

3. Modularity

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Outline

- 1 Source code organization
- 2 namespace
- 3 Stack allocation
- 4 Error handling
 - Exceptions
 - Catching exceptions
 - Throwing exceptions
 - Exceptions and resource management
 - Specification of exceptions
 - Static assert
- 5 Input and output

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Program organization

- ▶ A program consists of many separately developed parts
 - ▶ user-defined types
 - ▶ functions
 - ▶ templates
- ▶ managed by clearly defined interactions.
- ▶ Separate
 - ▶ interfaces
 - ▶ implementations

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General program structure Organizing a program in several files

- ▶ Handle declarations and definitions
 - ▶ An entity must be defined at most once
 - ▶ The declaration is needed in all places it is used
 - ▶ `#include`

Source code organization

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The One Definition Rule

- ▶ For a *translation unit*, there must be no more than one definition for
 - ▶ a template
 - ▶ a type
 - ▶ a function, or
 - ▶ an object
- ▶ In the entire *program*, an object or *non-inline* function cannot have more than one definition.
- ▶ If an object or function is used, it must have a definition.
- ▶ Types and templates can be defined in multiple translation units, but must be the same.

Source code organization

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General program structure Example: Header file

Minimal example:

mean – a mean value library

- ▶ `mean.h`
- ▶ `mean.cc`

Use:

- ▶ `main.cc`

mean.h: declarations

```
double mean(double x1, double x2);
double mean(int x1, int x2);
```

Source code organization

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General program structure

Example: Source code file

mean.cc: definitions

```
#include "mean.h"      // make declarations visible so that the
                       // compiler can check that they agree
double mean(double x1, double x2)
{
    return (x1+x2)/2;
}

double mean(int x1, int x2)
{
    return static_cast<double>(x1 + x2) / 2;
}
```

General program structure

Example: main program

main.cc: use

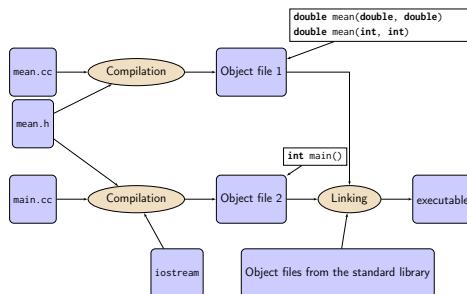
```
#include <iostream>
using std::cout;
using std::endl;

#include "mean.h"      // make declarations visible
                       // to be able to use them
int main()
{
    double a=2.3;
    double b=3.9;
    int m=3;
    int n=4;
    cout << mean(a, b) << endl;
    cout << mean(m, n) << endl;
}
```

General program structure

Separate compilation

- ▶ Function declarations are placed in *header files* (.h)
- ▶ The implementation is split into multiple source files (.cc)
- ▶ Separate compilation of each source file(.cc)
- ▶ Linking the program



File structure for classes

include guards

Class definitions are placed in header files (.h or .hpp)

- ▶ All users of a type need the definition
- ▶ A header file can be included more than once (e.g., via other header files)
- ▶ To avoid defining a type multiple times use *include guards*:

```
#ifndef FOO_H
#define FOO_H
//...
class Foo {
//...
};
#endif
```

Member functions are placed in a source file (.cc or .cpp)

namespace

- ▶ Limit visibility of names
 - ▶ expressing which functions/classes/objects belong together
 - ▶ reduce risk of name clashes
 - ▶ cf. package in Java
- ▶ Accessing names in namespaces:
 - ▶ qualified name (with scope operator): `std::cout`
 - ▶ `using` declaration: `using std::cout;`
 - ▶ brings in a single name into the current scope
 - ▶ `using` directive: `using namespace std;`
 - ▶ brings in all names in namespace std into the current scope
 - ▶ avoid in general, or use in limited scope
 - ▶ never write `using`-directives in header files
 - ▶ introduces names in user code
- ▶ Namespaces *can be extended*
 - ▶ Except (with some exceptions) std (⇒ undefined behaviour)

namespace

Example

declarations (.h)

```
namespace foo {
    void test();
}

namespace bar {
    void test();
}
```

definitions (.cc)

```
using std::cout;
using std::endl;

void foo::test()
{
    cout << "foo::test()\n";
}

void bar::test()
{
    cout << "bar::test()\n";
}

int main()
{
    foo::test();
    bar::test();
    using namespace foo;
    test();
}
```

namespace

- ▶ Unnamed namespaces
 - ▶ local to a particular file (also if `#included`)
 - ▶ is used to hide names (cf. `static` in C)
 - ▶ names clash with global names

```
namespace foo {
    void test()
    {
        cout << "foo::test()\n";
    }
}

namespace {
    void test()
    {
        cout << "::test()\n";
    }
}
```

```
int main()
{
    test();
    foo::test();
    ::test();
}

::test()
foo::test()
::test()
```

- ▶ Alternative names for namespaces (*namespace aliases*):

```
namespace my_name=a_really_long_and_weird_namespace_name;
```

namespace

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Argument Dependent Lookup (ADL)

Name lookup is done in *enclosing scopes*, but...

```
namespace test{
    struct Foo{
        Foo(int v) :x{v} {}
        int x;
    };
    std::ostream& operator<<(std::ostream& o, const Foo& f) {
        return o << "Foo(" << f.x << ")";
    }
} // namespace test

int main()
{
    test::Foo f(17);
    cout << f << endl;
}
```

- ▶ The function `operator<<(ostream&, const Foo&)` is not visible in `main()`.
- ▶ Through ADL it is found in the namespace of its argument (`test`).

namespace

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Argument Dependent Lookup (ADL)

```
namespace test{
    struct Foo;
    std::ostream& operator<<(std::ostream& o, const Foo& f);

    void print(const Foo& f)
    {
        cout << f << endl;
    }

    void print(int i)
    {
        cout << i << endl;
    }
} // namespace test

int main()
{
    test::Foo f(17);

    print(f);
    print(17);
    test::print(17);
}
```

namespace

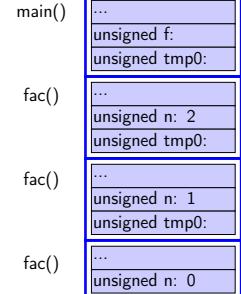
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Memory allocation stack allocation

```
unsigned fac(unsigned n)
{
    if(n == 0)
        return 1;
    else return n * fac(n-1);
}

int main()
{
    unsigned f = fac(2);
    cout << f;
    return 0;
}
```



Stack allocation

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Error handling Three levels of error handling

- 1 Directly handle the error locally and continue execution
- 2 Categorize and pass error to another module that is expected to handle it
- 3 Identify the error, give an error message, and crash the program (*"fail-fast"*, e.g., `assert`)

Level 2: exceptions (or return values)

Error handling : Exceptions

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Throwing exceptions

Example: checking arguments in the `Vector` class

```
Vector::Vector(int size) {
    if(size < 0) throw length_error("negative size");
    elem = new double[size];
    sz = size;
}

int& Vector::operator[](int i) {
    if (i<0 || i>=sz) throw out_of_range("Vector::operator[]");
    return elem[i];
}
```

- ▶ NB: to allow checking arguments, we use a signed integer type for values that should always be positive
- ▶ Vector cannot reasonably handle the error locally, only the caller can know why it passed a certain argument

Error handling : Exceptions

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Exceptions

- ▶ Error handling is done with `throw` and `catch`. Like Java.
- ▶ “*stack unwinding*” until a matching `catch` is found.
- ▶ When an exception is thrown, activation records are popped off the stack until a function containing a matching `catch` is found. (“*stack unwinding*”)
- ▶ If an exception is not caught, the program crashes. (by calling `std::terminate()`)
- ▶ Standard classes for exceptions: `#include <stdexcept>`

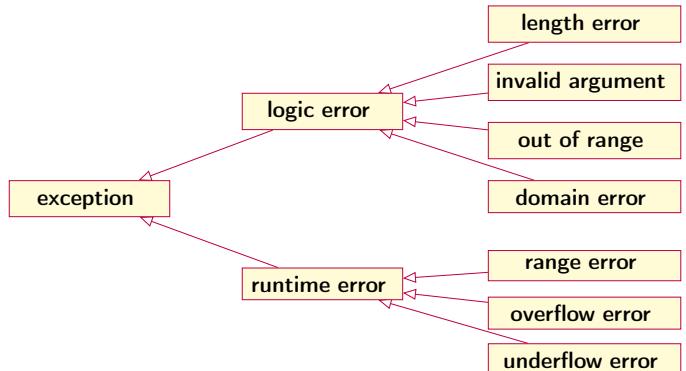
Error handling : Exceptions

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The exception classes of the standard library

Class hierarchy for classes in `<stdexcept>`



Error handling : Exceptions

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Error handling Catching exceptions

```
try {  
    // Code that may throw  
}  
catch (some_exception&) {  
    // Code handling some_exception  
}  
catch (another_exception&) {  
    // Code handling another_exception  
}  
catch (...) {  
    // default/generic exception handling  
}
```

The first `catch` clause with a matching type is selected.
⇒ Catch derived classes before the base class.

... is valid C++, matches anything

Error handling : Catching exceptions

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Catching exceptions

Example:

```
try {  
    cout << "Enter a number: ";  
    int i;  
    if (cin >> i) {  
        int r = f(i);  
        cout << "Result: " << r << endl;  
    }  
}  
catch(overflow_error&) {  
    cout << "Overflow error\n";  
}  
catch(exception& e) {  
    cout << typeid(e).name() << ": " << e.what() << endl;  
}
```

Error handling : Catching exceptions

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Catching exceptions

Exempel:

```
try {  
    cout << "Enter a number: ";  
    int i;  
    if (cin >> i) {  
        int r = f(i);  
        cout << "Result: " << r << endl;  
    }  
}  
catch(overflow_error&) {  
    cout << "Overflow error\n";  
}  
catch(exception& e) {  
    cout << typeid(e).name() << ": " << e.what() << endl;  
}
```

predefined function in the class exception

Error handling : Catching exceptions

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Catching exceptions ... and rethrowing

```
try{  
    do_something();  
}  
catch (length_error& le) {  
    // hantera length error  
}  
catch (out_of_range&) {  
    throw; // pass on  
}  
catch (...) {  
    // default  
}
```

Error handling : Catching exceptions

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Throwing exceptions

Creating own exceptions as subclasses

```
#include<stdexcept>

class communication_error : public runtime_error {
public:
    communication_error(const string& mess = "") : runtime_error(mess) {}
};
```

Throwing

```
throw communication_error("Checksum error");
```

Error handling : Throwing exceptions

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Throwing exceptions

Creating custom exceptions

```
struct MyOwnException {
    MyOwnException(const std::string& msg, int val)
        : m{msg}, v{val} {}
    std::string m;
    int v;
};
```

Using custom exceptions

```
void f() {
    throw MyOwnException("An error occurred", 17);
}

void test1() {
    try {
        f();
    } catch(MyOwnException &e) {
        cout << "Exception: " << e.m << " - " << e.v << endl;
    }
}
```

Error handling : Throwing exceptions

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Catching exceptions

Resource management: destructors and “*stack unwinding*”

```
struct Foo {
    int x;
    Foo(int ix) :x{ix} {
        cout << "Foo("<<x<<")\n";
    }
    ~Foo() {
        cout << "~Foo("<<x<<")\n";
    }
};

void test(int i) {
    Foo f(i);
    if(i == 0) {
        throw std::out_of_range("noll?");
    } else {
        Foo g(100+i);
        test(i-1);
        cout << "after call to test(" << i-1 << ")\n";
    }
}
```

```
int main() {
    Foo f(42);
    try {
        Foo g(17);
        test(2);
    } catch(std::exception& e) {
        cout << e.what() << endl;
    }
    Foo(42)
    Foo(17)
    Foo(2)
    Foo(102)
    Foo(1)
    Foo(101)
    Foo(0)
    ~Foo(0)
    ~Foo(101)
    ~Foo(1)
    ~Foo(102)
    ~Foo(2)
    ~Foo(17)
    noll?
    ~Foo(42)
```

Error handling : Exceptions and resource management

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Specifying exceptions in C++11

The keyword **noexcept** specifies if a function may throw or not.
No specification is equal to **noexcept(false)**.

In the function declaration

```
struct Foo {
    void f();
    void g() noexcept;
};
```

and in the function definition

```
#include<stdexcept>
void Foo::f() {
    throw std::runtime_error("f failed");
}
void Foo::g() noexcept{
    throw std::runtime_error("g lied and failed");
}
```

Error handling : Specification of exceptions

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Exception specification

Example usage

```
#include<typeinfo> // for typeid

void test_noexcept()
{
    Foo f;

    try {
        f.f();
    }catch(std::exception &e) {
        cout << typeid(e).name() << ":" << e.what() << endl;
    }
    try {
        f.g();
    }catch(std::exception &e) {
        cout << typeid(e).name() << ":" << e.what() << endl;
    }
    cout << "done\n";
}

St13runtime_error: f failed
terminate called after throwing an instance of 'std::runtime_error'
what(): g lied and failed
```

Error handling : Specification of exceptions

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Exception specification

older C++, do not use

Older C++ had “exception lists” for a function: the types of exceptions that may be generated by the function are specified with the keyword **throw**.

Example of exception list:

```
int f(int) throw(typ1, typ2, typ3) {
    //...
    throw typ1("Error of type 1 occurred");
    //...
    throw typ2("Error of type 2 occurred");
    //...
    throw typ3("Error of type 3 occurred");
}
```

No list \Rightarrow Any type of exception may be thrown
Empty list (**throw()**) \Rightarrow No exceptions may be thrown

Error handling : Specification of exceptions

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Rules of thumb for exceptions

- ▶ Consider error handling early in the design process
- ▶ Use specific exception types, not built-in types.
(`do not throw 17;, throw false; , etc.`)
- ▶ “Throw by value, catch by reference”
- ▶ If a function should not throw, declare `noexcept`.
- ▶ Specify *invariants* for your types
 - ▶ The constructor establishes the invariant, or throws.
 - ▶ Member functions can rely on the invariant.
 - ▶ Member functions must not break the invariant.
 - ▶ Example: `Vector`
 - ▶ the size `sz` is a positive number
 - ▶ the array `elem` points to has size `sz`
 - ▶ if the allocation of the array fails `std::bad_alloc` is thrown

If something can be checked at compile-time, use `static_assert`.

Static assert

If something can be checked at compile-time, use `static_assert`.

```
constexpr int some_param = 10;

int foo(int x)
{
    static_assert(some_param > 100, "some_param too small");
    return 2*x;
}

int main()
{
    int x = foo(5);

    std::cout << "x is " << x << std::endl;
    return 0;
}

// error: static assertion failed: some_param too small
```

Stream I/O

- ▶ The C++ standard library contains facilities for
 - ▶ Structured I/O ("formatted I/O")
 - ▶ reading values of a certain type, `T`
 - ▶ overload `operator>>(istream&, T&)` and
 - ▶ `operator<<(ostream&, const T&)`
 - ▶ Character I/O ("raw I/O")
 - ▶ `istream& getline(istream&, string&)`
 - ▶ `istream& istream::getline(char*, streamsize)`
 - ▶ `int istream::get()`
 - ▶ `istream& istream::ignore()`
 - ▶ ...
- ▶ NB! `getline()` as free function and member of `istream`.
- ▶ Choose raw or formatted I/O based on your application

Suggested reading

References to sections in Lippman

Exceptions 5.6, 18.1.1

Namespaces 18.2

I/O 1.2, 8.1–8.2, 17.5.2

Next lecture

References to sections in Lippman

Classes 2.6, 7.1.4, 7.1.5

Constructors 7.5–7.5.4

(Aggregate classes) ("C structs" without constructors) 7.5.5

Destructors 13.1.3

this and const s 257–258

inline 6.5.2, s 273

friend 7.2.1

static members 7.6

Copying 13.1.1

Assignment 13.1.2

Operator overloading 14.1 – 14.3