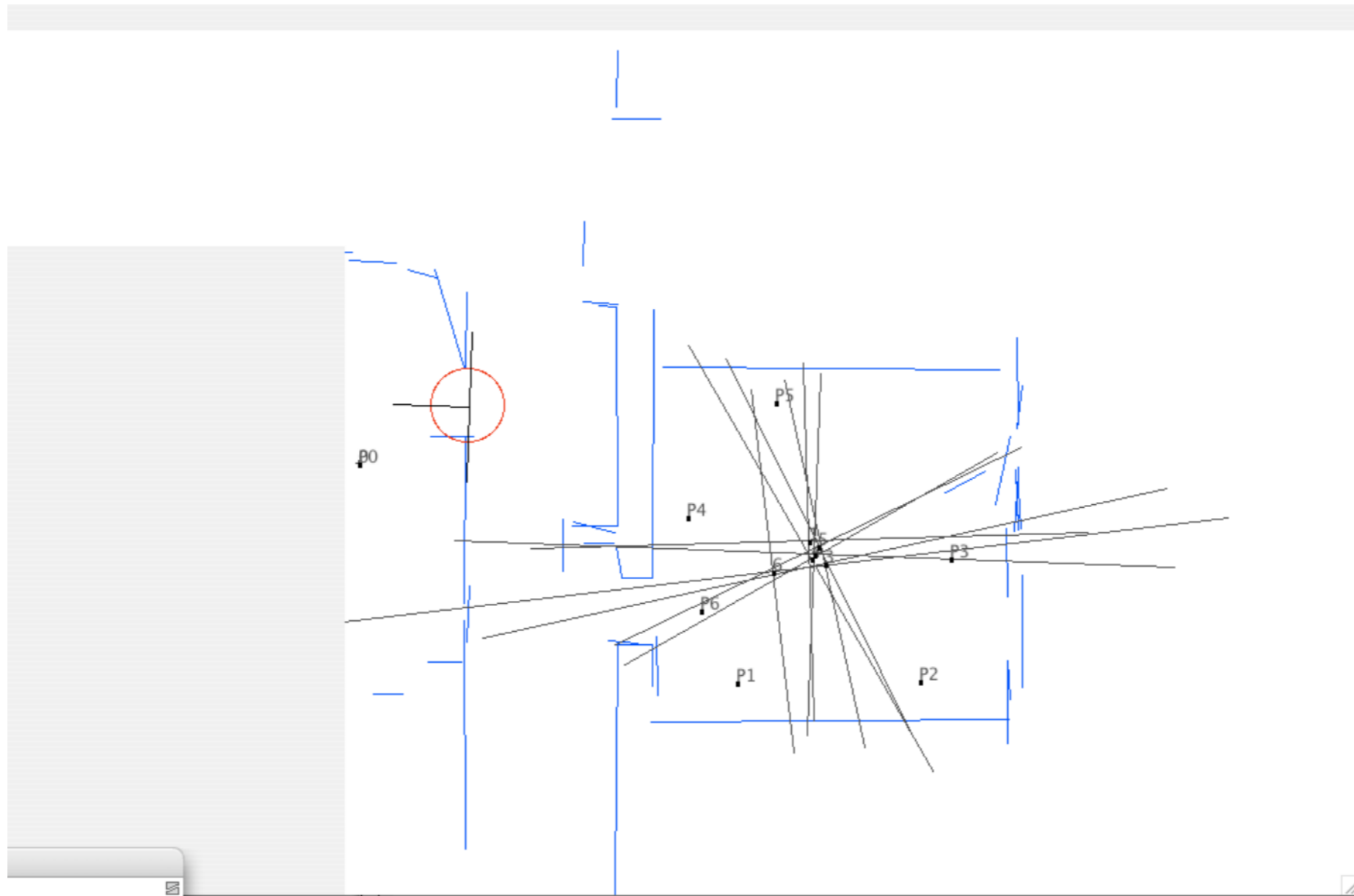




# Building up an ellipsoid from different viewpoints



# Building up an ellipsoid from different viewpoints



# Using the estimate to ask for clarification



# Today's agenda

- Concept learning
- (Recap) Linear Algebra (Goodfellow chapter 2)
- Some tips on Python / Jupyter notebooks and Numpy (shown in Jupyter notebook)

# Outlook lecture 3

- Decision Trees
- Recap Information Theory and Probability Theory
  
- Reading advise: Tom Mitchell, chapter 3, Goodfellow chapter 3, online material by Géron on DTs.

# Today's summary

- Introduced concept learning as an intuitive (conceptual) approach to machine learning (including its limitations)
- Walked through a recap of Linear Algebra concepts, touching upon EVD / SVD and PCA. Exemplified PCA with categorisation of locations from own research
- Showed some examples of use for Numpy in context of image filtering (convolution)
  
- Reading advise: Tom Mitchell, chapter 2, Goodfellow chapter 2, Numpy (SciPy) tutorials / reference at <https://docs.scipy.org/doc/numpy/reference/index.html>, Pierre Nugues introductory chapter on Python (holler, if you did not get it yet)