

## Solutions

1.  $X(X X) = (X X) K S K = X X K S K = (X K S K) K S K = X K S K K S K = K K S K S K K S K = K K S K K S K = K K K S K = K S K = S$
2.  $M = M I S S = (\lambda m.m I S S)M$  so  $M = Y(\lambda m.m I S S)$  has the requested property.
3. There are 26 abstractions in  $A$  and 27 identifiers inside the parentheses. Observe that  $r$  is the last abstraction and that it occurs first and last in the body. Informally using  $A^n$  for  $A \cdots A$  with  $n$  occurrences of  $A$  we get  
 $BF = A A^{25} F = F(A^{26} F) = F(BF)$
4. The new alternative will process the declarations in reverse order so we will have different meanings for `var x=1; var x=2.`

$$\frac{\langle \epsilon, \sigma \rangle \rightarrow \sigma}{\langle \text{var } x:=2; \epsilon, \sigma \rangle \rightarrow \sigma[x \mapsto 2]}}$$

$$\frac{\langle \text{var } x:=1; \text{var } x:=2; \epsilon, \sigma \rangle \rightarrow \sigma[x \mapsto 2][x \mapsto 1]}}$$

5.

$$\langle \text{random}(x), \sigma \rangle \rightarrow \sigma[x \mapsto n] \quad \text{where } n \in N$$

$$\langle \text{random}(x), \sigma \rangle \Rightarrow \sigma[x \mapsto n] \quad \text{where } n \in N$$

It can be done by replacing `random(x)` by `x:=0; y:=0; while (y<1) do (x:=x+1 or y=1)` where  $y$  is a new variable. It is not possible to implement this so that all values are equally probable. On the other hand, the operational rules do not specify anything about probability.

6.

$$\frac{\langle S, \sigma \rangle \Rightarrow \langle S', \sigma' \rangle \quad \langle \text{protect } S' \text{ end}, \sigma' \rangle \Rightarrow \sigma''}{\langle \text{protect } S \text{ end}, \sigma \rangle \Rightarrow \sigma''}}$$

and

$$\frac{\langle S, \sigma \rangle \Rightarrow \sigma'}{\langle \text{protect } S \text{ end}, \sigma \rangle \Rightarrow \sigma'}}$$

This solution is not in the spirit of structural operational semantics since the first rule describes a “big step”. I don’t know any better solution.

7. We have to redefine the `updP` function:

$$\text{upd}_P(\text{proc } p(x_1, x_2) \text{ is } S; D_P, \text{env}_V, \text{env}_P) =$$

$$\text{upd}_P(D_P, \text{env}_V, \text{env}_P[p \mapsto (x_1, x_2, S, \text{env}_V, \text{env}_P)])$$

$$\text{upd}_P(\epsilon, \text{env}_V, \text{env}_P) = \text{env}_P$$

This is then used in the rule for a block without change.

$$\frac{\langle D_V, \text{env}_V, \text{sto} \rangle \rightarrow_D (\text{env}'_V, \text{sto}') \quad \text{env}'_V, \text{env}'_P \vdash \langle S, \text{sto}' \rangle \rightarrow \text{sto}''}{\text{env}_V, \text{env}_P \vdash \langle \text{begin } D_V D_P S \text{ end}, \text{sto} \rangle \rightarrow \text{sto}''}}$$

where  $\text{env}'_P = \text{upd}_P(D_P, \text{env}'_V, \text{env}_P)$

The call statement obeys the rule

$$\frac{\text{env}'_V, \text{env}'_P \vdash \langle \text{begin var } x_1 = n_1; \text{var } x_2 = n_2; S \text{ end}, \text{sto}' \rangle \rightarrow \text{sto}''}{\text{env}_V, \text{env}_P \vdash \langle \text{call } p(a_1, a_2), \text{sto} \rangle \rightarrow \text{sto}''}}$$

where  $\text{env}_P p = (x_1, x_2, S, \text{env}'_V, \text{env}'_P)$  and

$$\mathcal{N}[[n_1]] = \mathcal{A}[[a_1]](\text{sto} \circ \text{env}_V)$$

$$\mathcal{N}[[n_2]] = \mathcal{A}[[a_2]](\text{sto} \circ \text{env}_V)$$