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Real-Time and Concurrent Programming

Lecture 5 (F5):

Part1: Deadlock Part 2: Messages

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## Part I

# Deadlock |



#### Content

- Introduction and Definitions
  - Circular wait.
- Examples
  - Resource allocation graph
  - Monitor deadlock
- 3 Conditions and Analysis
  - Conditions for deadlock
  - Analysis: Resource allocation graphs
- Deadlock Avoidance
- 5 Classic Example
  - The Dining Philosophers problem



# Background

Mutual exclusion means that a thread can be delayed

- ▶ A thread will not be allowed to enter a critical region (using a shared resource) as long as it is occupied by another thread.
- For consistency (concurrency correctness), predictability (real-time correctness), and for efficiency (embedded computing), access of such a locked resource may not be interrupted or subject to a roll-back.

Hence, we have no preemption on resources (only on time as in preemptive scheduling; not to be confused).

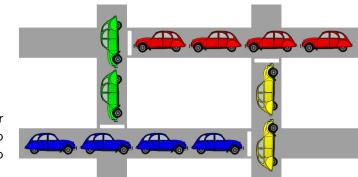
▶ If the blocking never ends we have a **Deadlock** (Swe: Dödläge)

Wikipedia: Deadlock refers to a specific condition when two or more processes are each waiting for the other to release a resource, or more than two processes are waiting for resources in a circular chain.

# The problem

If waiting can be or is circular:

- ▶ When several threads can be waiting for each other we have a Deadlock risk.
- ▶ When several threads are waiting for each other we have a Deadlock.



Thus, circular wait appears to be related too deadlock:

## Example: deadlock with semaphores

```
P1
             P2
                             P1:
                                        P2:
S1.take(); S2.take();
                             S1.take();
S2.take(); S1.take();
                                        S2.take();
. . .
                                        S1.take();
                                                   blocked
S2.give(); S1.give();
S1.give(); S2.give();
                                                   blocked
                             S2.take();
```

Deadlock may occur if: one thread performs a take, followed by a context switch (swe: trådbyte).

2016-09-27

## Example cont'd: resource allocation graph

```
P1
                     P2
S1.take():
                     S2.take();
                                                       S1 ⋈
                                          Holds resource
S2.take();
                     S1.take();
                                                               P2
S2.give();
                     S1.give();
                                        Waits for resource
S1.give();
                     S2.give();
```

Method: draw resources (boxes) and threads (circles). Draw arrows for **hold** (filled) + **wait** (outlined).

P2

m2.op1();

P1

m1.op1();

## Deadlock with monitors

```
Holds resource
                     M1 ⋈
Waits for resource
                     M2
```

```
class M1 {
  synchronized void op1() {
    m2.op2();
  synchronized void op2() {
    wait();
```

```
class M2 {
  synchronized void op1() {
    m1.op2();
 }
  synchronized void op2() {
    wait();
```

# Necessary conditions for deadlock

#### Necessary conditions for deadlock to occur:

- 1. Mutual Exclusion only one thread can access a resource at a time.
- 2. Hold and Wait a thread can reserve a resource and wait for another.
- 3. No resource preemption a thread can not be forced to release held resources.
- 4. Circular Wait thread-resources dependencies must be circular.

#### Monitor - satisfied conditions:

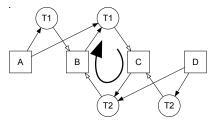
- 1. Monitor one thread only is allowed to enter at a time.
- 2. Call of an operation in a monitor from inside a monitor operation in another monitor
- 3. A monitor can only be released if a thread voluntarily waits (wait()) or exits the monitor.
- 4. But 4? Must prevent circular wait that can result in deadlock.

Analysis: Resource allocation graphs

# Resource allocation graphs

Tool for detecting circular hold-wait situations and to determine under which conditions deadlock can occur.

- 1. Draw resources
- Draw all hold-wait situations (arrows from each held resource to a thread marker, arrows from thread marker to resource waited for)
- Circular? Then risk for deadlock. The number of 'hold-wait' links in the circular chain shows how many and which threads are required for deadlock.



2016-09-27

Resource allocation graphs - example

# Resource allocation graphs - example

```
Thread 1
                   Thread 2
A.take():
                   D. take():
B. take():
                   C.take();
C.take():
                   B.take():
                                     Α
                                              В
                                                                D
C.give();
                   B.give();
B.give();
                   C.give();
A.give();
                   D.give();
```

F5b: Messages

Conclusion: Deadlock possible when T1 is waiting for C and T2 is simultaneously waiting for B! Circular wait!

## Monitors in Concurrent Pascal

Concurrent Pascal (Per-Brinch Hansen 1979) only has monitors and the rule: no forward references, i.e. the program we looked at earlier is illegal:

```
class M1 {
  synchronized void op1() {
    // Illegal since it introduces
    // a forward reference
    m2.op2();
  synchronized void op2() { ... }
class M2 {
  synchronized void op1() {
    m1.op2();
  synchronized void op2() { ... }
```

- Monitors, Semaphores, etc. are often referred to as resources.
- Generally: all resources is assigned a (partial) order, only allocate from lower to higher.
- M2 can call M1 but not the other way around.

## Limitations in the language - a good idea?

- Deadlock impossible in Concurrent Pascal with Monitors as resources.
- ▶ Often inefficient and unpractical might be necessary to prematurely allocate resources just to satisfy the demands on allocation order.
- ► Easy to implement ones own resource management using Monitors:

```
R R1, R2;
/*monitor*/ class R {
                                     class P1 extends Thread {
  boolean occupied;
  synchronized void request() {
                                       R1.request();
    while (occupied) wait();
                                       R2.request();
      occupied = true;
    }
  synchronized void release() {
                                     class P2 extends Thread {
    occupied = false;
                             R1
    notify();
                                       R2.request();
                                   P2
                                       R1.request();
                             R2
```

# Avoiding deadlock

- Language and library support not applicable.
- Run-time deadlock detection: Not suitable for real-time or embedded systems (useful in a generic OS, but here it would be too late).
- Instead, remove the risk for deadlock:
  - Create and analyze the resource-allocation graph.
  - Arrange the order of allocations, according to a resource ordering, preferably without extending the locking times.

F5b: Messages

- If really necessary: add logic that prevents the dead-lock.

Avoidance conclusion

## Notions

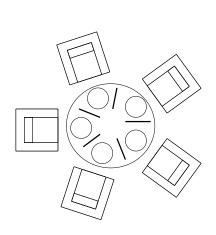
- Deadlock (swe: dödläge)
  - When several resources attempts to allocate the same resource one must be able to get it.
  - Bad enough if there exists an execution order such that Deadlock occurs - even if it happens only seldom. The system locks, hangs, nothing happens. Can apply to subsystems.
- Starvation (swe: svält)
  - If a thread attempts to allocate a resource it must be able to get it eventually.
  - We renounce the 'no starvation' property in favor of priority; less important activities might suffer from starvation.
- Livelock
  - Occurs when several threads attempts to allocate the same resource but none actually gets it due to the execution pattern.
  - Behaves like Deadlock, but if you study the system closely the threads actually run. They do no meaningful work though.

## Dining Philosophers problem

The life of a philosopher is boring:

```
class Philosopher
  while
    think();
    preProto();
    eat();
    postProto();
```

- Logical spaghetti:
  - Two forks are required to eat
- Solution requirements:
  - No deadlock
  - No starvation
  - **Efficient**



# Semaphore solution 1

```
Semaphore[] fork = new MutexSem[5];
for (int i=0; i<5; i++) fork[i] = new MutexSem();
class Philosopher extends Thread {
 int i;
  Philosopher(int i) {this.i=i;}
  public void run() {
    while (true) {
      think();
      fork[i].take();
      fork [(i+1)%5].take();
      eat();
      fork[i].give();
      fork[(I+1)%5].give();
```

- Eat() acts as a critical region for a pair of forks, but for different pairs of forks
  - mutual exclusion for both
- Can this solution cause Deadlock? Two resources is required for each activity (hold-wait satisfied) so we have to make a more detailed analysis.

Solution 1 cont'd - deadlock?

## Philosophers 1 - deadlock?

Draw a complete allocation graph, all Hold-Wait dependencies

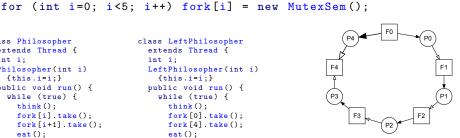


- ▶ Circular → unsafe program, Deadlock can occur.
- Step 2: Can we present a scenario where deadlock occurs or prove that the situation can not occur in practice?
- Scenario: Suppose all 5 philosophers starts simultaneously, takes their left forks and then (all of them) waits for their right forks.
- This solution can thus cause deadlock.
- Can we solve the problem in a better way?
  - avoid circularity or
  - make sure that all Hold-Wait can not occur simultaneously?

## Philosophers 2 - one left handed philosopher

```
class Philosopher
                               class LeftPhilosopher
  extends Thread {
                                 extends Thread {
 int i:
                                 int i:
 Philosopher (int i)
                                 LeftPhilosopher(int i)
   {this.i=i;}
                                   {this.i=i;}
 public void run() {
                                 public void run() {
   while (true) {
                                   while (true) {
      think():
                                     think():
      fork[i].take():
                                     fork[0].take():
      fork[i+1].take():
                                     fork[4].take():
      eat();
                                     eat();
      fork[i].give();
                                     fork[4].give();
      fork[i+1].give();
                                     fork[0].give():
```

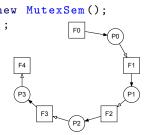
Semaphore[] fork = new MutexSem[5];



- No circular dependency
- No deadlock

# Philosophers 3 - only four chairs

```
Semaphore[] fork = new MutexSem[5];
for (int i=0; i<5; i++) fork[i] = new MutexSem();</pre>
Semaphore room = new CountingSem(4);
class Philosopher extends Thread {
  int i:
  Philosopher(int i) {this.i=i;}
  public void run() {
    while (true) {
      think();
      room.take();
      fork[i].take();
      fork [(i+1)%5].take();
      eat();
      fork[i].give();
      fork[(i+1)%5].give();
      room.give();
```



Complete allocation graph cyclic, 'unsafe' as before, but: At most four Hold-Wait can be active simultaneously  $\rightarrow$  at least one philosopher can eat, no deadlock possible.

# Philosophers 4 - polite philosophers

#### A philosopher only picks up the forks and starts to eat if BOTH forks are free.

- Implemented using a monitor or a MultistepSem.
  - Trivially deadlock free since no Hold-Wait situations occur.
  - but, starvation possible.
- Suppose two philosophers, e.g. 1 and 3 agrees to eat alternating:
  - ▶ I.e. philosopher 1 eats until philosopher 3 has begun to eat, and the other way around
  - Now will philosopher 2 never have two forks free at the same time, i.e. philosopher 2 will starve!!

## Part II

# Message-based communication and synchronization



- 6 Mailboxes and messages
  - Buffering and asynchronous interaction
  - System aspects
- 7 Events and Buffers
  - Messages within a program Event objects
- 8 Examples
  - Dataflows: Producer Consumer



## The buffering monitor as a mailbox for messages

- While monitors in general are for operations on shared data, a monitor with operations post (called by a producer thread) and fetch (called by consumer thread) comprises a data flow.
- Data can provide information and/or synchronization.
- Originally and traditionally data is then referred to as messages, and the buffer is a mailbox.
- Between threads (the same program and memory space) a message can be an Object ref.

```
class Buffer { // Providing mailbox

synchronized void post(Object obj) {
   while (buff.size()>=maxSize) {
      wait();
   }
   if (buff.isEmpty()) notifyAll();
   buff.add(obj);
}

synchronized Object fetch() {
   while (buff.isEmpty()) {
      wait();
   }
   if (buff.size()>=maxSize) notifyAll();
   return buff.remove();
   }
}
```

# Message sending – Mailboxes

Reasons for message-based interactions between threads:

- Producer-Consumer relations (data flows) between threads are very common
- Asymmetric synchronization (signaling); the producer should be allowed to continue without having to wait for the consumer.
- Transfer information data referred to as message content.
- ► Thus, asynchronous communication (signaling plus data transfer) that provides **Buffering** and Thread/Activity interaction.

Additionally, for complex systems today:

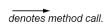
- **Distribution:** Threads are, or need to be prepared for being, distributed over several computers with network communication.
- Encapsulation: Concurrent and real-time properties of objects (handling timeout/overrun/exceptions etc.) requires means for message passing between concurrently running objects/threads.

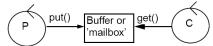
Situations with Producer-Consumer relations between threads are very common.

We want to achieve:

- Asymmetric synchronization i.e. the producer should be allowed to continue without having to wait for the consumer.
- Transfer information a message

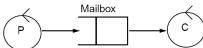
So far we have used a Monitor/Buffer to achieve this:





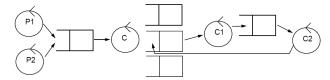
We introduce a special name, Mailbox (brevlåda), for this way of using a Monitor. We draw it somewhat differently:





# Systems of mailboxes

Communication between threads often forms a network of mailboxes.



- The same principle for (operating system) processes and threads.
- A thread can put a message in several mailboxes.
- A mailbox can, in Java, handle various types of messages subclassing of message (RTEvent).
- A thread has in most cases only one mailbox it reads from (otherwise problems fetching a messag is a blocking operation).
- Message objects need to be serialized (transformed into a stream of bytes) in order to be sent to another OS process.
- Within a OS process (between threads), we can send pointers/references or a copy of the object.

F5b: Messages

How does the receiver know that another thread does not modify the contents of a message??? System aspects

# IPC (Inter-Process Communication)

	Local	Distributed
'Synchronous'	Object-method call	RPC/RMI
Synchronous	Monitor-method call	Database
Asynchronous	Event buffer	Stream(pipe/file/socket)

## Synchronous handling of Event

- Event model in Java (AWT, Swing Beans) basically NOT concurrent.
- Corresponding EventObject for realtime: RTEvent
- Corresponding synchronous event handling in se.lth.cs.realtime: See class documentation for RTEventListener, RTEventListenerList and JThread.
- Single-threaded 'synchronous' event handling is not a central issue in the course.

## Unbounded mailbox with copy-on-send

## Advantages

- Flexible code; size of buffer does not need to be decided.
- ► Thread safety; sent message not accessable by sender.
- ▶ The same mechanism can be used for communication between OS processes running on the same computer or different ones (distributed systems), since shared memory is not assumed.

## Disadvantages

- Higher risk for running out of memory, detected later. (Memory is limited, so better set fixed bounds early.)
- Often unpractical when immediate response is required (i.e. synchronous communication).
- Increased memory use, CPU for copying, and GC work.
- Recycling via message pools difficult to implement.

We use a 'bounded buffer' in the form of RTEventBuffer in shared memory.

## Mailbox == Monitor == Semaphore

- ▶ A Mailbox can easily be implemented using a Monitor
- Also a Semaphore is sort of a monitor.
- Suppose we only send empty messages, then a Mailbox is equivalent to a Semaphore:

F5b: Messages

- The value of the counter of the Semaphore corresponds to the number of messages in the mailbox.
- Send message give()
- Receive message take()

All three constructions are thus equally powerful, but practical in different situations.

## Events as messages

- java.util.EventObject comprises an event class that is suitable for messages, providing a transient (will be null outside JVM) source, referring to the sending object/thread.
- se.lth.cs.realtime.event.RTEvent is a subclass that, as java.awt.InputEvent, has a timestamp, expressing object age.
- → We use such timestamped events for asynchronous communication between threads.

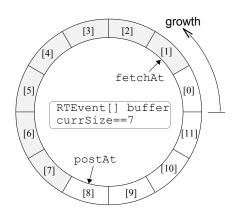
F5b: Messages

Note that graphics such as swing is basically single-threaded!

## The RTEvent class

## The RTEventBuffer class

- ▶ As for RTEvent, part of se.lth.cs.realtime.event
- Example with maxSize==12 and currSize==7, internal attributes:
- Obtain message/event by RTEvent fetch() or specific final methods.
- Send message/event by RTEvent post(RTEvent ev) or specific final methods.



## More RTEventBuffer / mailbox

Blocking and non-blocking methods for posting and fetching messages:

```
doPost(RTEvent e) // Add e to queue, blocks if the queue is full.
tryPost(RTEvent e) // Adds to the queue, without blocking if full.
doFetch() // Fetch from queue, block if empty.
tryFetch() // Fetch without blocking if empty.
awaitEmpty() // Waits for buffer to become empty.
awaitFull() // Checks if buffer is empty.
isFull() // Checks if buffer is full.
```

The try-Post/Fetch returns null if the buffer is non-full/empty, and the supplied/next event otherwise, respectively.

The attributes are declared protected in order to make it possible to create subclasses with revised functionality.

## A producer

```
class Producer extends Thread {
  Consumer receiver;
  MyMessage msg;
  public Producer(Consumer theReceiver) {
    receiver = theReceiver;
  public void run() {
    while (true) {
                                 class MyMessage extends RTEvent {
      char c = getChar();
                                   character ch;
      msg = new MyMessage(c);
                                   public MyMessage(char data) {
                                     super(); // Set time stamp;
      receiver.putEvent(msg);
                                     ch = data;
```

Note: Buffering is hidden by putEvent as of the receiving thread.

#### A consumer

```
class Consumer extends Thread {
  RTEventBuffer mailbox:
  public Consumer(int size) {mailbox=new RTEventBuffer(size);}
  public void putEvent(RTEvent ev) {
    mailbox.post(ev); // In context of Producer
  public void run() {
    RTEvent m;
    while (true) {
      m = mailbox.fetch(); // In context of Consumer
      if (m instanceof MyMessage) {
        MyMessage msg = (MyMessage) m;
        useChar(msg.ch);
      } else { ... // Handle other messages
      };
    } // ...
```

## The JThread utility class

- ▶ Part of the se.lth.cs.realtime package.
- Subclass of java.lang.Thread; thus it is a Java Thead, hence JThread.
- Encapsulates an RTEventBuffer, exposed via a public putEvent method.
- Default run method is a cyclic call of perform
- Internally the perform (or run) method refers to the mailbox attribute like

```
event = mailbox.doFetch();
```

► Methods sleepUntil and terminate are also provided (compare lab1).