

Computer Graphics

Introduction to 3D

EDAF80

Michael Doggett



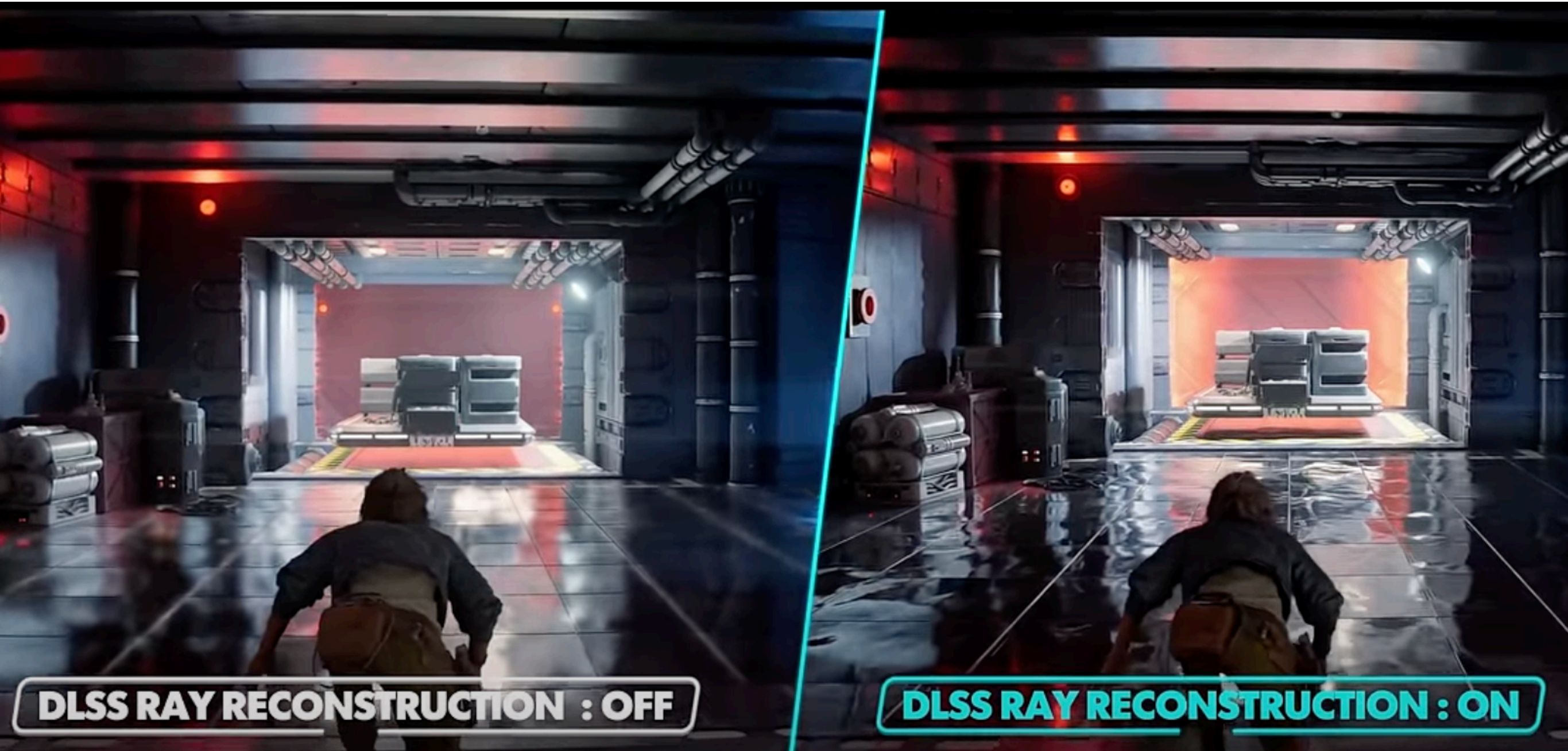
Slides by Jacob Munkberg 2012-13

What words come to mind when you think about Computer Graphics?

137 responses



Ubisoft MASSIVE SW Outlaws PC trailer

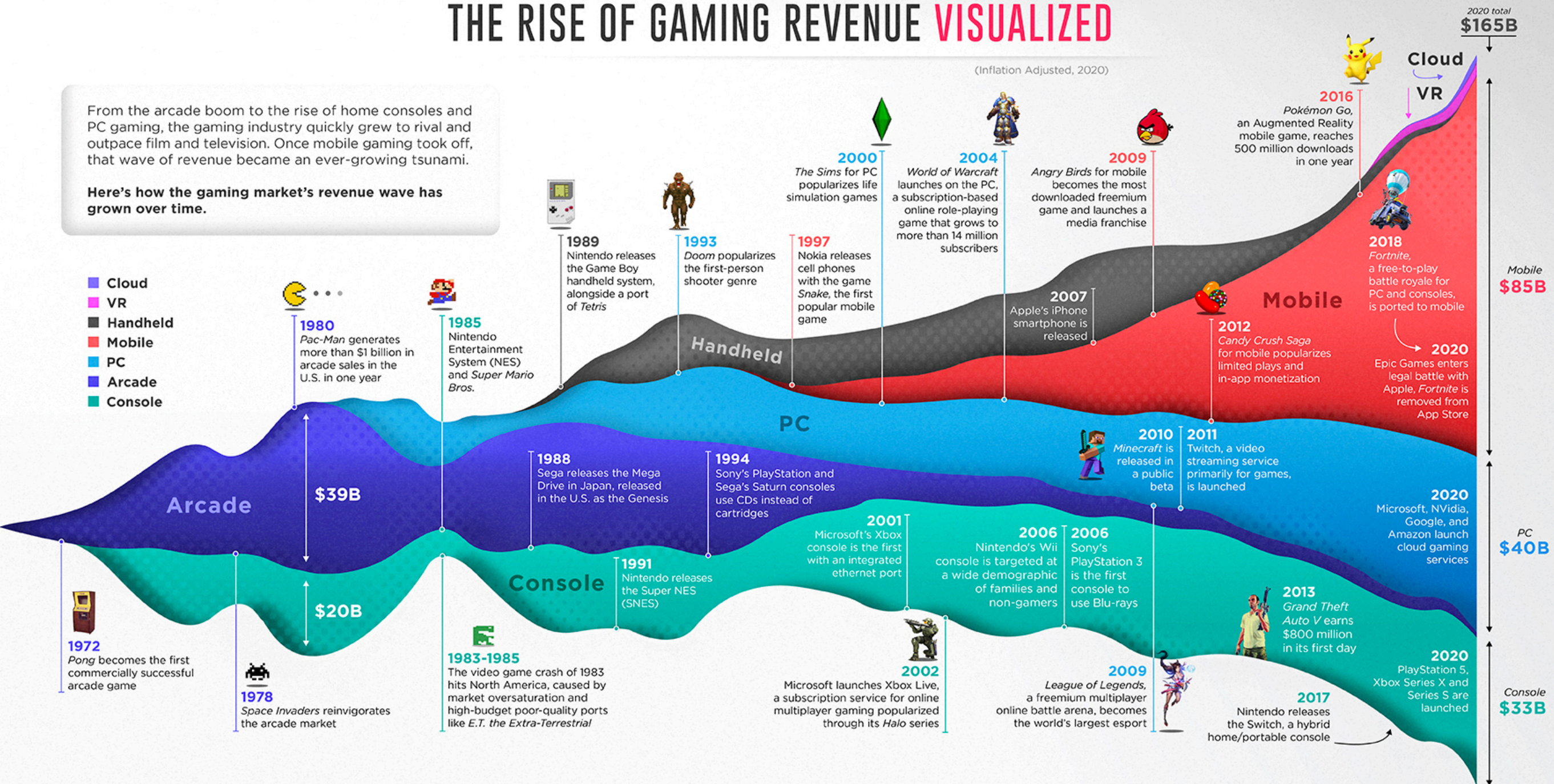


<https://youtu.be/cMqqfkLhuZk>

THE RISE OF GAMING REVENUE VISUALIZED

From the arcade boom to the rise of home consoles and PC gaming, the gaming industry quickly grew to rival and outpace film and television. Once mobile gaming took off, that wave of revenue became an ever-growing tsunami.

Here's how the gaming market's revenue wave has grown over time.



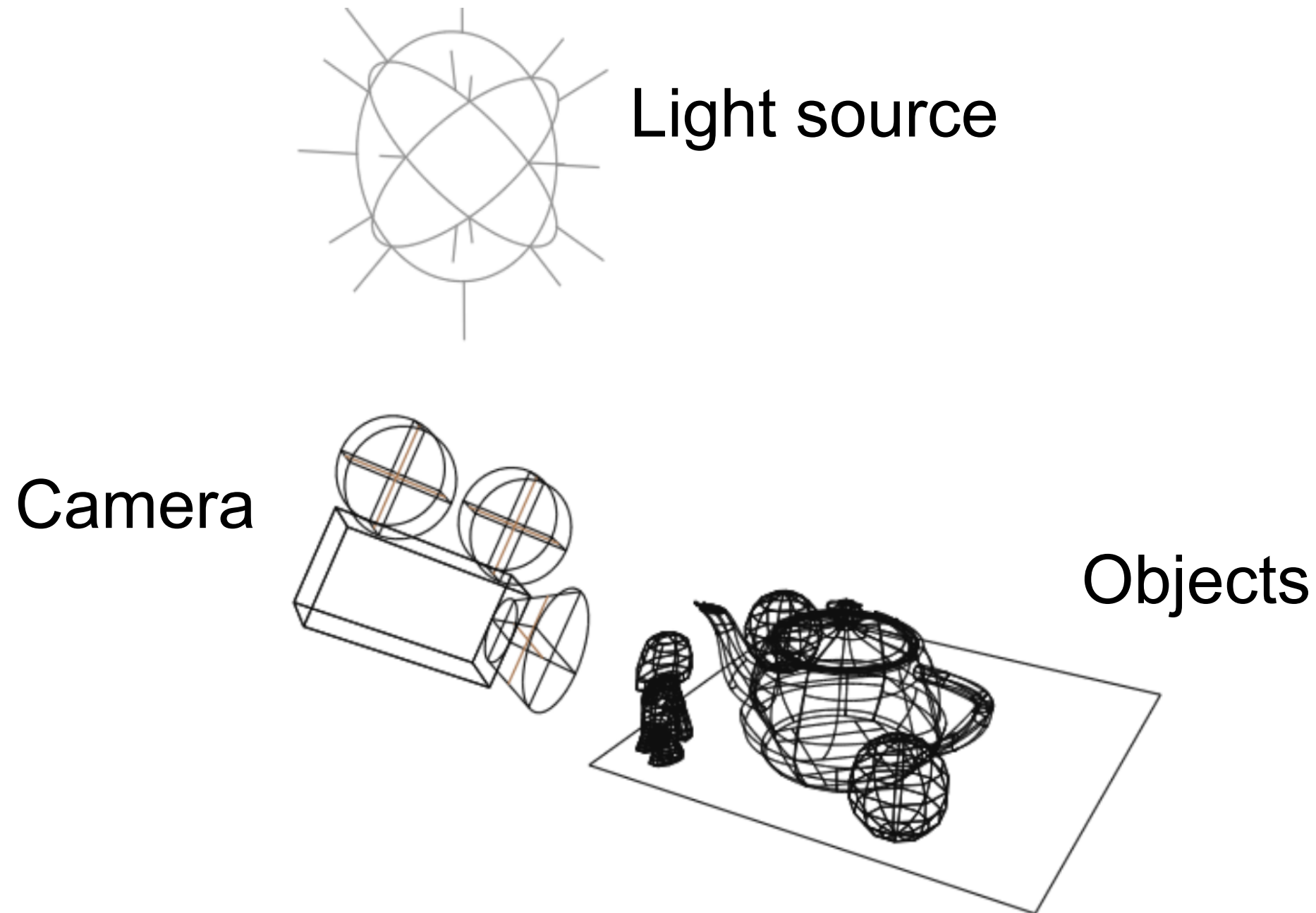
SOURCE: Pelham Smithers
COLLABORATORS: RESEARCH • WRITING Omri Wallach | DESIGN • ART DIRECTION Clayton Wedsworth

VISUAL CAPITALIST

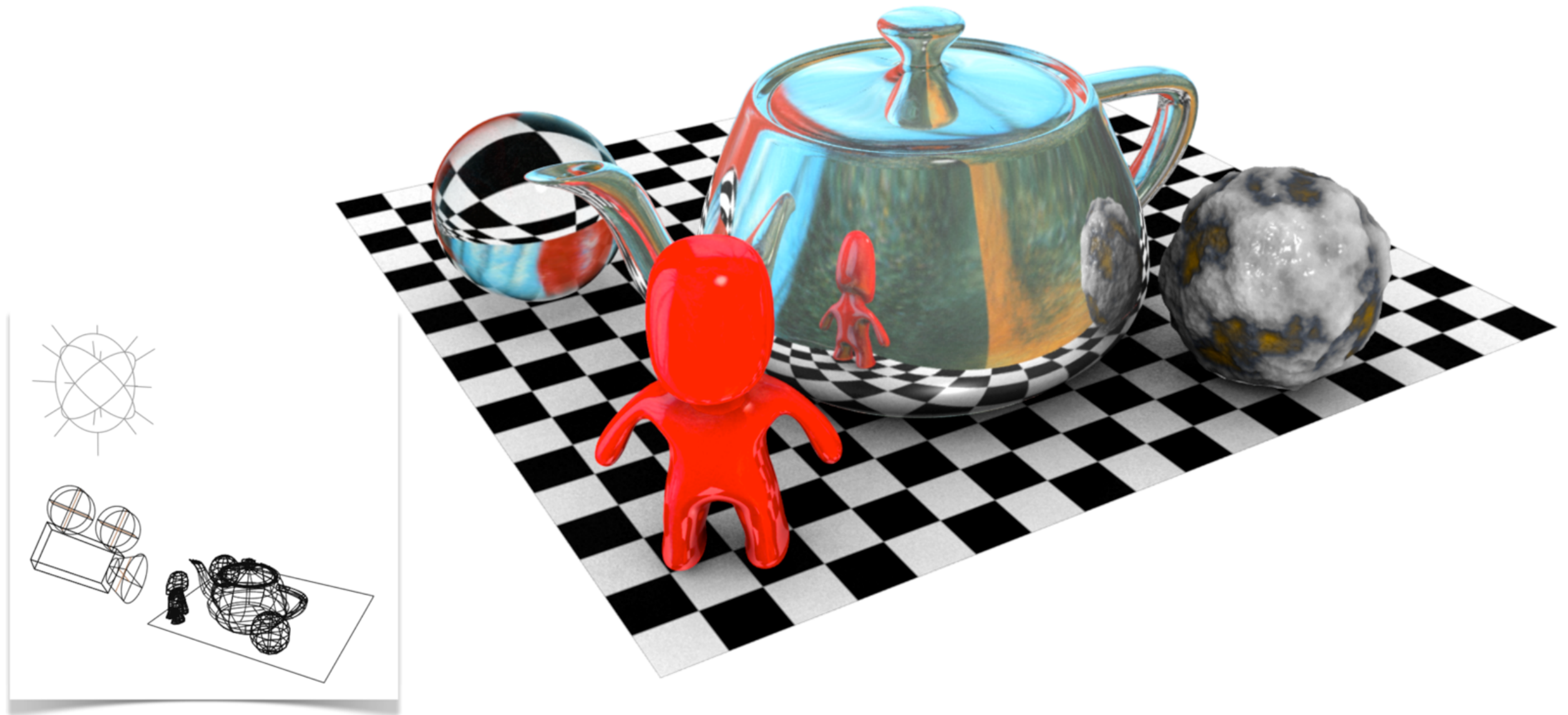
f /visualcapitalist t @visualcap i visualcapitalist

<https://www.visualcapitalist.com/50-years-gaming-history-revenue-stream/>

Create Virtual Scenes



Rendered Image



Course Goals

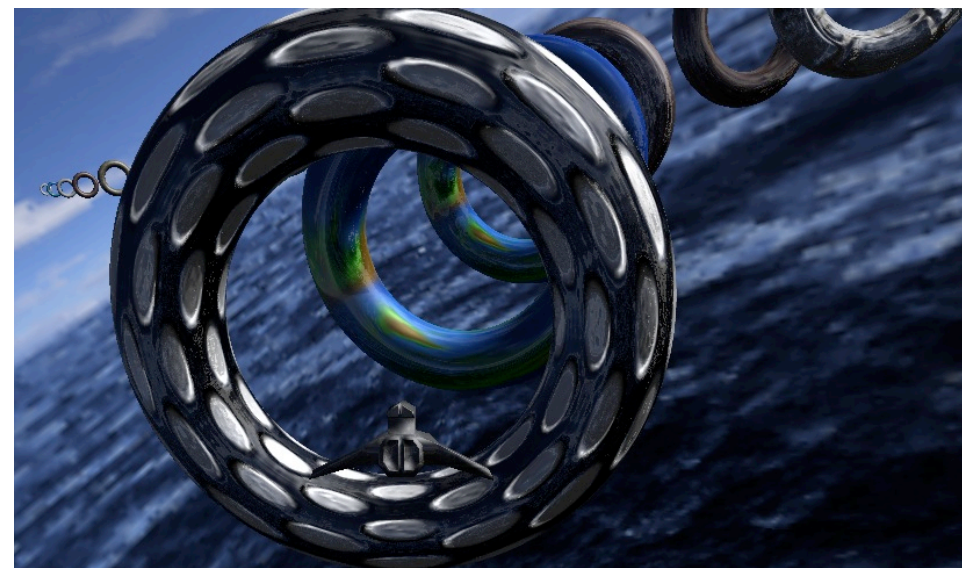
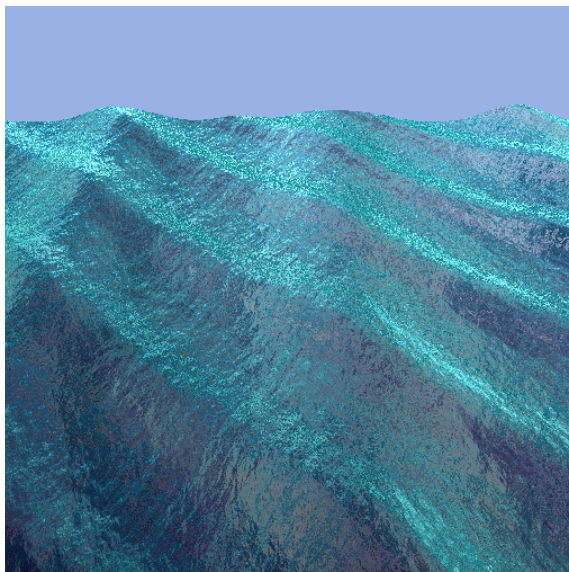
- Introduction to Computer Graphics
- Create and **position** objects in 3D
- Create materials - write **shaders**
- Visualize 3D scenes - **render** images
- Introduction to **OpenGL**
 - Create interactive graphics

Organization

- Lectures : Theory and concepts
- Seminars
 - Applied theory & hands-on examples
- Assignments
 - Computer Graphics in practice, C++, OpenGL & GLSL
- Examination
 - All five assignments approved
 - Written exam

Assignments

- Five mandatory programming assignments
- Code is downloadable from GitHub, see web page
- Seminars: Wednesdays 10-12 in M:1201
 - Bring your laptops!



Lab Sessions

- Done in pairs - book a lab!
 - <https://sam.cs.lth.se/LabsSelectSession?occasionId=890>
- Both students must be present at marking, and answer questions (including lab 5)
- If you don't have a partner, ask in the seeking-lab-partner channel on the Graphics discord server
- Pick only one lab time per week, that is for the term

C++ programming language

- Game industry is still C++ centric
 - low-level for performance, memory management
- We use a limited subset, roughly C++98
- If you are unfamiliar with C++, you will need to learn it as you go through the course.

Website

- cs.lth.se/edaf80
- Lectures will be posted online
- Online discussion using Discord (Check Canvas page for link)
- Booking system for assignment approval sessions
 - Sign up for 1 of 4 lab sessions
- Code & assignments - Code available on GitHub
- Links

Course Material

- Literature
 - Lectures & Seminars
 - No Textbook
 - Edward Angel, Dave Shreiner, **Interactive Computer Graphics: A Top-Down Approach with Shader-Based OpenGL**, Pearson Education, 6th edition (old course textbook)
 - Many very good graphics resources online
 - learnopengl.com
 - [Graphics Codex](#)
 - Advanced : [Physically Based Rendering \(PBRT\)](#)
- Prerequisites
 - Programming (first course) & Linear Algebra
 - Assumed knowledge - Programming second course

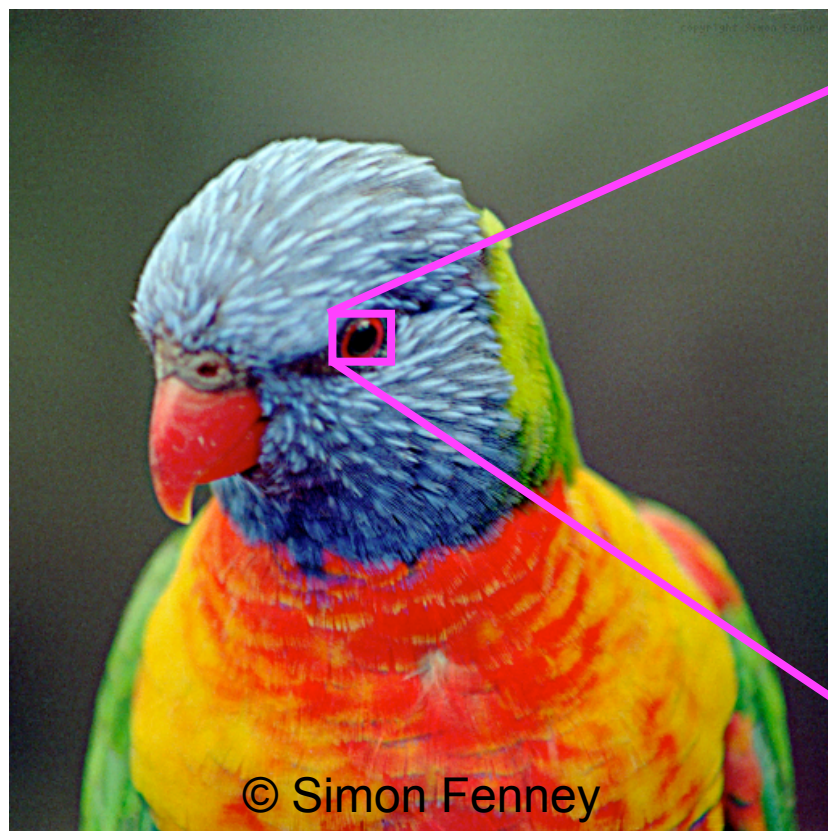
Staff

- Michael Doggett - Lectures, Exam
 - Visiting Professor at Facebook Reality Labs, Seattle, Docent, GPU architect at ATI/AMD, Post-doc in Germany, PhD in Australia
- Rikard Olajos - Seminars, TA
- TAs - Michail Boulasikis, Jintao Yu

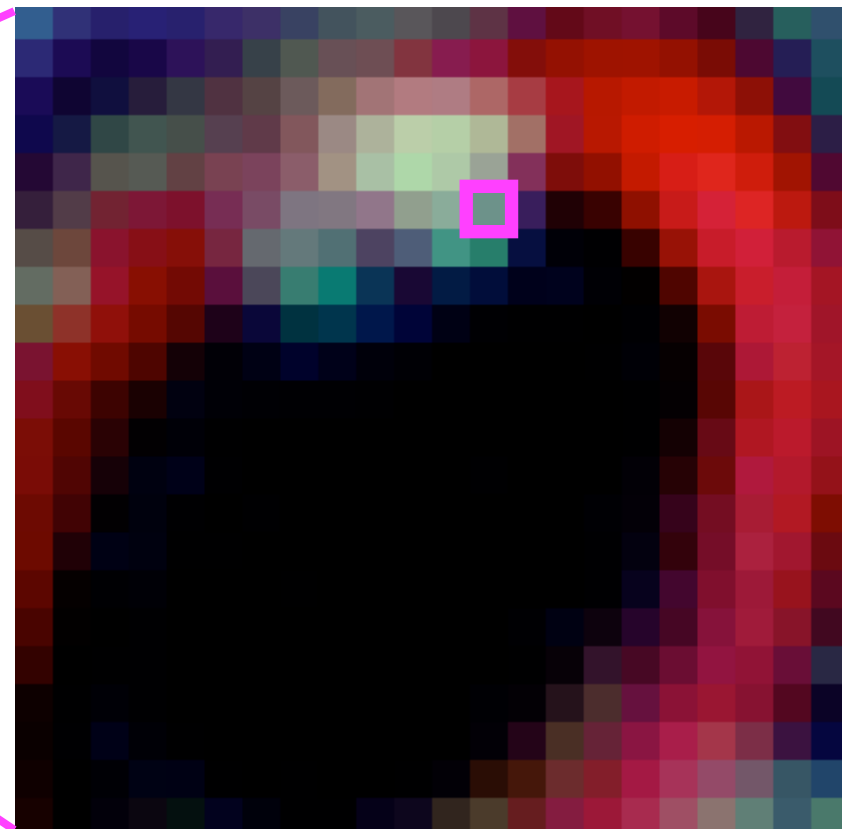
Definitions

Pixel

- Pixel - Picture element
- Our task - compute color of each pixel



512x512 pixels

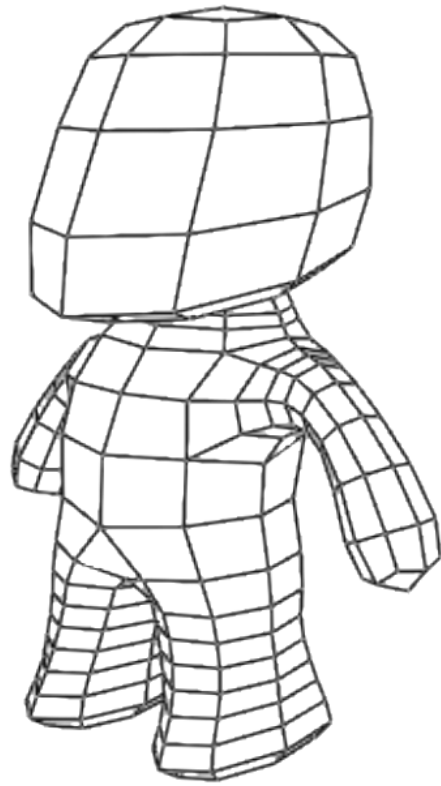


22x22 pixels

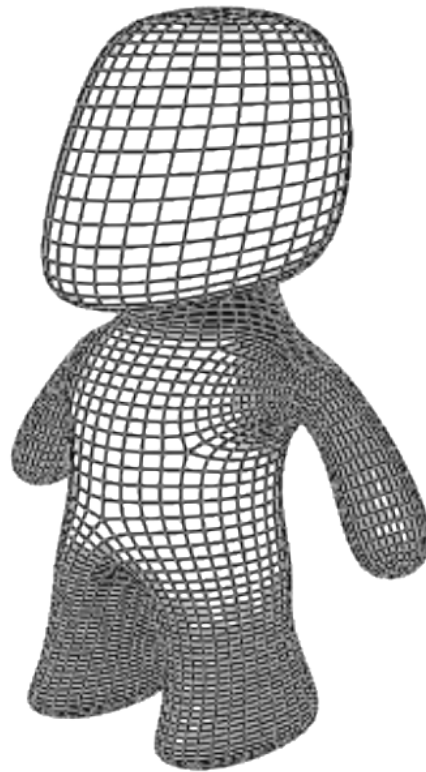
Pixel Resolutions

- Doom (320x240)
- VGA (640x480)
- 1080p - Smartphone (1920 x 1080)
- MacBook Pro retina (2880 x 1800)
- 4K TV “Ultra HD” (3840 x 2160)
- 8K (7680 x 4320)
- Camera - Hasselblad X2D 100C - 100MPixel (11,656 x 8742)

Image Formation



Mesh



Tessellated Mesh



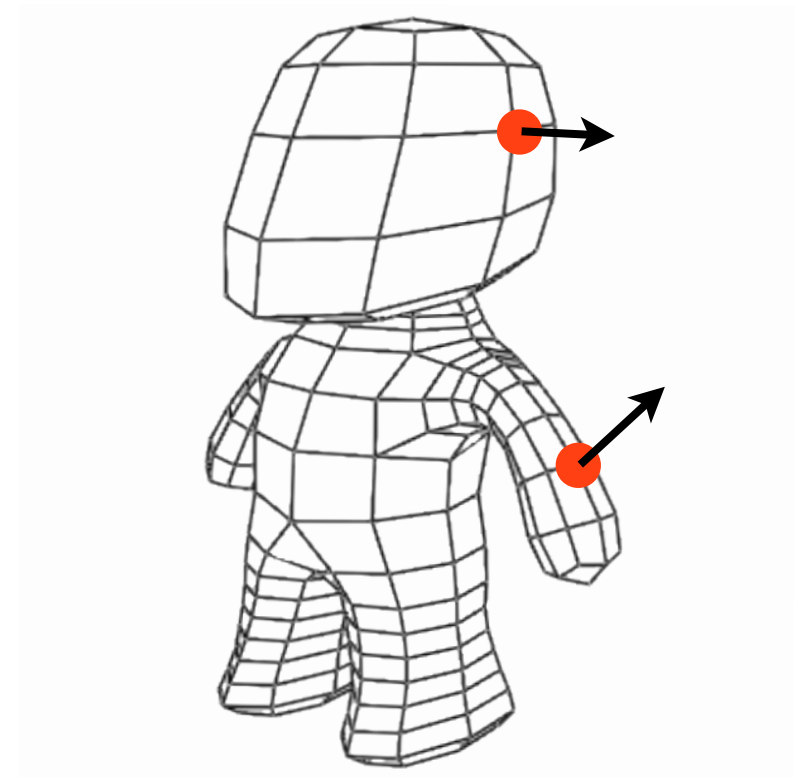
Lit & Shaded Mesh

We need ways to represent geometry and move objects in three-dimensional coordinate systems

Vertex

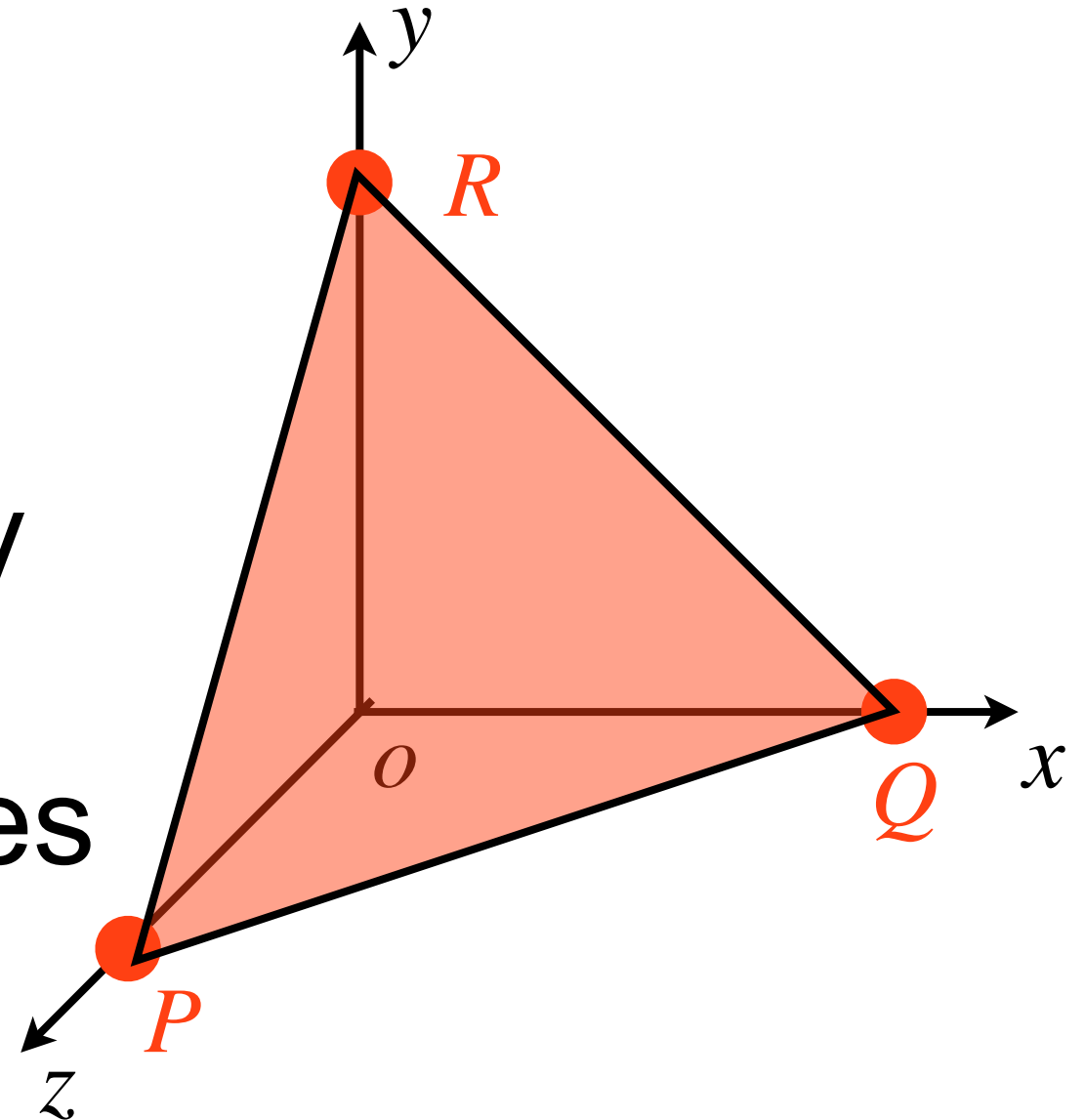
- A set of attributes describing a point in space

```
struct Vertex
{
    float x,y,z;           // pos
    float nx, ny, nz;      // normal
    float r,g,b;           // color
};
```



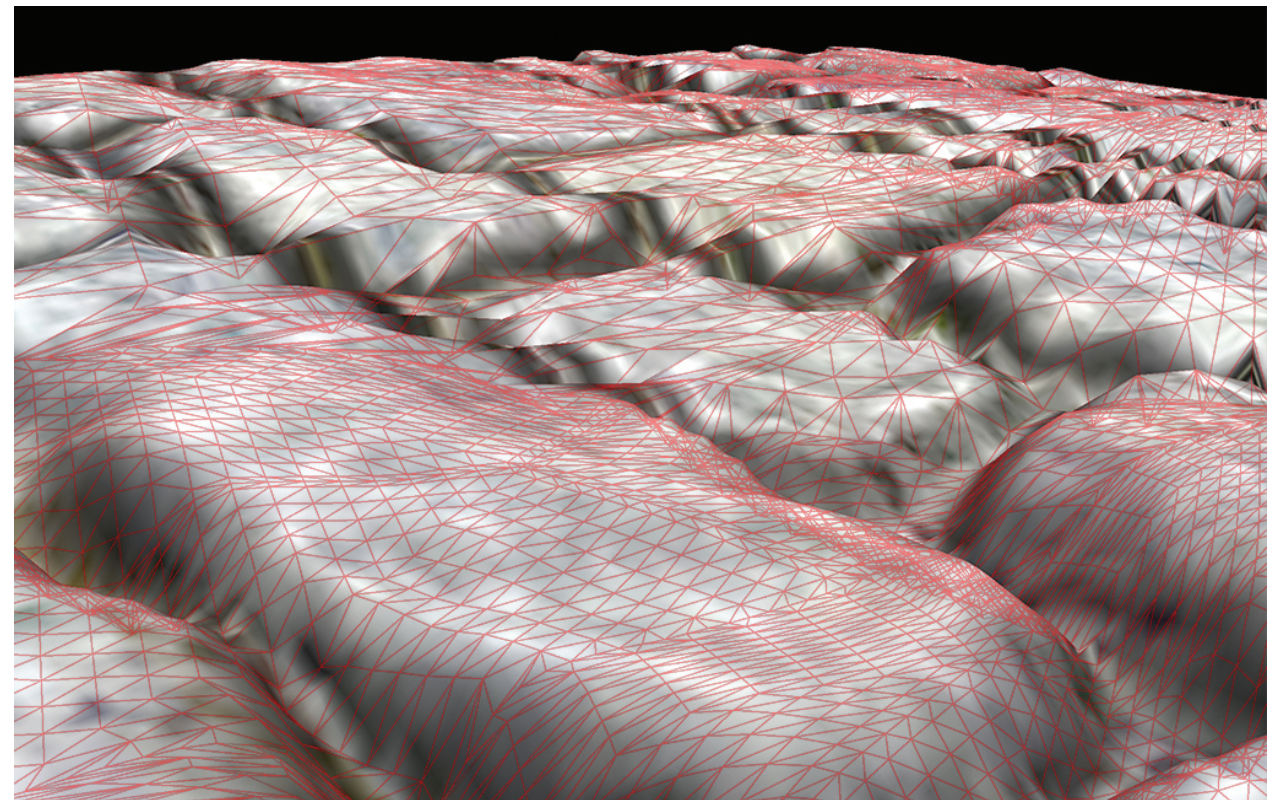
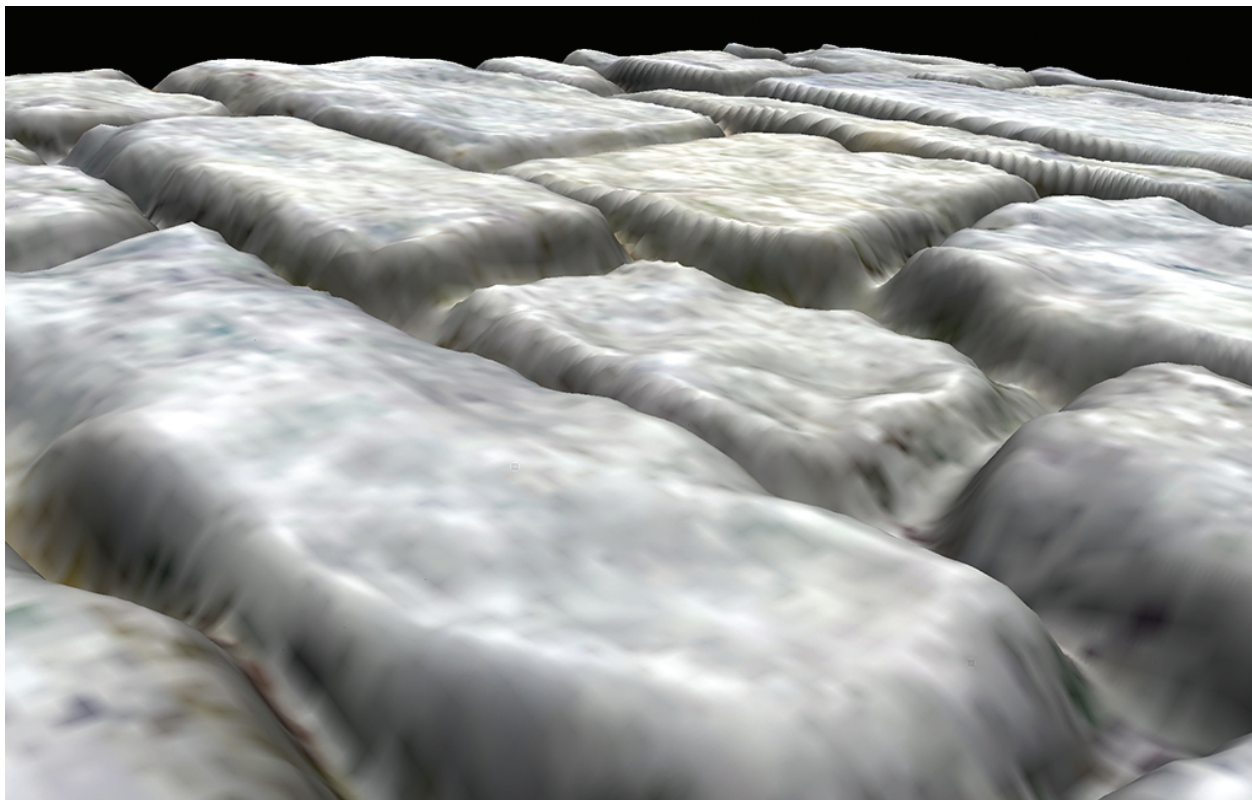
Triangle in 3D

- Defined by three connected vertices
 - Here: specified in the Cartesian system
- Models are typically built from a large collection of triangles



Geometry Meshes

- Model complex shapes from triangles



Materials



- Determine the appearance of objects
 - How objects interact with light
- Specified as “small” programs called **shaders**

Simple Pixel Shader

- Set pixel color to red

```
out vec4 fColor;
```

```
void main()
```

```
{
```

```
    fColor = vec4(1,0,0,1);
```

```
}
```

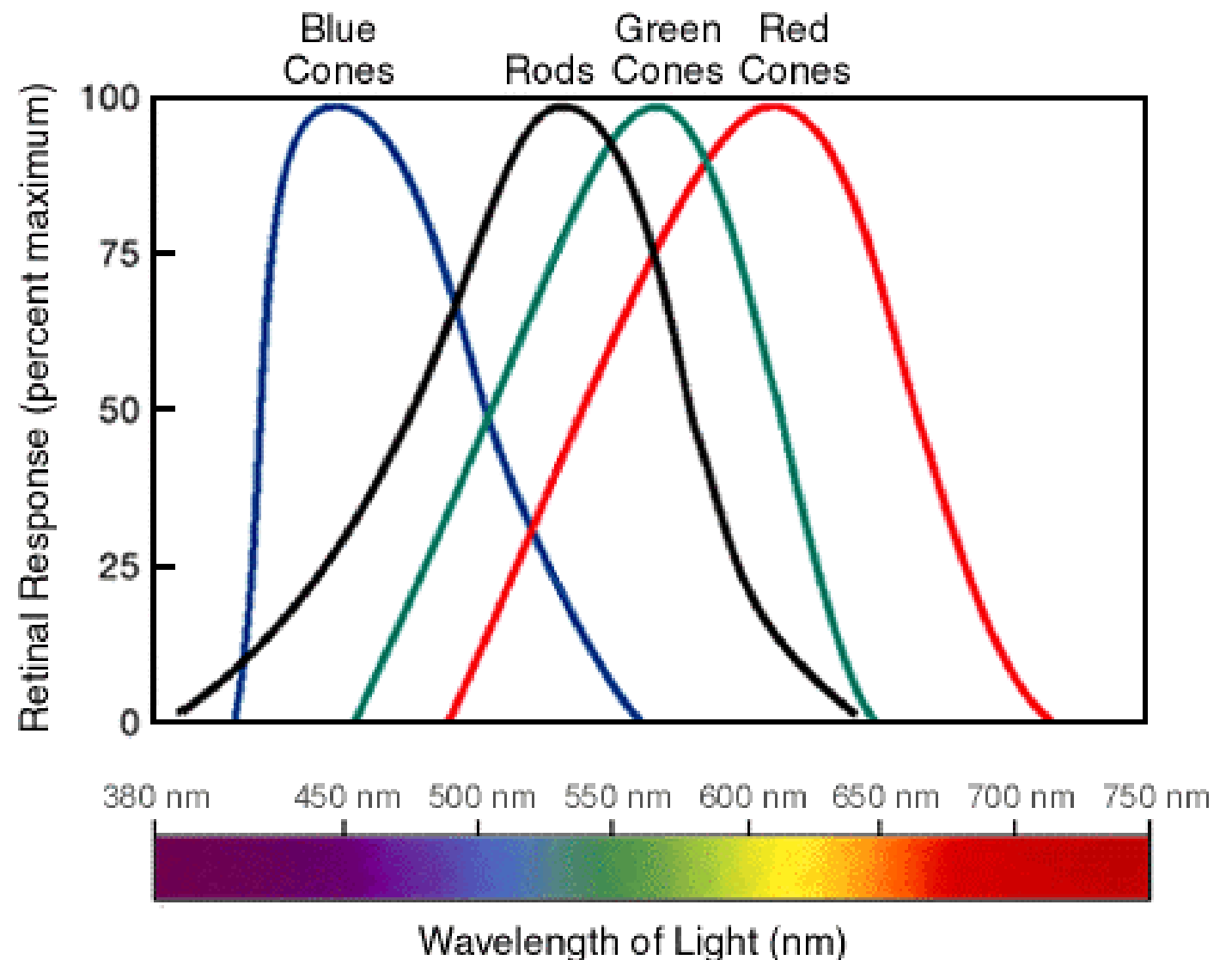
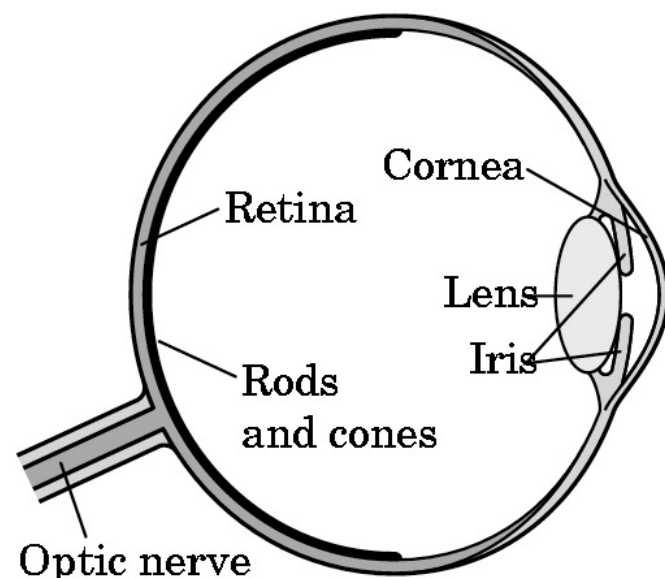

Light

- Light is the part of the electromagnetic spectrum that causes a reaction in our visual systems
- Wavelengths in 380-750 nanometers
- Long wavelengths appear as reds and short wavelengths as blues



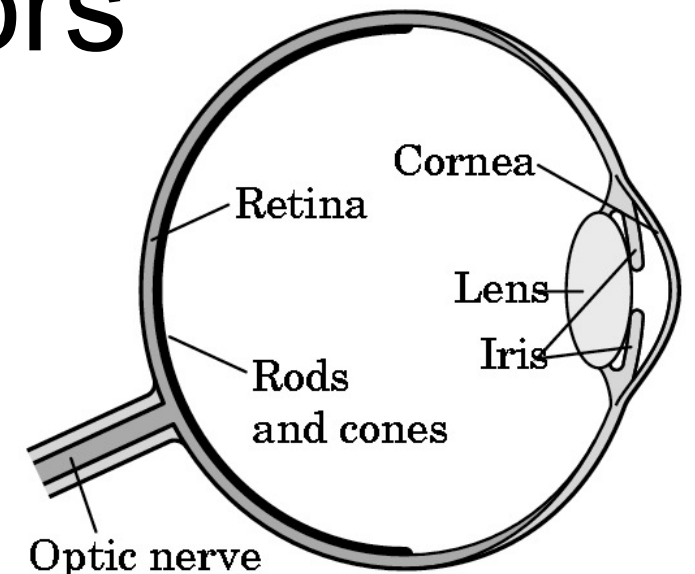
Color Perception

- Color stimulates cones in the retina
- Three different kinds of cones



Human Visual System (HVS)

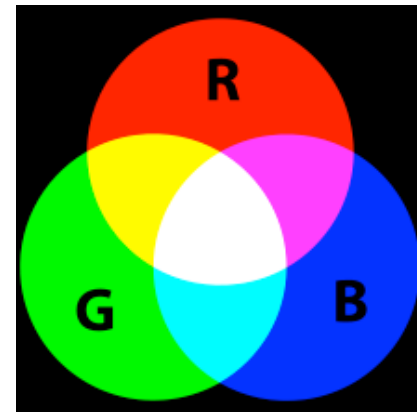
- HVS has two types of sensors
 - **Rods:** monochromatic, night vision
 - **Cones:** Color sensitive, three types of cones
 - Only three values (the *tristimulus* values) are sent to the brain
- Need only match these three values
- Need only three primary colors: RGB



Color

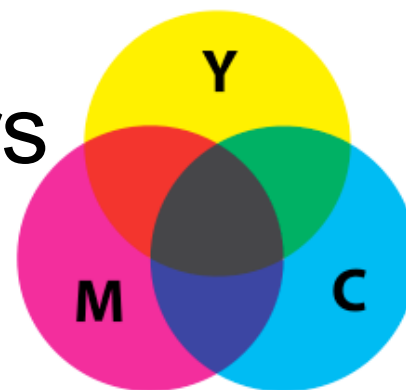
- Additive color

- Form a color by adding amounts of three primaries: Red (R), Green (G), Blue (B)
- Often stored using 8 bits per primary which gives $(2^8)^3 = 16.8\text{M}$ unique colors

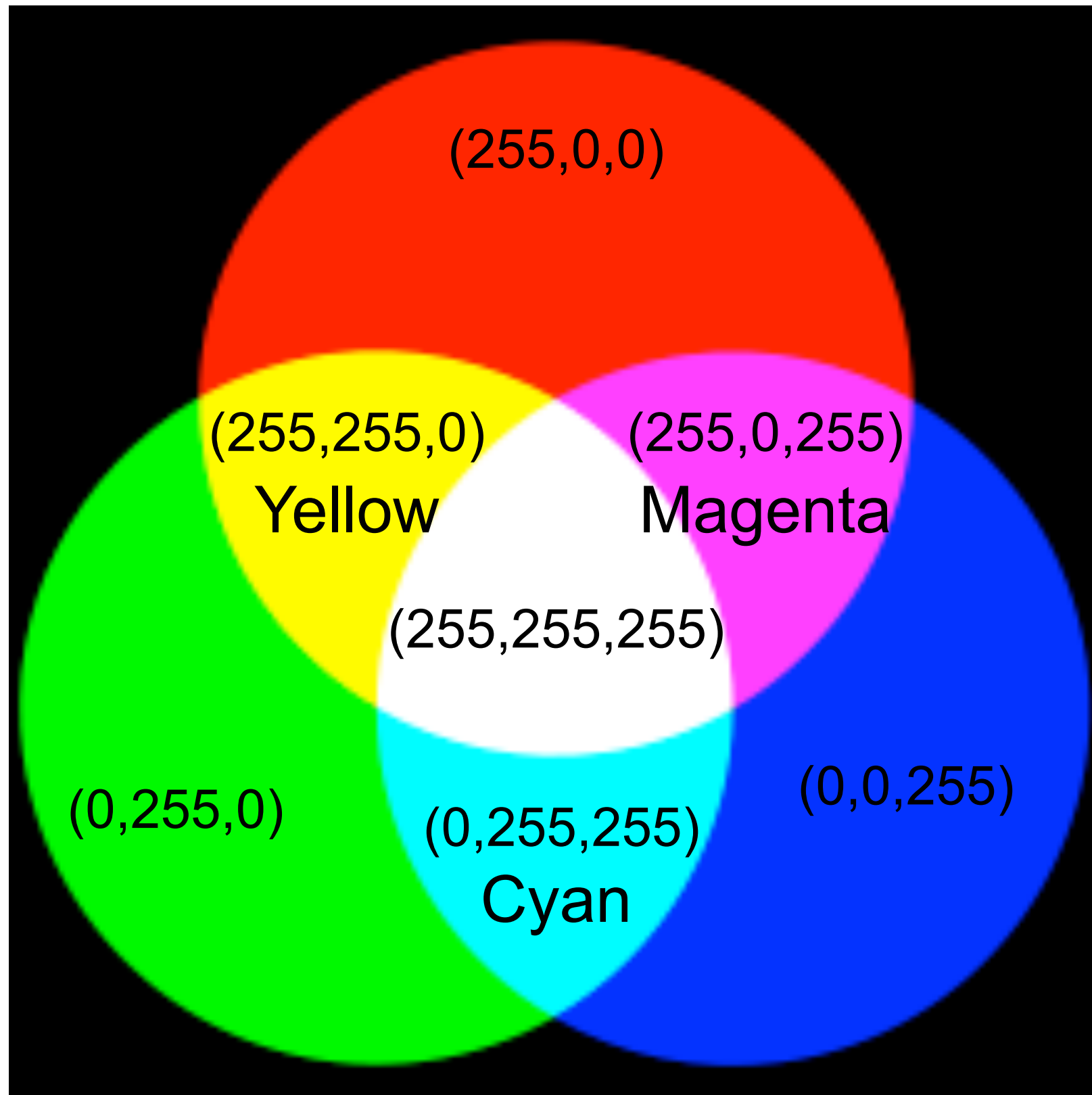


- Subtractive color

- Form a color by filtering white light with Cyan (C), Magenta (M), and Yellow (Y) filters
- Light-material interactions, printing

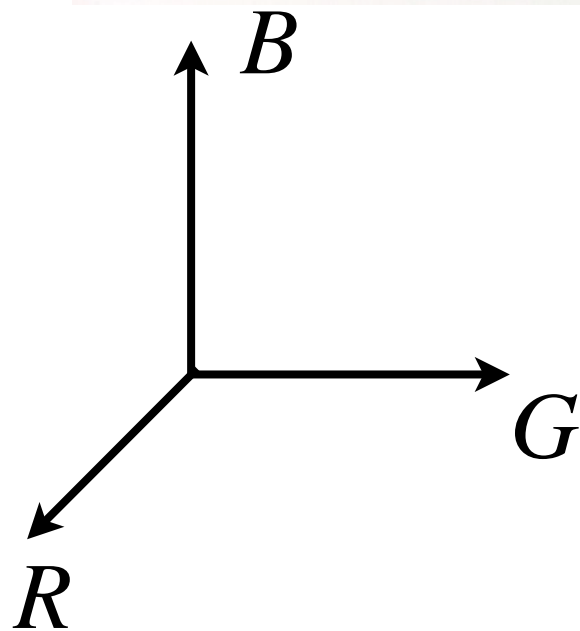
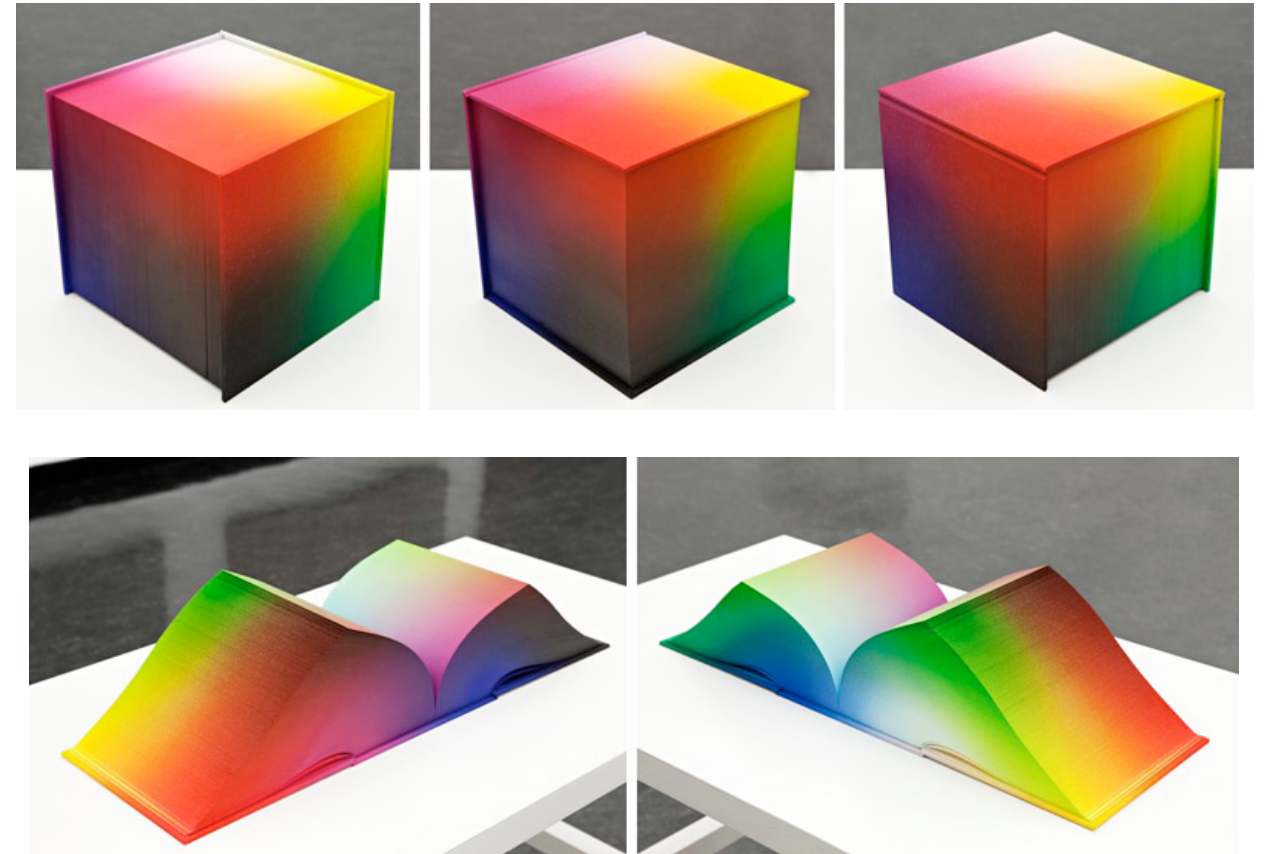
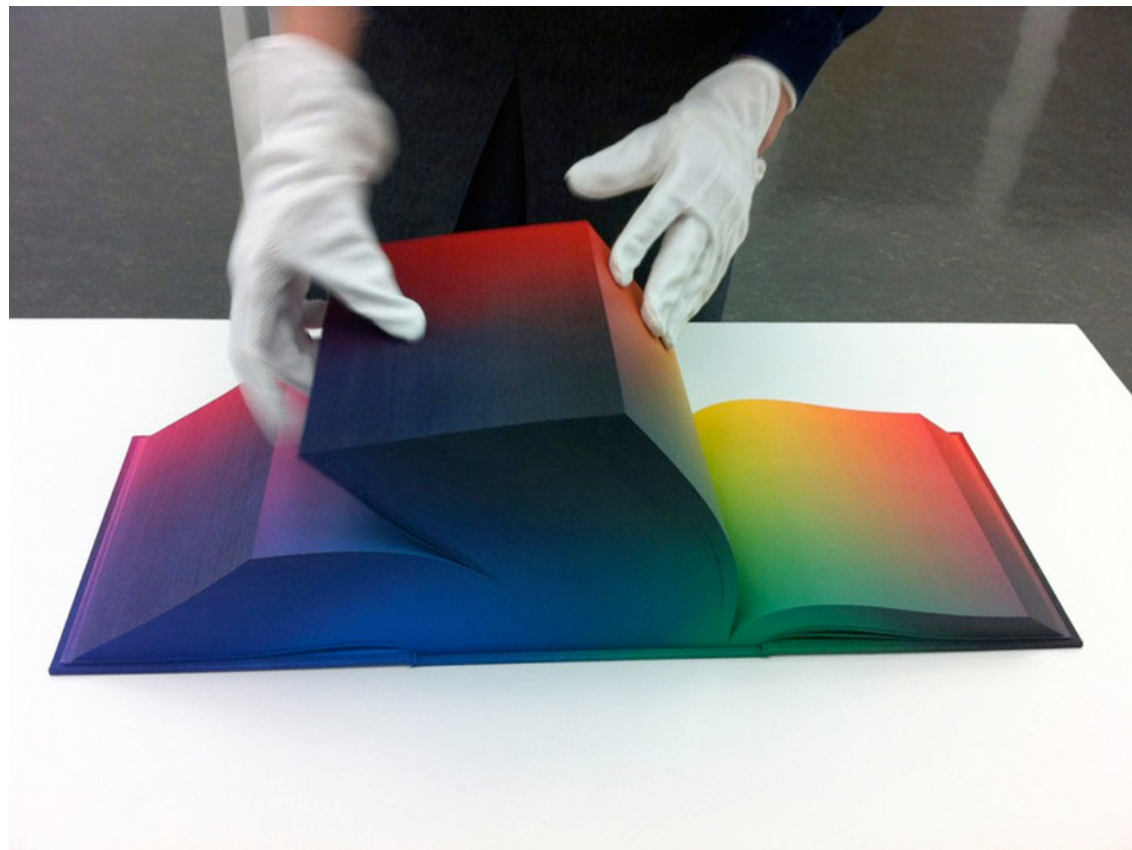


RGB Color

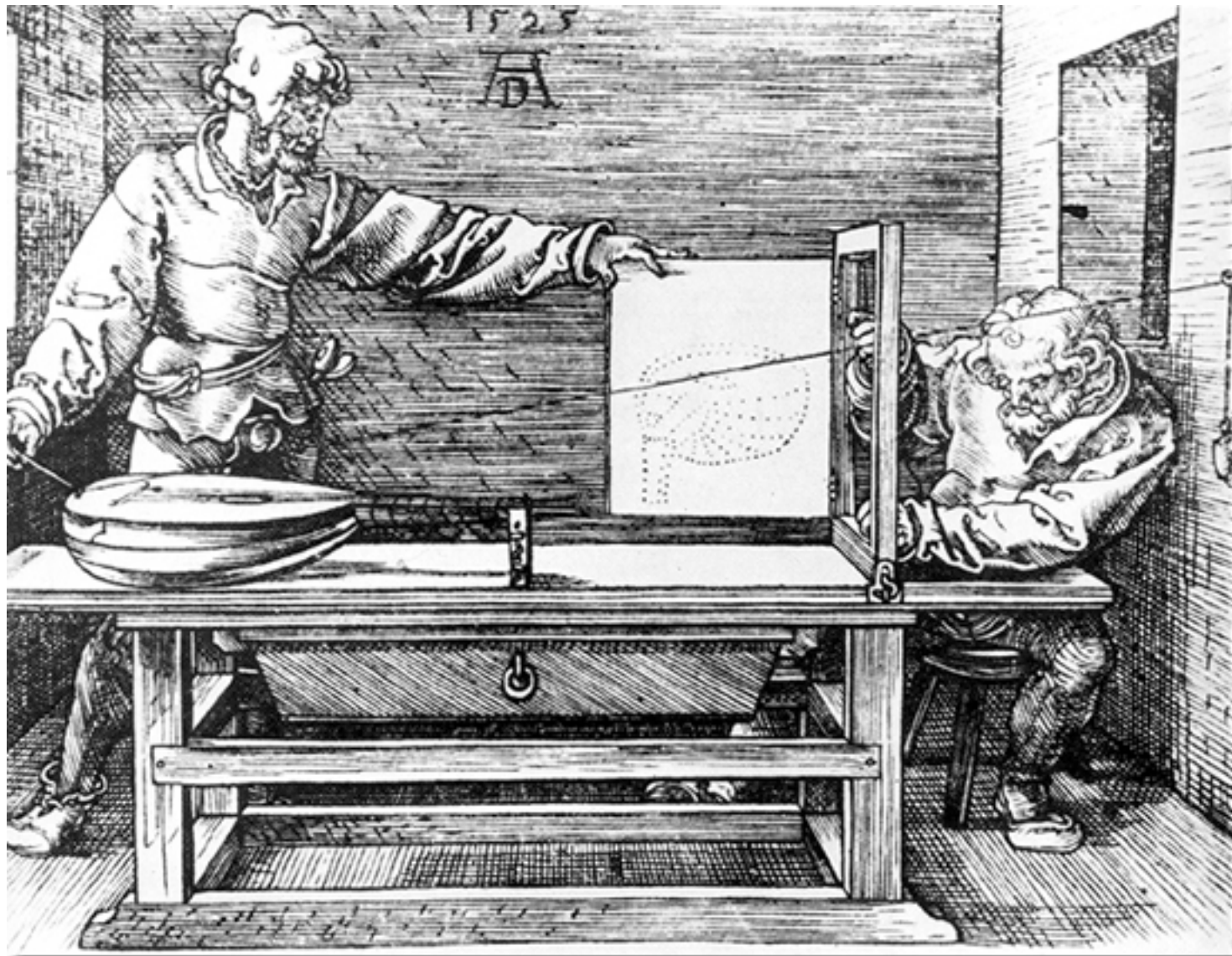


RGB Color Space

<http://www.designboom.com/weblog/cat/10/view/23357/tauba-auerbach-rgb-colorspace-atlas.html>

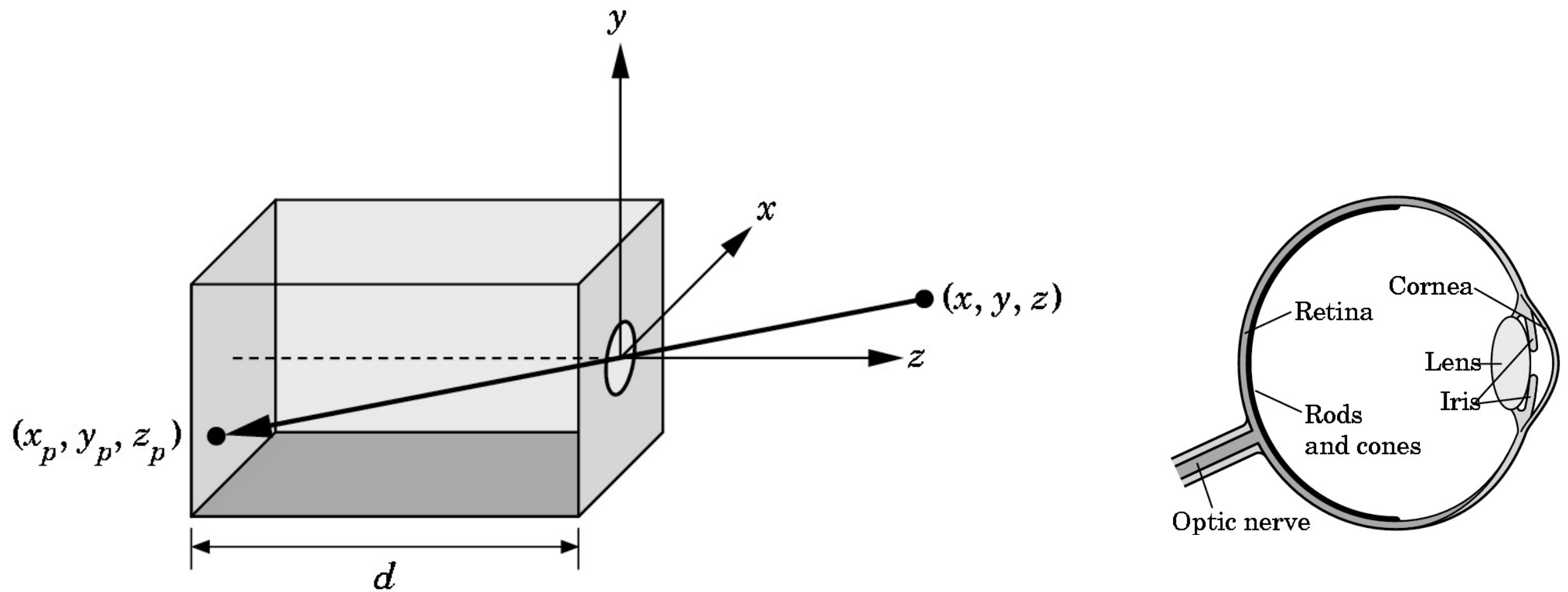


Rendering a 2D image



Perspective drawing in the Renaissance: “Man drawing a lute” by Albrecht Dürer, 1525

Pinhole Camera



- Projection of a 3D point (x, y, z) on image plane:

$$x_p = -d \frac{x}{z}, \quad y_p = -d \frac{y}{z}$$
- Equal triangles:

$$\frac{x}{z} = \frac{x_p}{z_p} \Leftrightarrow x_p = z_p \frac{x}{z} = -d \frac{x}{z}$$

Synthetic Camera Model

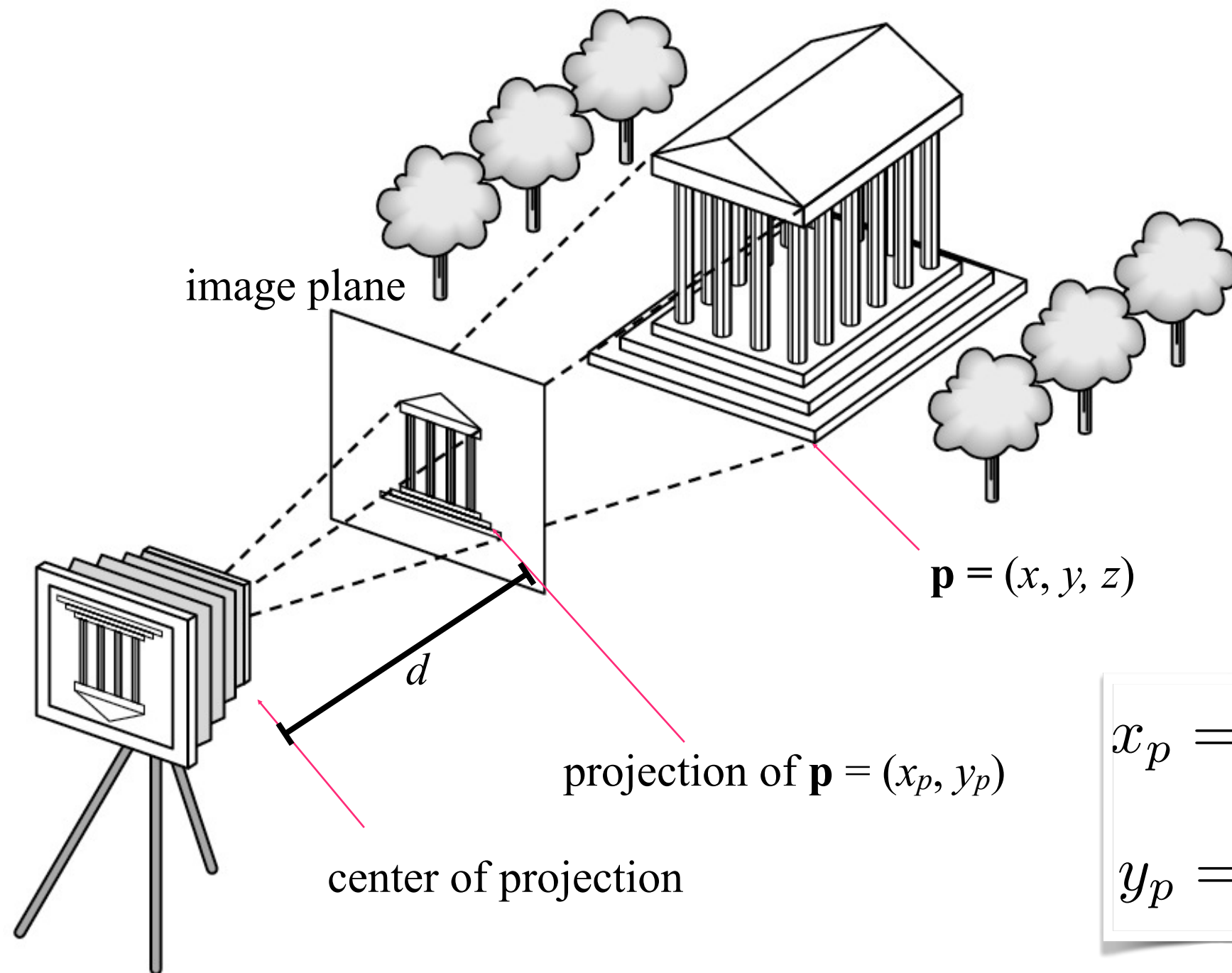


Image Formation

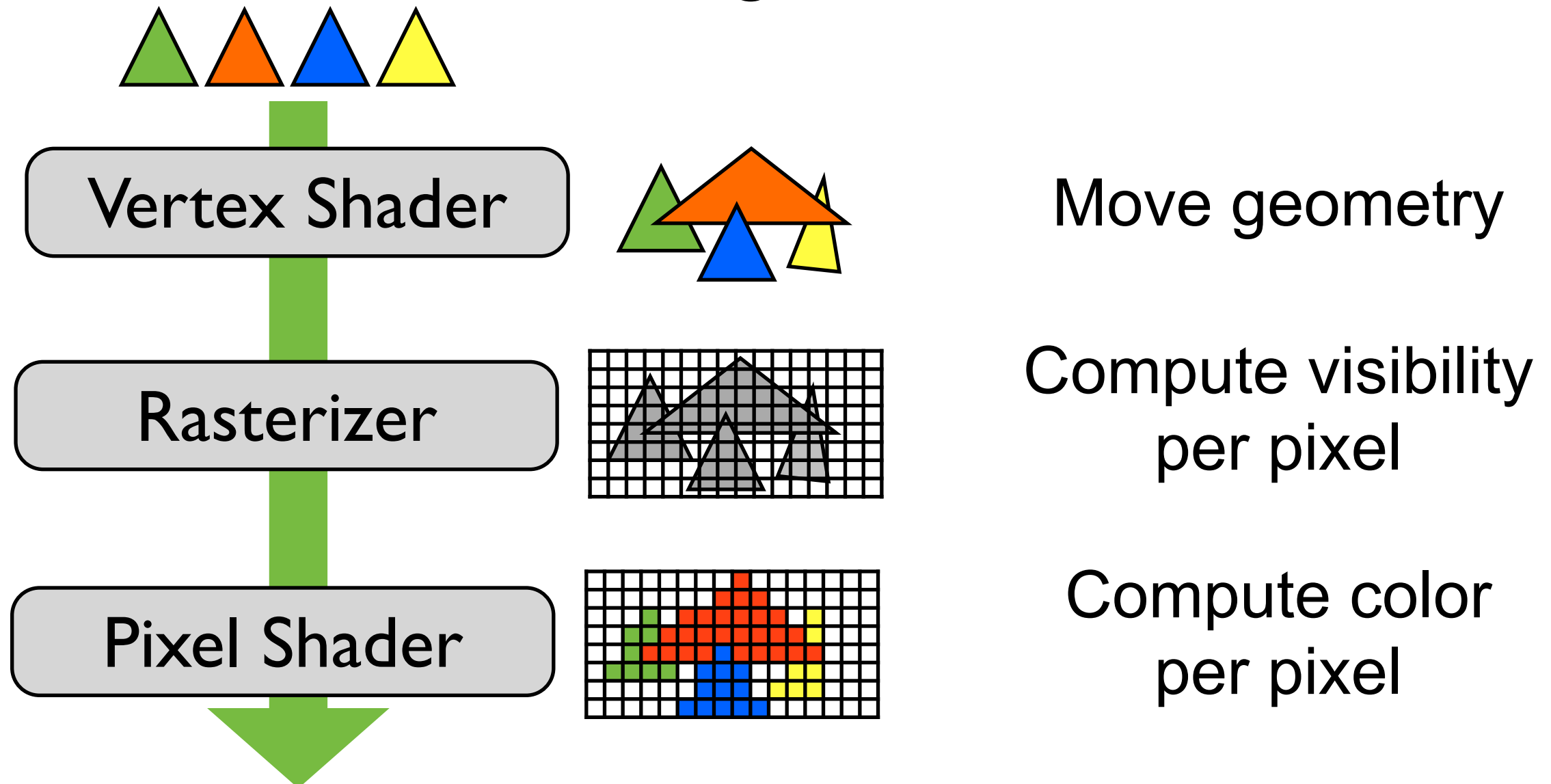
- Create geometric models
 - Position the models in a 3D scene
 - Assign materials to each model
 - Add lights & position a virtual camera
- For each pixel - find visible object
- Compute color of pixel based on the visible object's material and light

Challenges

- Create geometric models 1M triangles
 - Position the models in a 3D scene (Move 1M tris)
 - Assign materials to each model
 - Add lights & position a virtual camera
- For each pixel (5M), compute which triangle (of the 1M tris) that is visible
- Compute color of pixel (5M) based from the object's material and light

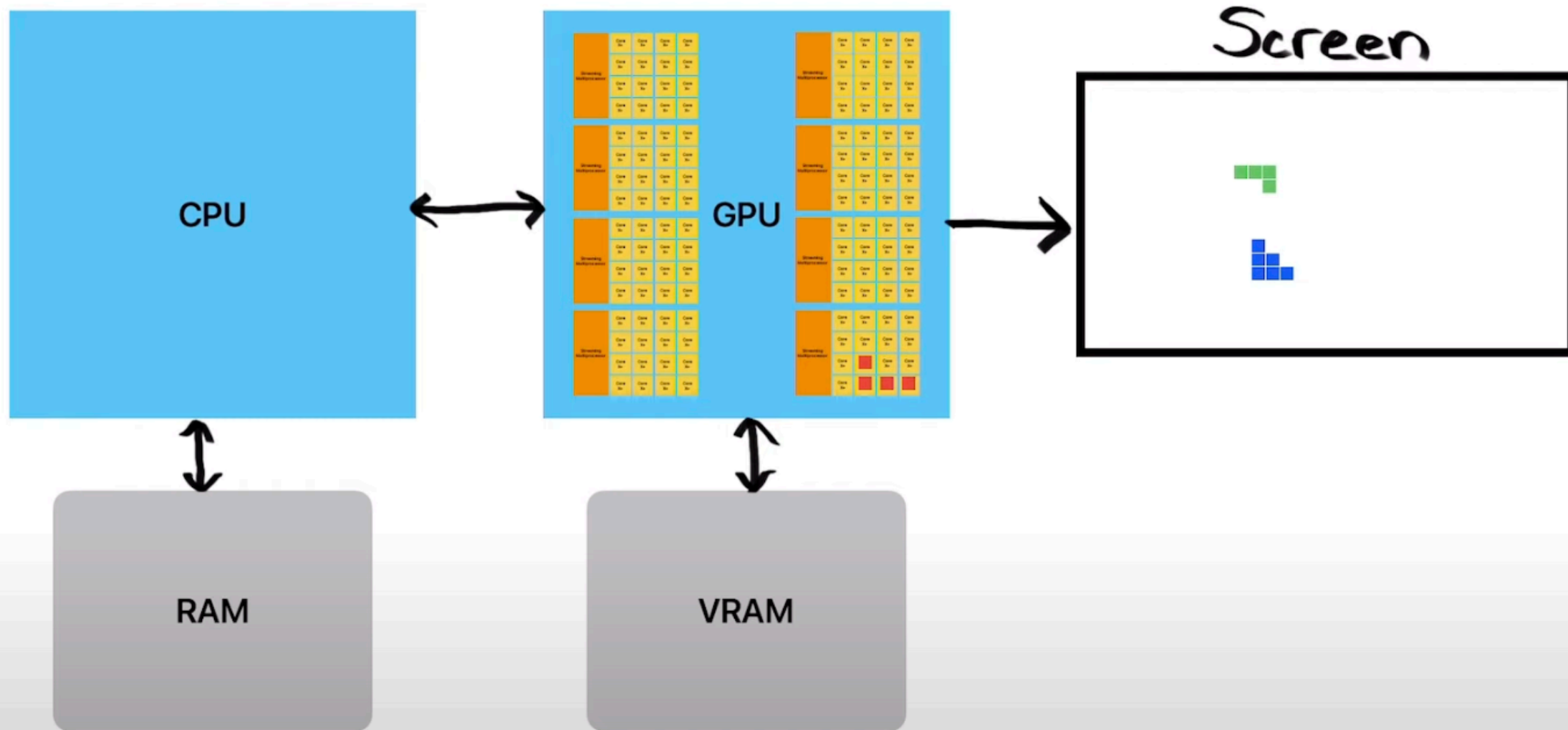
Graphics Hardware - GPU

- **Pipeline** that accelerates the costly tasks of rendering



GPU cores and memory

Computer Graphics

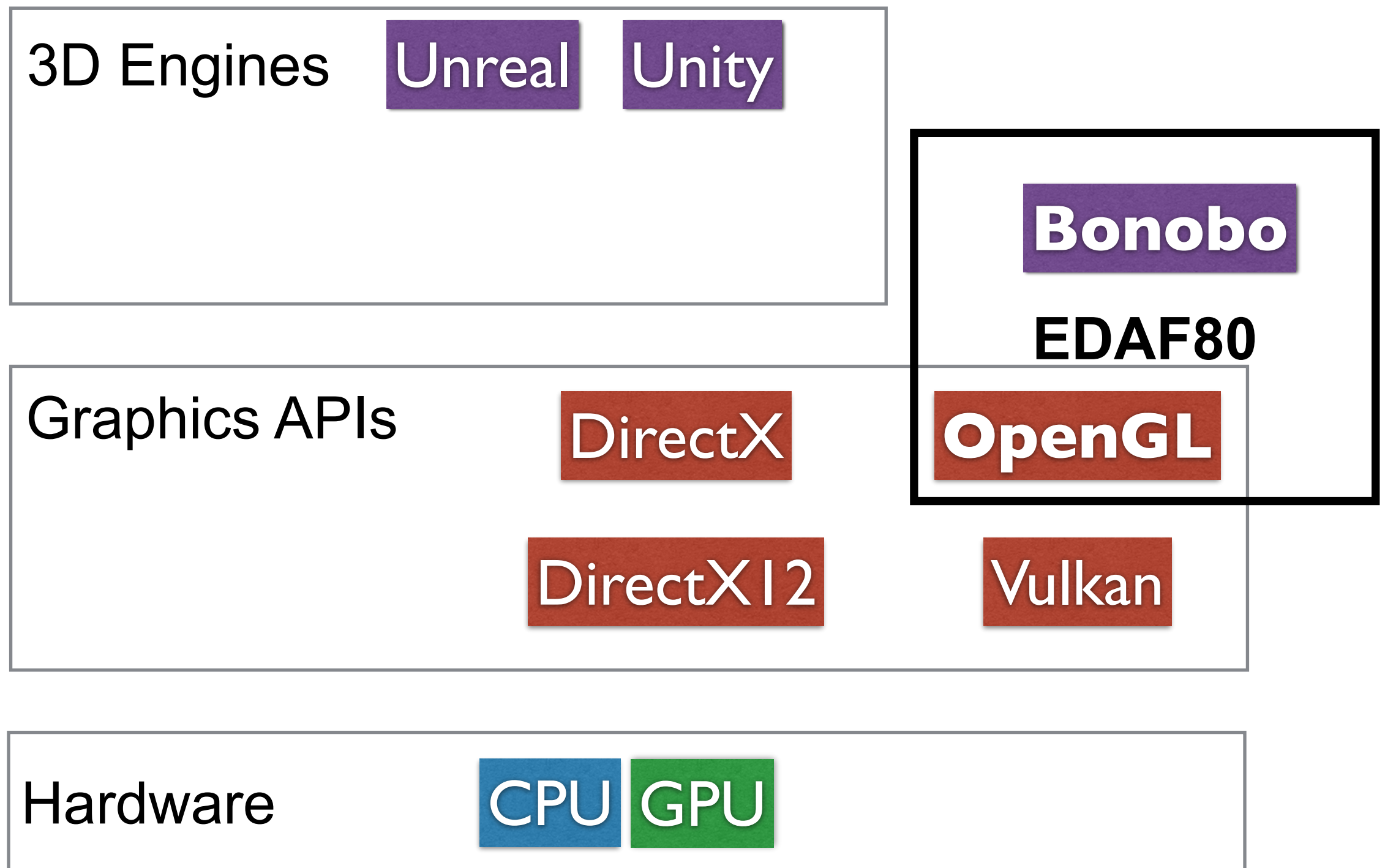


<https://youtu.be/EmBSghZSNCE>

What is OpenGL?

- OpenGL is a computer graphics rendering *application programming interface* (API)
- High level API to graphics hardware
- Abstracts the graphics pipeline
- State machine
 - Input can either change the state or produce visible output

Graphics programming layers



Real-time vs Movies (Offline)

- Real-time
 - Render image in ~16 ms (60 FPS)
 - Instant feedback
 - User interactions
- Offline (feature films)
 - Each image may take hours or days
 - Photorealism
 - No user interaction



Real-Time

Cocoon



Animated Movies

Inside Out 2



Live Action Movies

The Creator

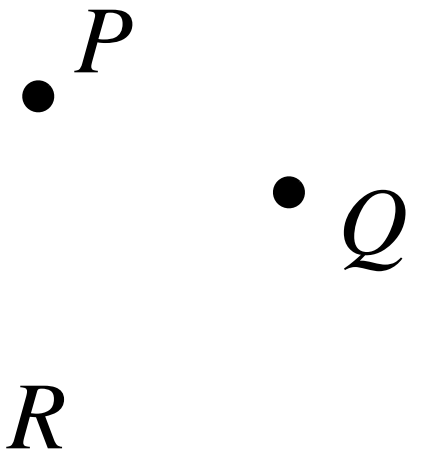
Linear Algebra in Computer Graphics

Linear Algebra

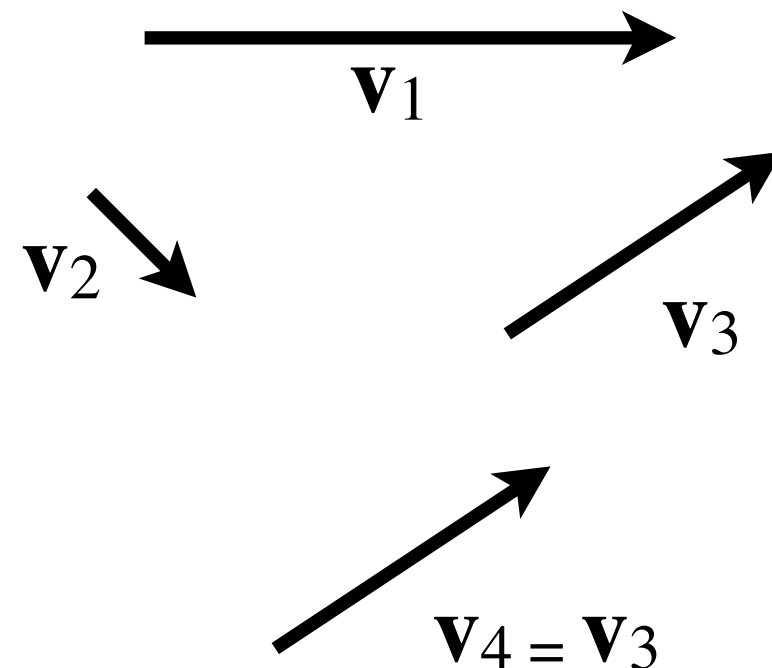
- Points vs Vectors
- Angles between vectors
- Dot (scalar) product
- Cross product
- Coordinate systems

Points & Vectors

- A **point** is a location in space

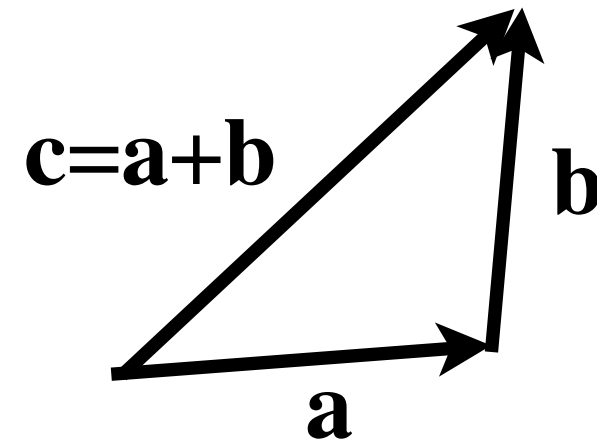


- A **vector** represents a direction and magnitude

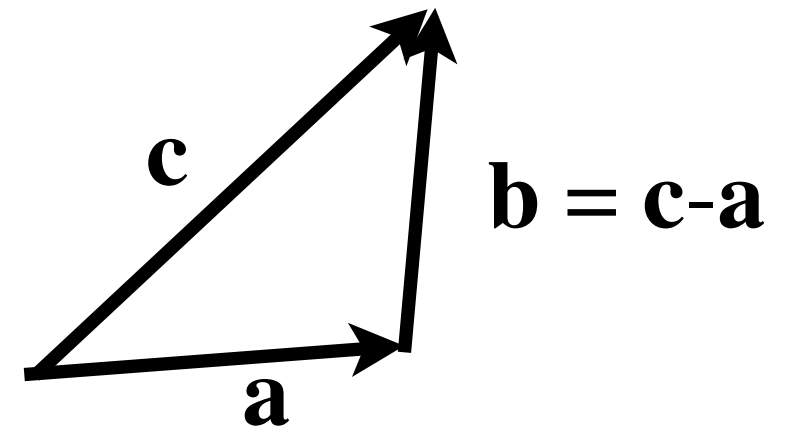


Basic Operations

- Vector-vector addition



- Vector-vector subtraction



- Point-point subtraction

$$\mathbf{v} = Q - P \Leftrightarrow Q = P + \mathbf{v}$$



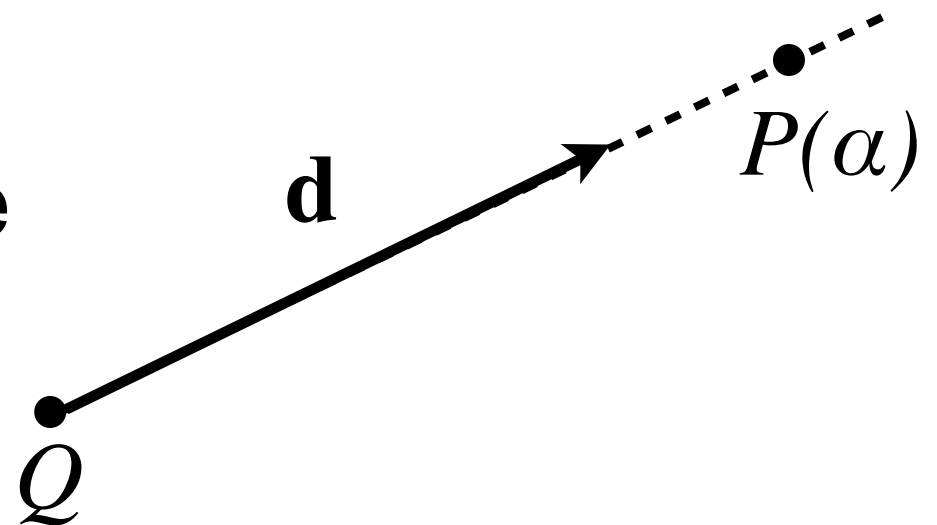
Lines

- Parametric form

- Start with a point Q and a vector \mathbf{d}

$$P(\alpha) = Q + \alpha \mathbf{d}$$

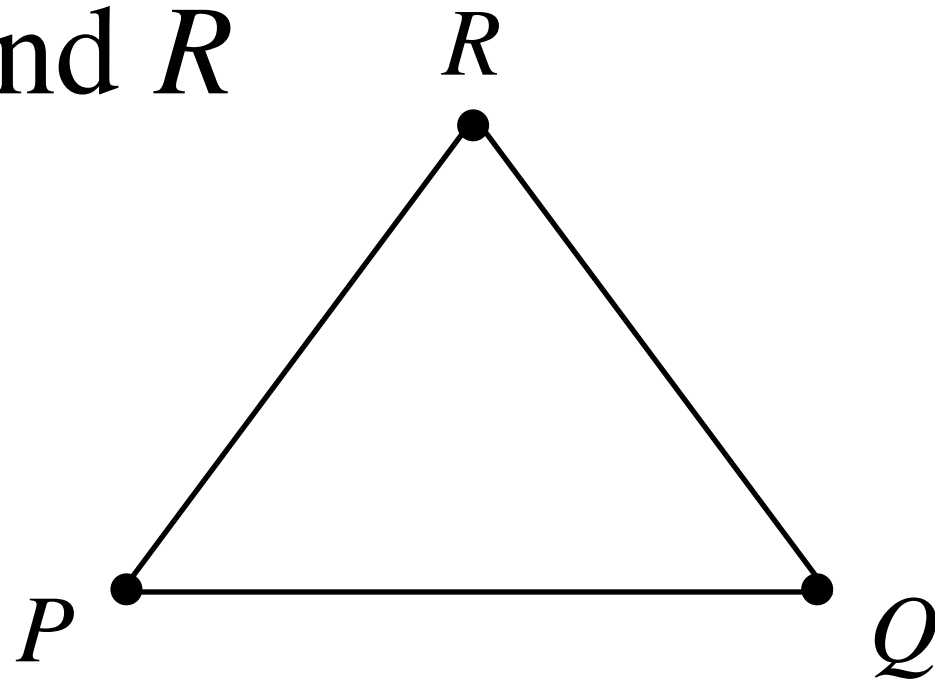
- If $\alpha > 0$, the line is called the **ray** from Q in the direction \mathbf{d}
- α is a scalar parameter that determines how far we have travelled along the line



Triangle

- Defined by three points

P , Q and R

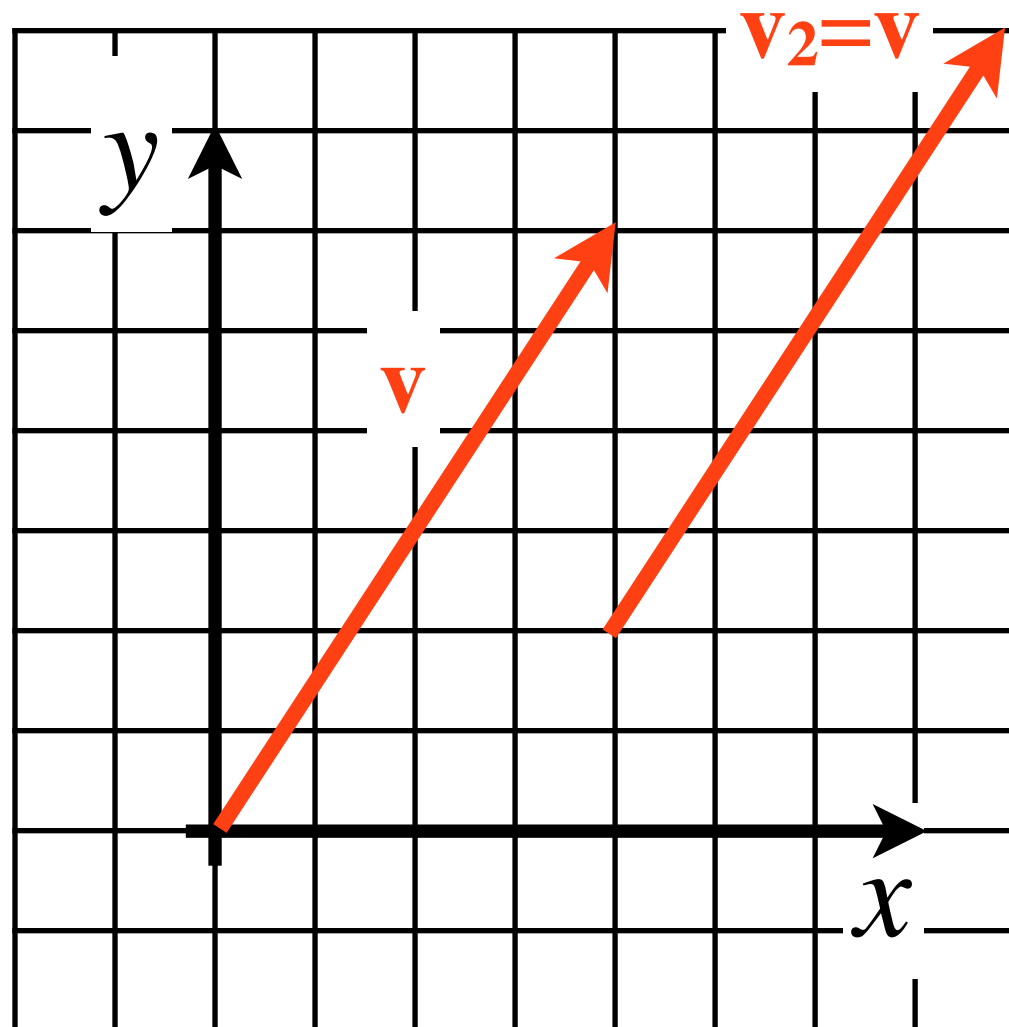


- Points inside triangle: $wP + uQ + vR$
- u, v, w : barycentric coordinates

$$u + v + w = 1$$

$$u, v, w \geq 0$$

Cartesian Coordinates



$$\begin{aligned}\mathbf{v} &= 4\mathbf{x} + 6\mathbf{y} \\ &= 4 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + 6 \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 4 \\ 6 \end{bmatrix}\end{aligned}$$

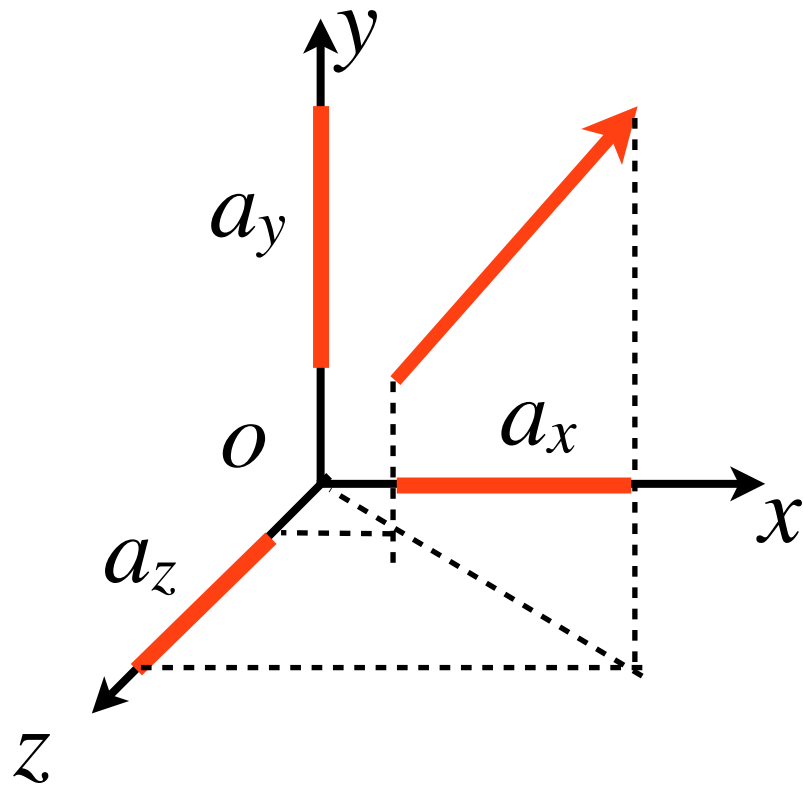
$$|\mathbf{v}| = \sqrt{(4^2 + 6^2)}$$

Cartesian Coordinates in 3D

- Express vector in terms of three orthonormal basis vectors

$$\mathbf{a} = a_x \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + a_y \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + a_z \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} = \boxed{\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}} \begin{bmatrix} a_x \\ a_y \\ a_z \end{bmatrix}$$

Basis



In this basis, the vector \mathbf{a} can be expressed as

$$\mathbf{a} = \begin{bmatrix} a_x \\ a_y \\ a_z \end{bmatrix}$$

Vector notation

- To avoid clutter, we introduce the notation:

$$\mathbf{a} = \begin{bmatrix} a_x \\ a_y \\ a_z \end{bmatrix} = (a_x, a_y, a_z)$$

- Note that $\mathbf{a} = (a_x, a_y, a_z)$ is still a **column-vector**, expressed in a certain basis

Points in 3D

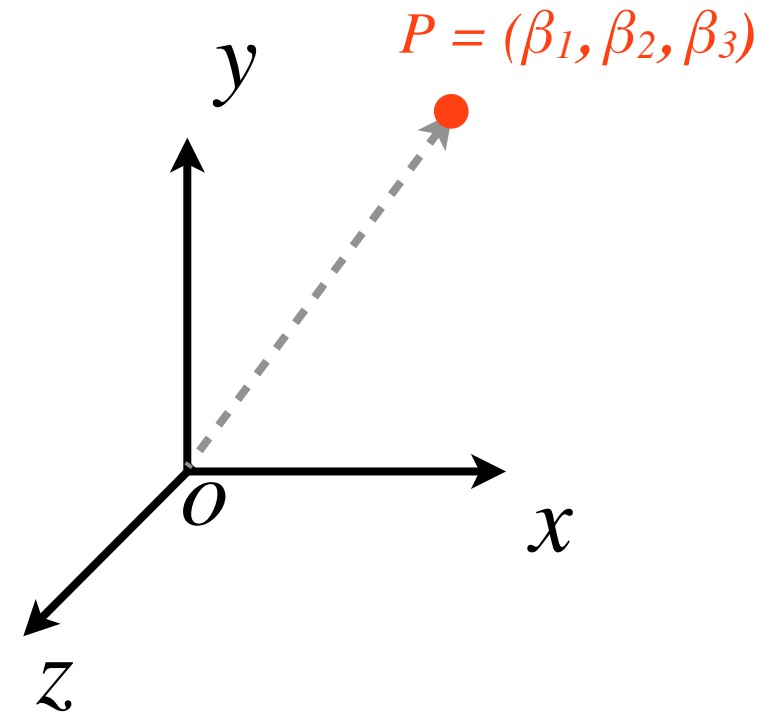
- Coordinate frame
 - Basis vectors + **origin**

$$\mathbf{v}_1 = (1, 0, 0)$$

$$\mathbf{v}_2 = (0, 1, 0)$$

$$\mathbf{v}_3 = (0, 0, 1)$$

$$\mathbf{o} = (0, 0, 0)$$



- In this frame, a **point** is given by:

$$P = \mathbf{o} + \beta_1 \mathbf{v}_1 + \beta_2 \mathbf{v}_2 + \beta_3 \mathbf{v}_3$$

$$= \beta_1 (1, 0, 0) + \beta_2 (0, 1, 0) + \beta_3 (0, 0, 1)$$

$$= (\beta_1, \beta_2, \beta_3)$$

Example: Triangle in 3D

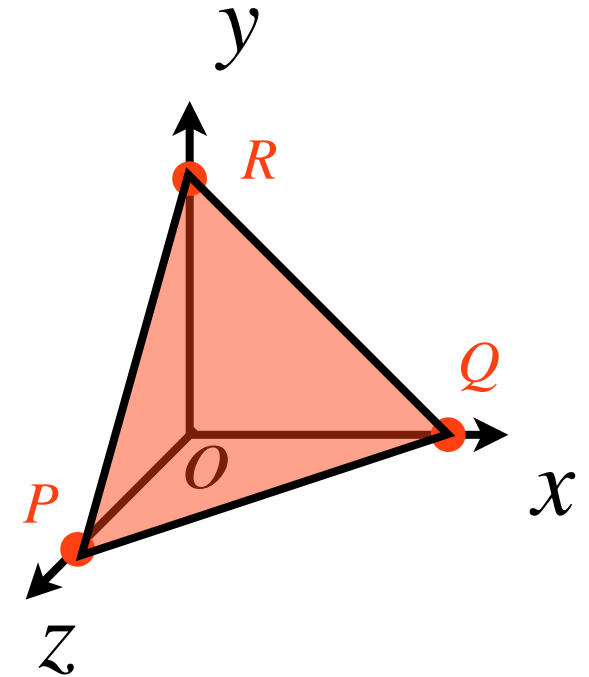
- Defined by three points,

$$P = (0,0,1)$$

$$Q = (1,0,0)$$

$$R = (0,1,0)$$

specified in the
Cartesian system



$$P = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} + 0 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + 0 \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + 1 \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

Shadertoy Rainforest

<https://www.shadertoy.com/view/4ttSWf>

making of <https://youtu.be/BFId4EBO2RE>

Euclidean 3D Space

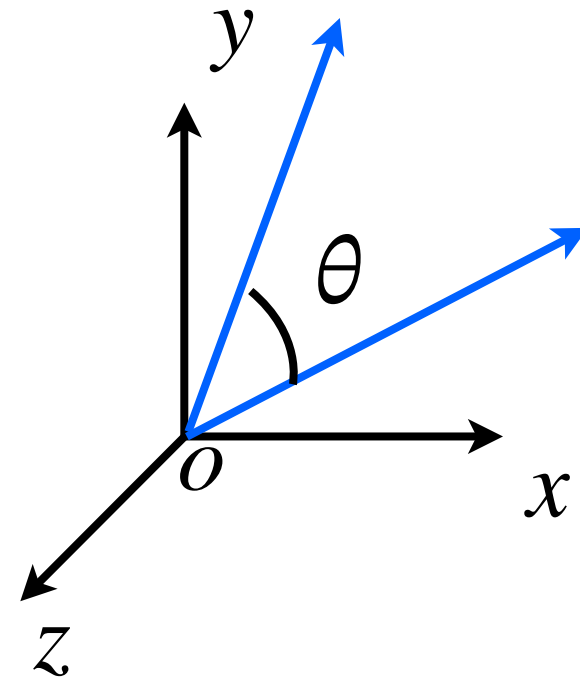
- **Coordinate frame**
 - **Basis vectors + origin**

$$\mathbf{v}_1 = (1, 0, 0)$$

$$\mathbf{v}_2 = (0, 1, 0)$$

$$\mathbf{v}_3 = (0, 0, 1)$$

$$\mathbf{o} = (0, 0, 0)$$

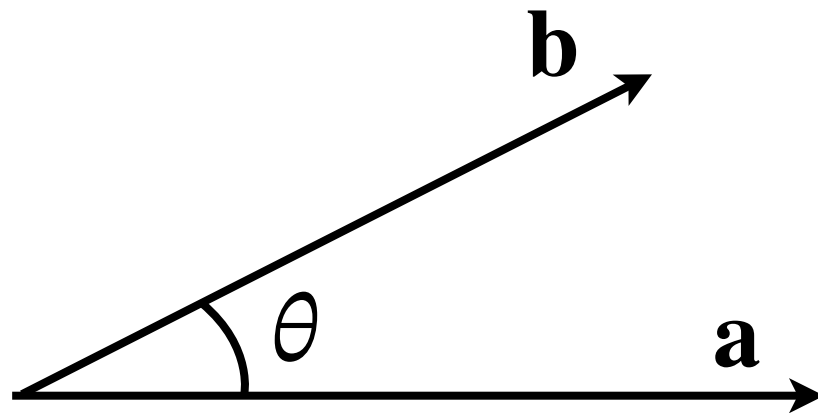


- The Cartesian coordinates express the three basis vectors, origin at (0,0,0)
- How to define the angle between two vectors in this coordinate frame?

Dot Product (scalar product)

- Given two 3D vectors $\mathbf{a} = (a_x, a_y, a_z)$ and $\mathbf{b} = (b_x, b_y, b_z)$, the dot product is given by

$$\mathbf{a} \cdot \mathbf{b} = a_x b_x + a_y b_y + a_z b_z = |\mathbf{a}| |\mathbf{b}| \cos \theta$$



- Angle between **a** and **b**: $\theta = \arccos \left(\frac{\mathbf{a} \cdot \mathbf{b}}{|\mathbf{a}| |\mathbf{b}|} \right)$

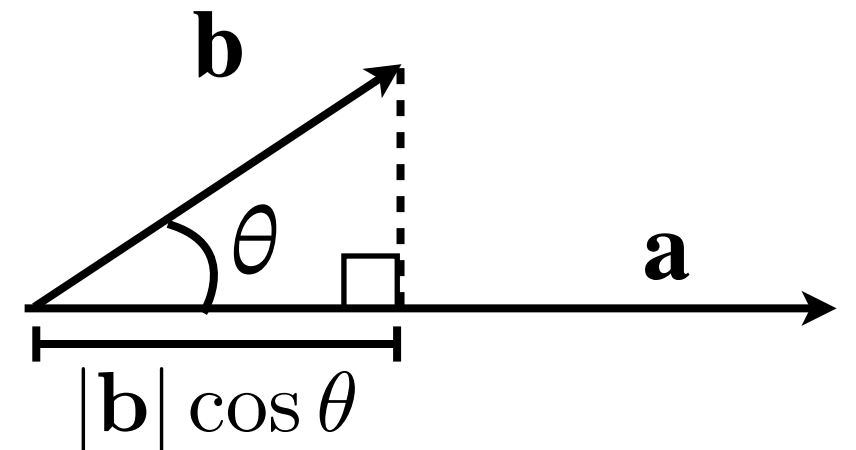
Dot Product (scalar product)

- Use cases

$$\mathbf{a} \cdot \mathbf{b} = a_x b_x + a_y b_y + a_z b_z = |\mathbf{a}| |\mathbf{b}| \cos \theta$$

- The projection of \mathbf{b} on \mathbf{a}

$$|\mathbf{b}| \cos \theta = \frac{\mathbf{a} \cdot \mathbf{b}}{|\mathbf{a}|}$$



- Square magnitude of vector

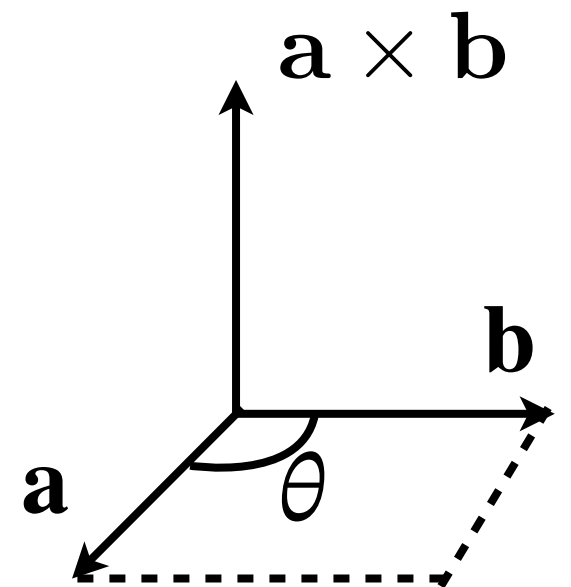
$$\mathbf{a} \cdot \mathbf{a} = |\mathbf{a}|^2 \Leftrightarrow |\mathbf{a}| = \sqrt{\mathbf{a} \cdot \mathbf{a}}$$

- \mathbf{a} and \mathbf{b} orthogonal if

$$\mathbf{a} \cdot \mathbf{b} = 0$$

Cross Product

- Given two 3D vectors $\mathbf{a} = (a_x, a_y, a_z)$ and $\mathbf{b} = (b_x, b_y, b_z)$, the cross product is given by
$$\mathbf{a} \times \mathbf{b} = (a_y b_z - a_z b_y, a_z b_x - a_x b_z, a_x b_y - a_y b_x)$$
- Signed area of the parallelepiped spanned by vectors \mathbf{a} and \mathbf{b} :
$$|\mathbf{a} \times \mathbf{b}| = |\mathbf{a}| |\mathbf{b}| \sin \theta$$
- $\mathbf{a} \times \mathbf{b}$ is orthogonal to both \mathbf{a} and \mathbf{b}
- $\mathbf{a} \times \mathbf{a} = \mathbf{0}$
- Note: $\mathbf{a} \times \mathbf{b} = -\mathbf{b} \times \mathbf{a}$



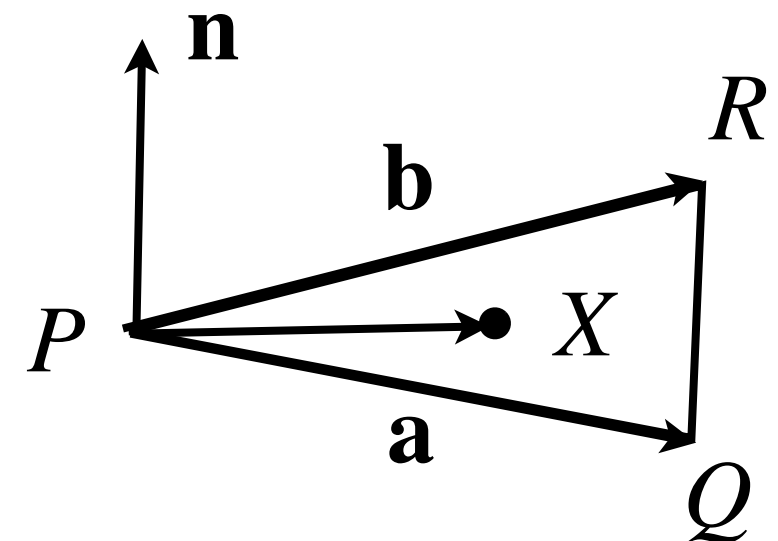
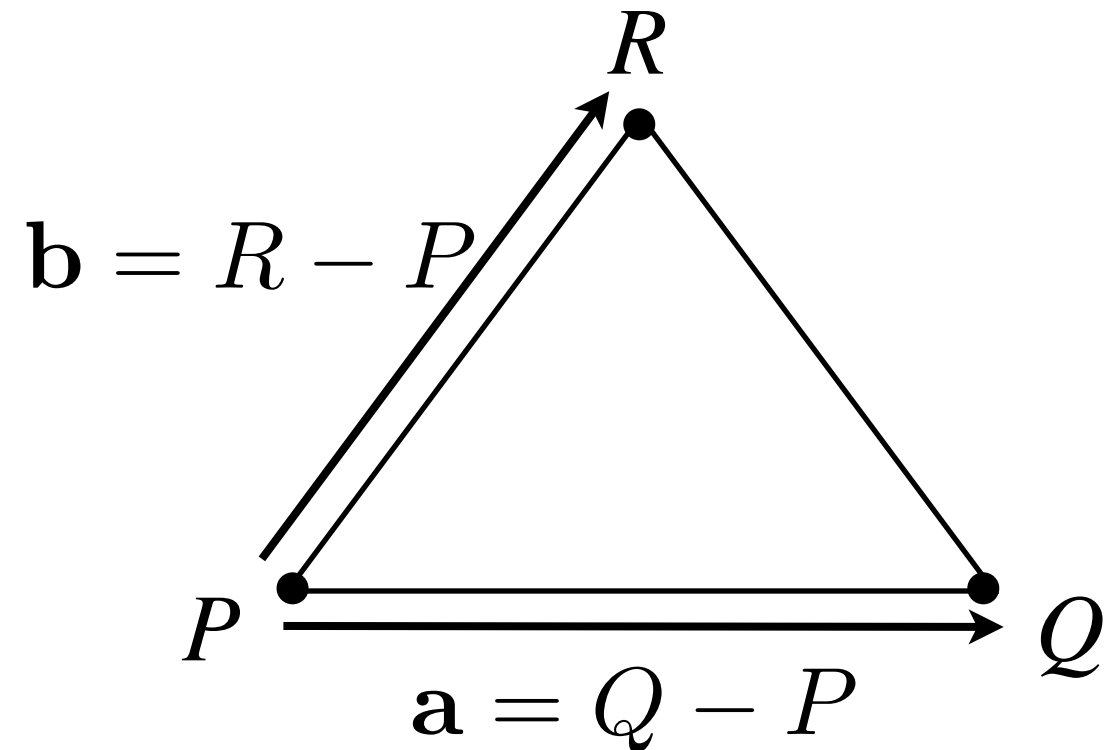
Triangle Normal

- Introduce two edge vectors **a**, **b**
- Triangle face normal

$$\mathbf{n} = \frac{\mathbf{a} \times \mathbf{b}}{|\mathbf{a} \times \mathbf{b}|}$$

- Plane equation:
 - X belongs to the triangle plane if

$$\mathbf{n} \cdot (\mathbf{X} - \mathbf{P}) = 0$$

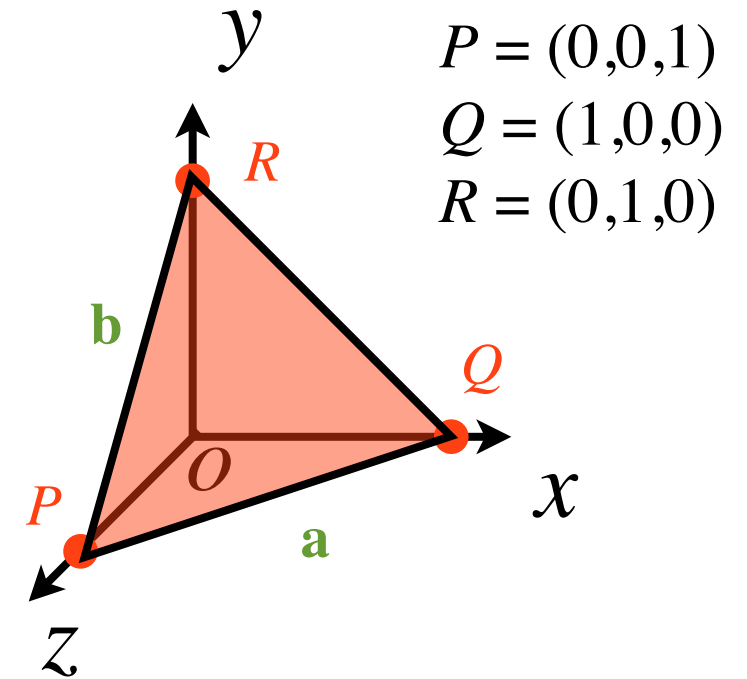


Example: Triangle in 3D

- Edge vectors

$$\mathbf{a} = \mathbf{Q} - \mathbf{P} = (1, 0, -1)$$

$$\mathbf{b} = \mathbf{R} - \mathbf{P} = (0, 1, -1)$$



$$P = (0,0,1)$$

$$Q = (1,0,0)$$

$$R = (0,1,0)$$

- Face normal

$$\mathbf{n} = \frac{\mathbf{a} \times \mathbf{b}}{|\mathbf{a} \times \mathbf{b}|} = \frac{(1, 1, 1)}{|(1, 1, 1)|} = \frac{1}{\sqrt{3}}(1, 1, 1)$$

- Plane: $\mathbf{n} \cdot (\mathbf{X} - \mathbf{P}) = 0$ $\mathbf{X} = (x, y, z)$

$$x + y + z - 1 = 0$$

Matrices

- We will use
 - Matrix-matrix multiplication: $\mathbf{A} \mathbf{B} = \mathbf{C}$
 - Concatenate transforms, change basis
 - Matrix-vector multiplication $\mathbf{A} \mathbf{x} = \mathbf{y}$
 - Transform vectors and points

Matrix-vector multiplication

$$A\mathbf{x} = \mathbf{y}$$

$$\begin{bmatrix} a_{00} & a_{01} & a_{02} \\ a_{10} & a_{11} & a_{12} \\ a_{20} & a_{21} & a_{22} \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} a_{00}x + a_{01}y + a_{02}z \\ a_{10}x + a_{11}y + a_{12}z \\ a_{20}x + a_{21}y + a_{22}z \end{bmatrix}$$

Matrix-matrix multiplication

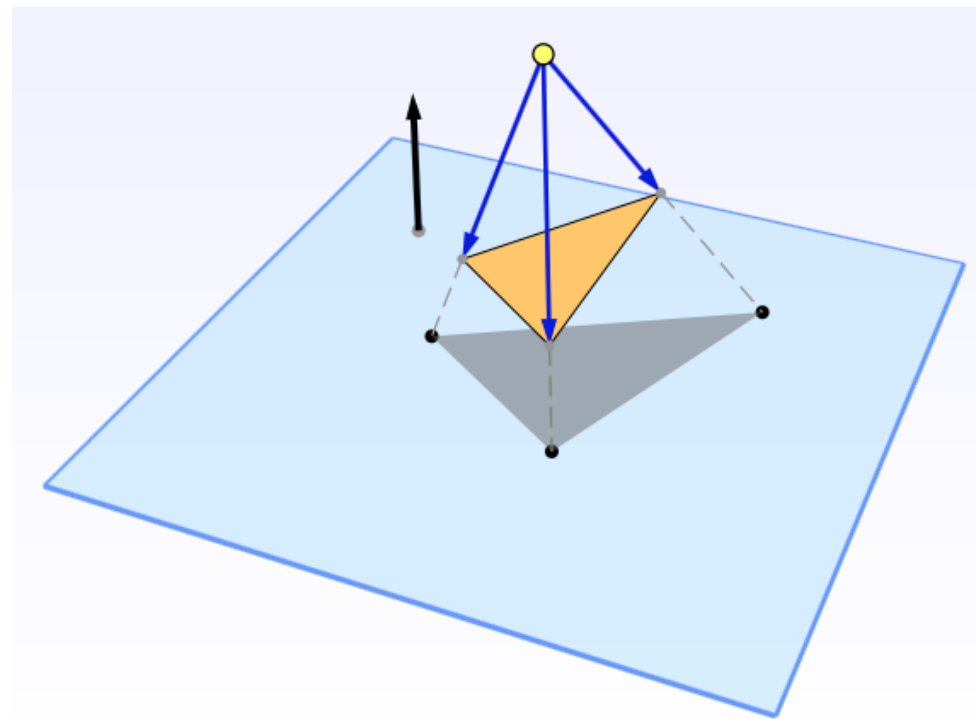
$$AB = C$$

$$\begin{bmatrix} a_{00} & a_{01} & a_{02} \\ a_{10} & a_{11} & a_{12} \\ a_{20} & a_{21} & a_{22} \end{bmatrix} \begin{bmatrix} b_{00} & b_{01} & b_{02} \\ b_{10} & b_{11} & b_{12} \\ b_{20} & b_{21} & b_{22} \end{bmatrix} = \begin{bmatrix} c_{00} & c_{01} & c_{02} \\ c_{10} & c_{11} & c_{12} \\ c_{20} & c_{21} & c_{22} \end{bmatrix}$$

$$c_{ij} = \sum_{k=0}^2 a_{ik} b_{kj}$$

Online Book on Linear Algebra

- immersive linear algebra
 - <http://immersivemath.com/>
 - by J. Ström, K. Åström, and T. Akenine-Möller
 - Interactive figures



Next

- Seminar : Wednesday 10 in Teknodromen, M:1201
 - OpenGL intro & C++ basics
 - **Bring Laptops**
- Next Lecture
 - Transforms
 - Coordinate Spaces
 - Homogeneous Coordinates
- Enrollment issues - Contact me or cs_expedition@cs.lth.se

Epic MetaHuman

<https://youtu.be/pnaKyc3mQVk>